

# Making choices in multi-dimensional parameter spaces

PhD thesis defence

Steven Bergner

# Model adjustment at different levels

- **User-driven experimentation:** Use cases for *paraglide*
- **Criteria optimization:** Lighting design
- **Theoretical analysis:** Sampling in volume rendering
- **Discretizing a region:** Lattices with rotational dilation
- Summary and conclusion



# Data acquisition and visualization

# Turning code into data

- Computer simulation code
- Function abstraction
  - ▶ Variables: input, output, and algorithm specific
  - ▶ Deterministic code



# Biological aggregations



(c) Sareh Nabi Abdolyousefi



# Biological aggregations

Input


Output



(c) Sareh Nabi Abdolyousefi



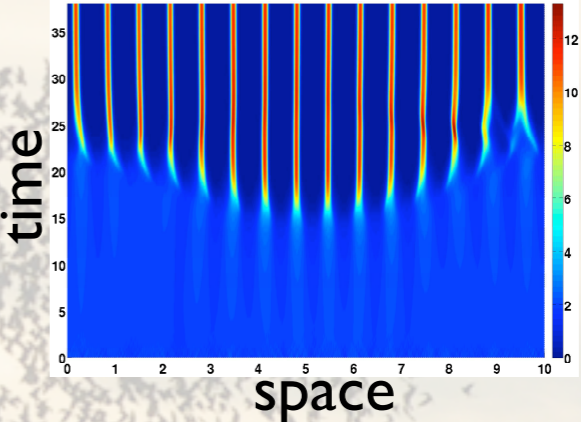
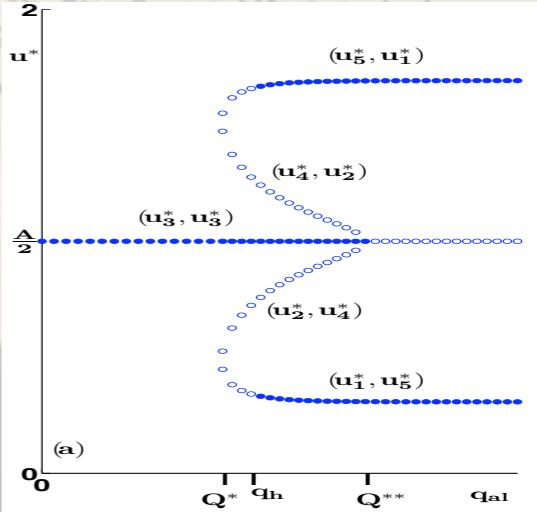
# Biological aggregations

Input	Output
<p data-bbox="255 764 867 840">1D+time model</p> <p data-bbox="255 983 784 1071"><i>14 parameters</i></p> <ul data-bbox="255 1095 1245 1402" style="list-style-type: none"><li>• attraction, repulsion, and alignment coefficients</li><li>• turning rates</li></ul> <p data-bbox="241 1422 537 1498"><i>internal:</i></p> <ul data-bbox="255 1535 1130 1712" style="list-style-type: none"><li>• space-time resolution influences cost</li></ul>	

(c) Sareh Nabi Abdolyousefi



# Biological aggregations

Input	Output
<p><math>1D+time</math> model</p> <p><i>4 parameters</i></p> <ul style="list-style-type: none"> <li>• attraction, repulsion, and alignment coefficients</li> <li>• turning rates</li> </ul> <p><i>internal:</i></p> <ul style="list-style-type: none"> <li>• space-time resolution influences cost</li> </ul>	<p>patterns:</p>  <p>steady state bifurcation and stability:</p> 

(c) Sareh Nabi Abdolyousefi





# More cases

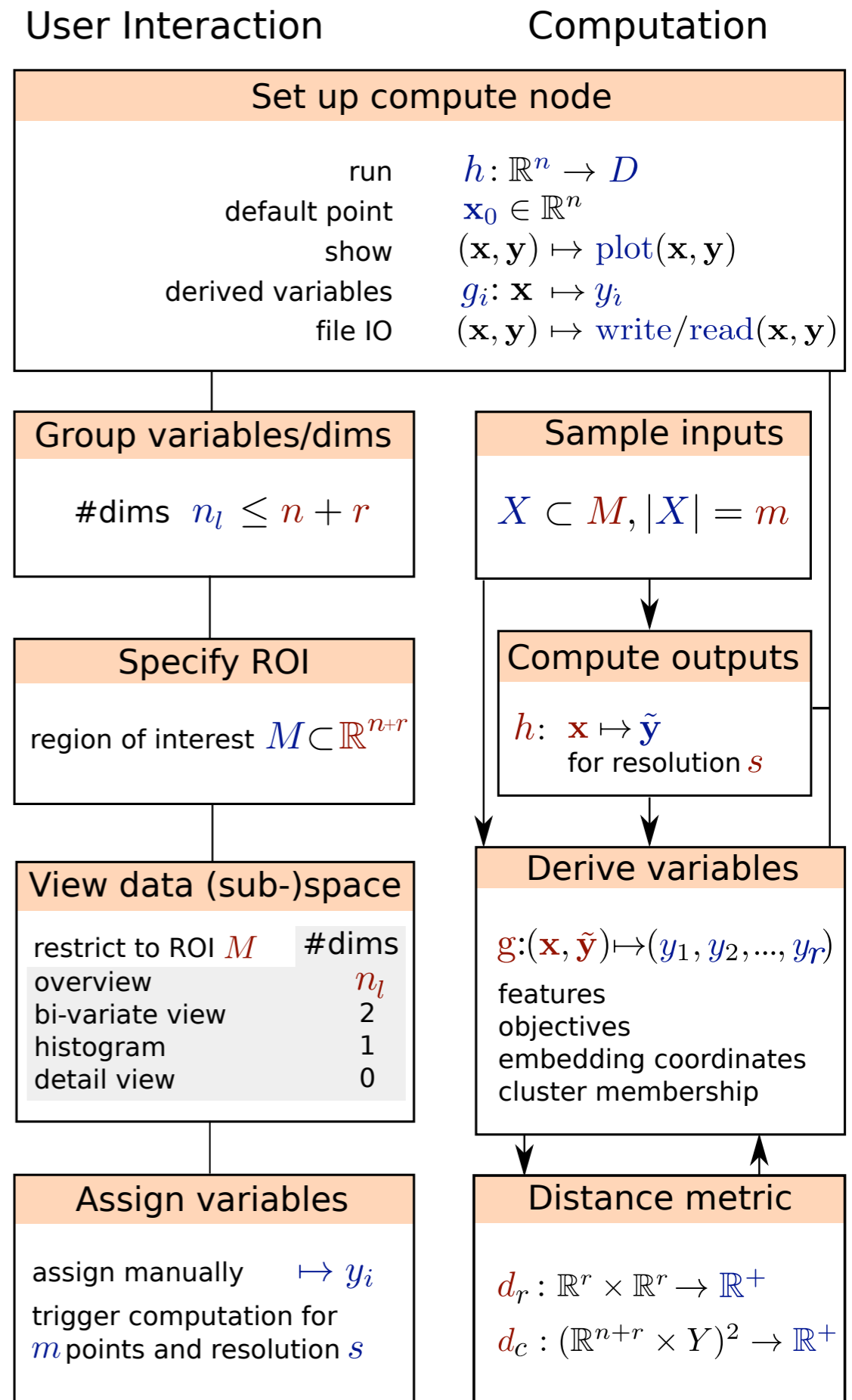
- Parameter space segmentation
- Bio-medical imaging algorithm
- Fuel cell design
- Scene lighting configuration
- Raycasting step size parameter



# *Paraglide* design

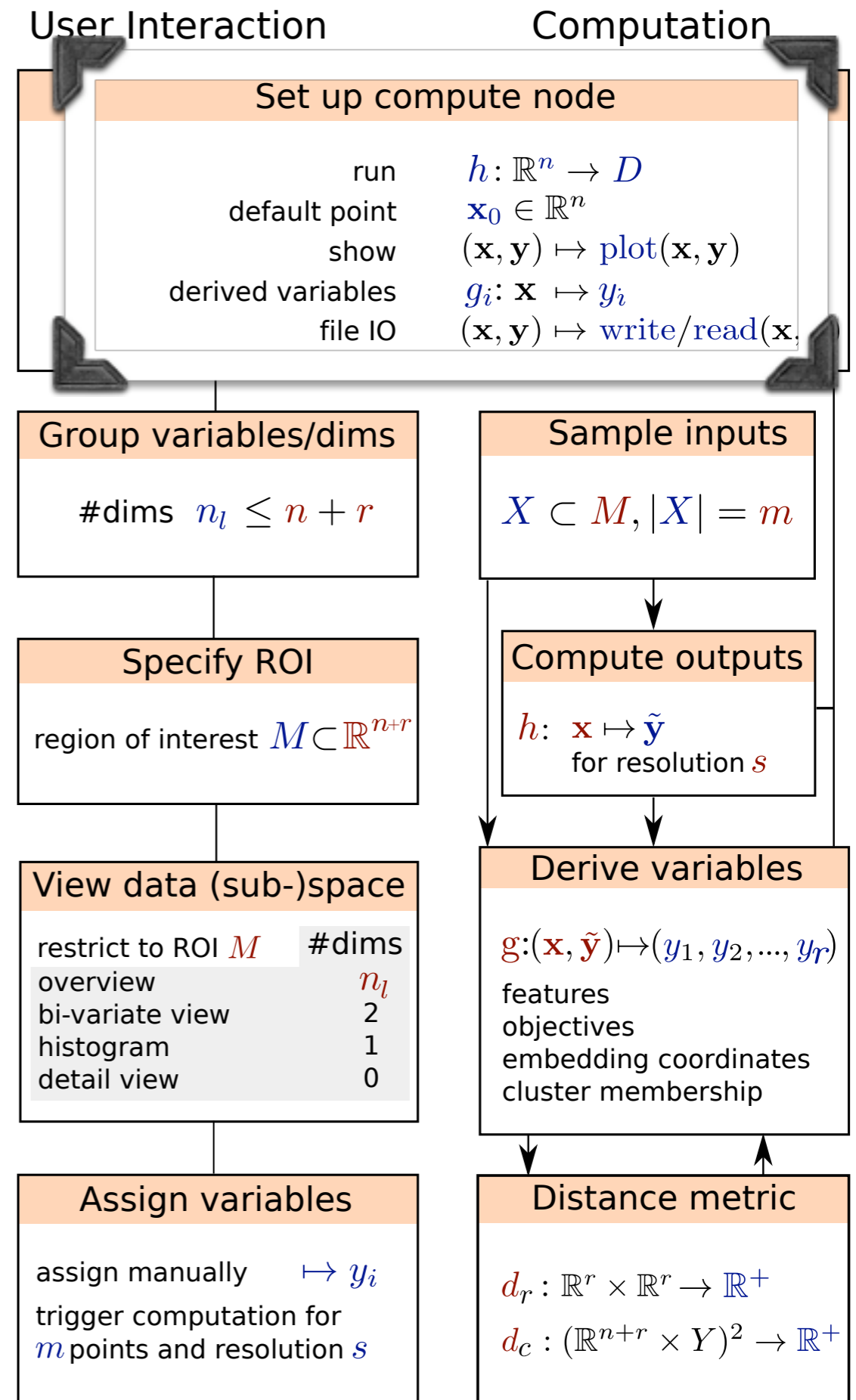


# Paraglidge design



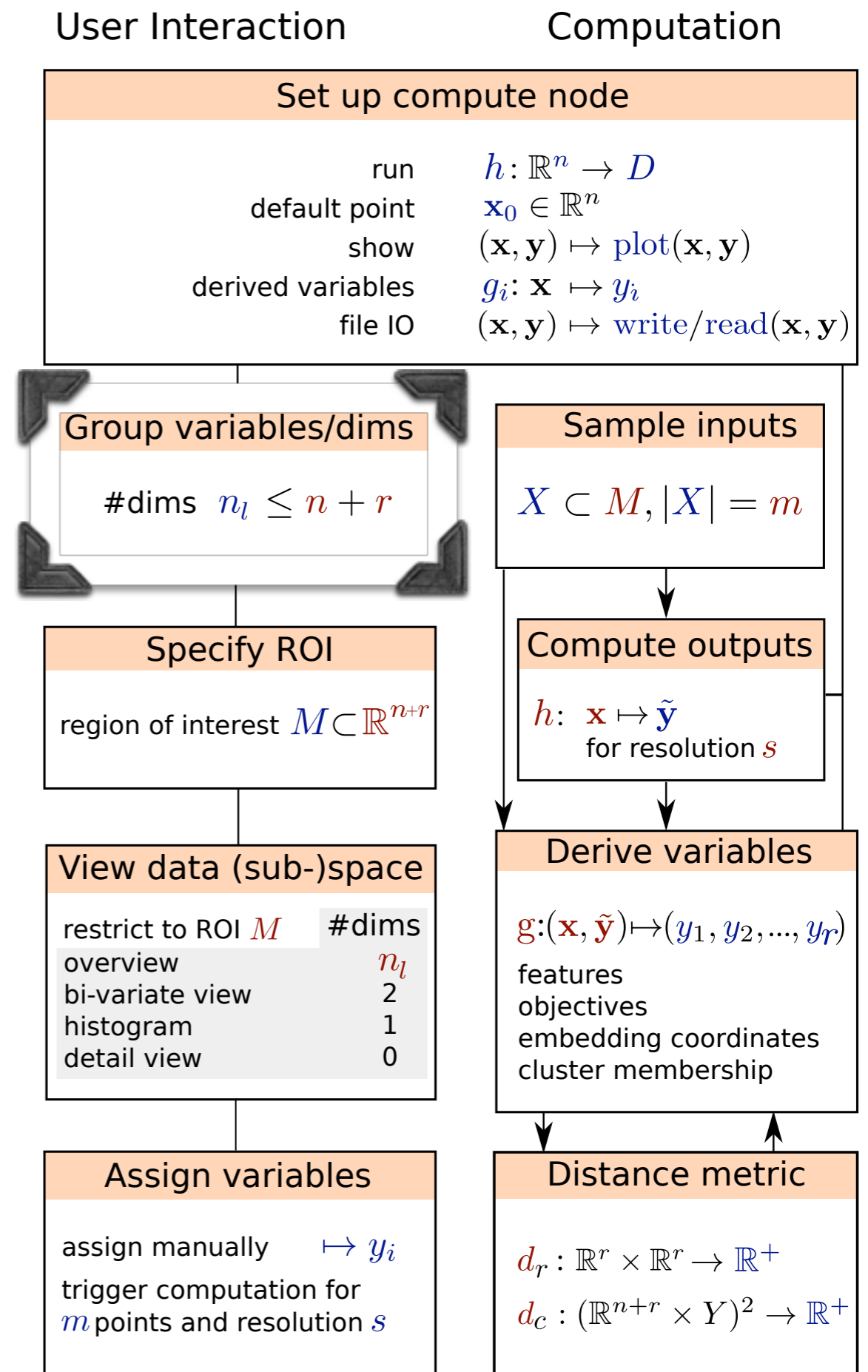
# Paraglide design

- Setup compute node



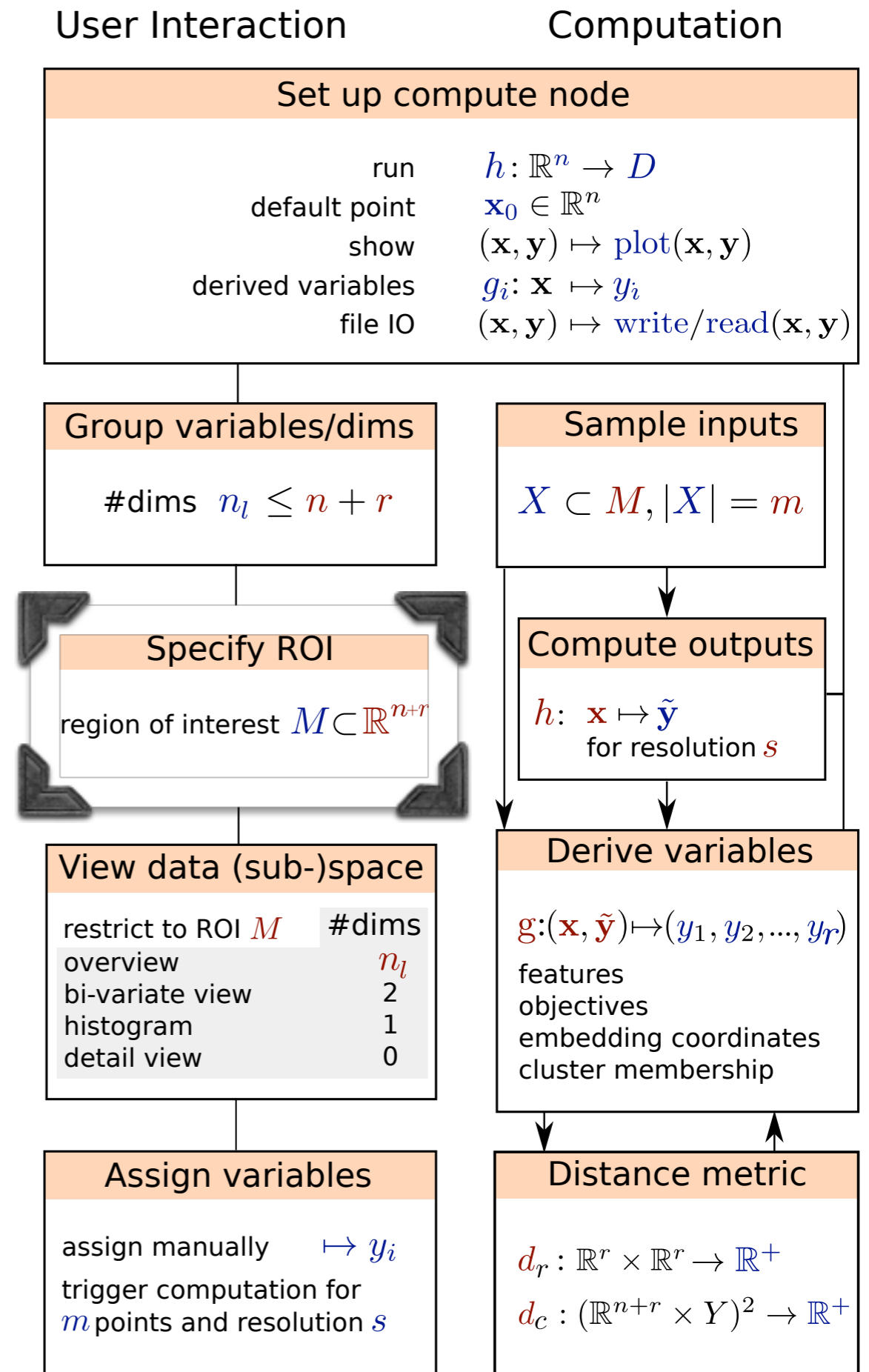
# Paraglide design

- Setup compute node
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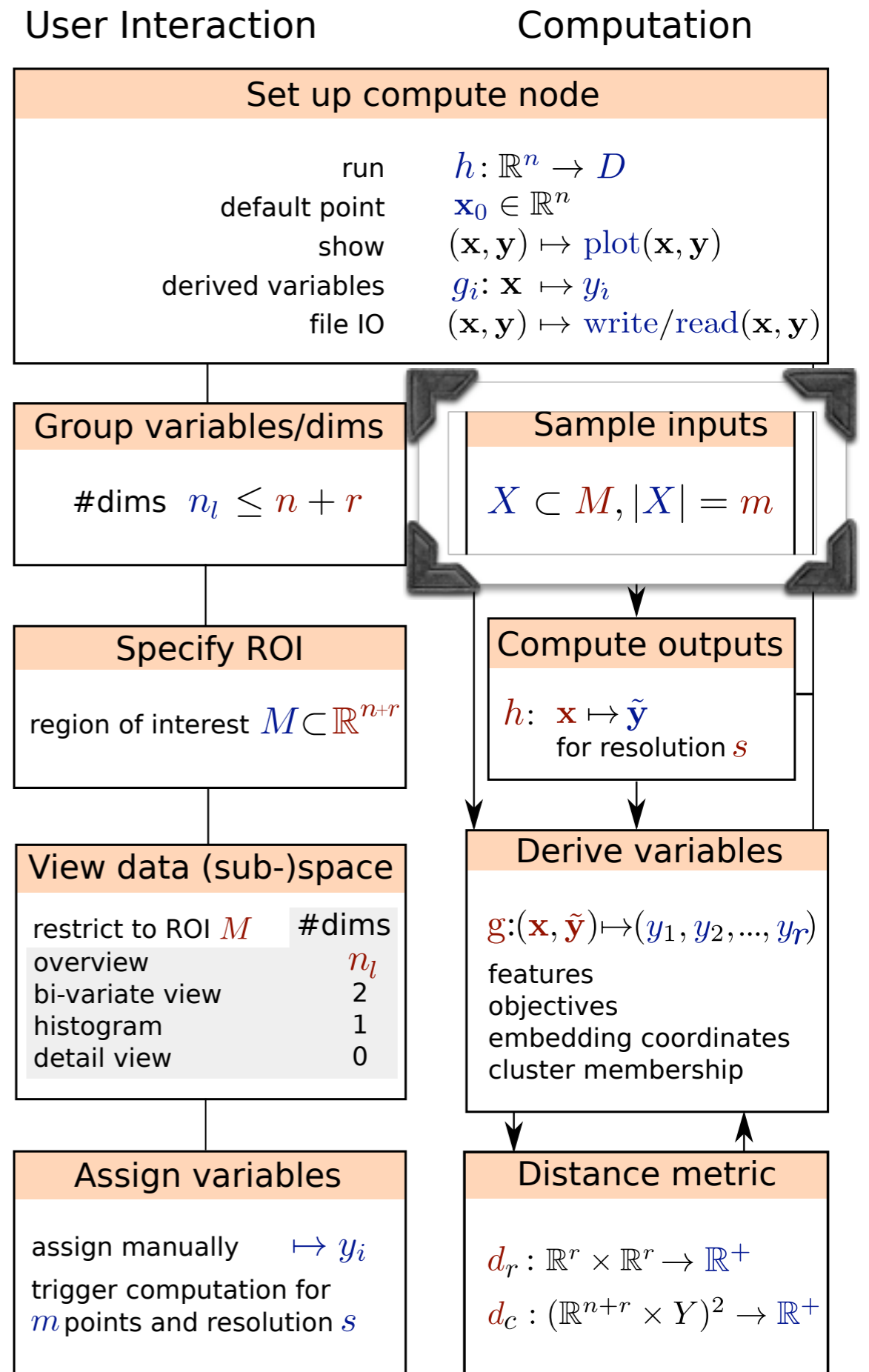
# Paraglide design

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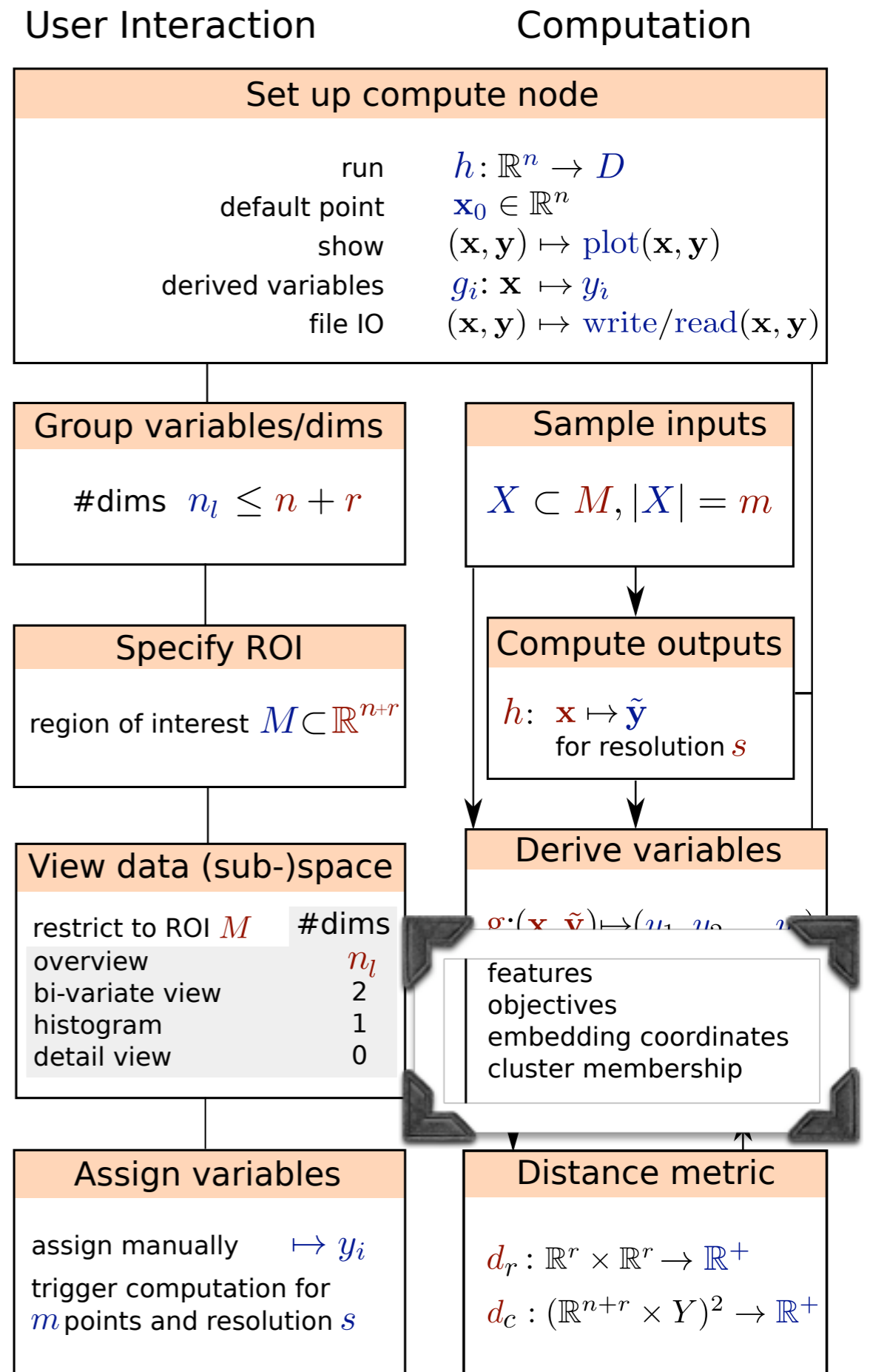
# Paraglidge design

- Setup compute node
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- Choose region
- Sample and compute



# Paraglide design

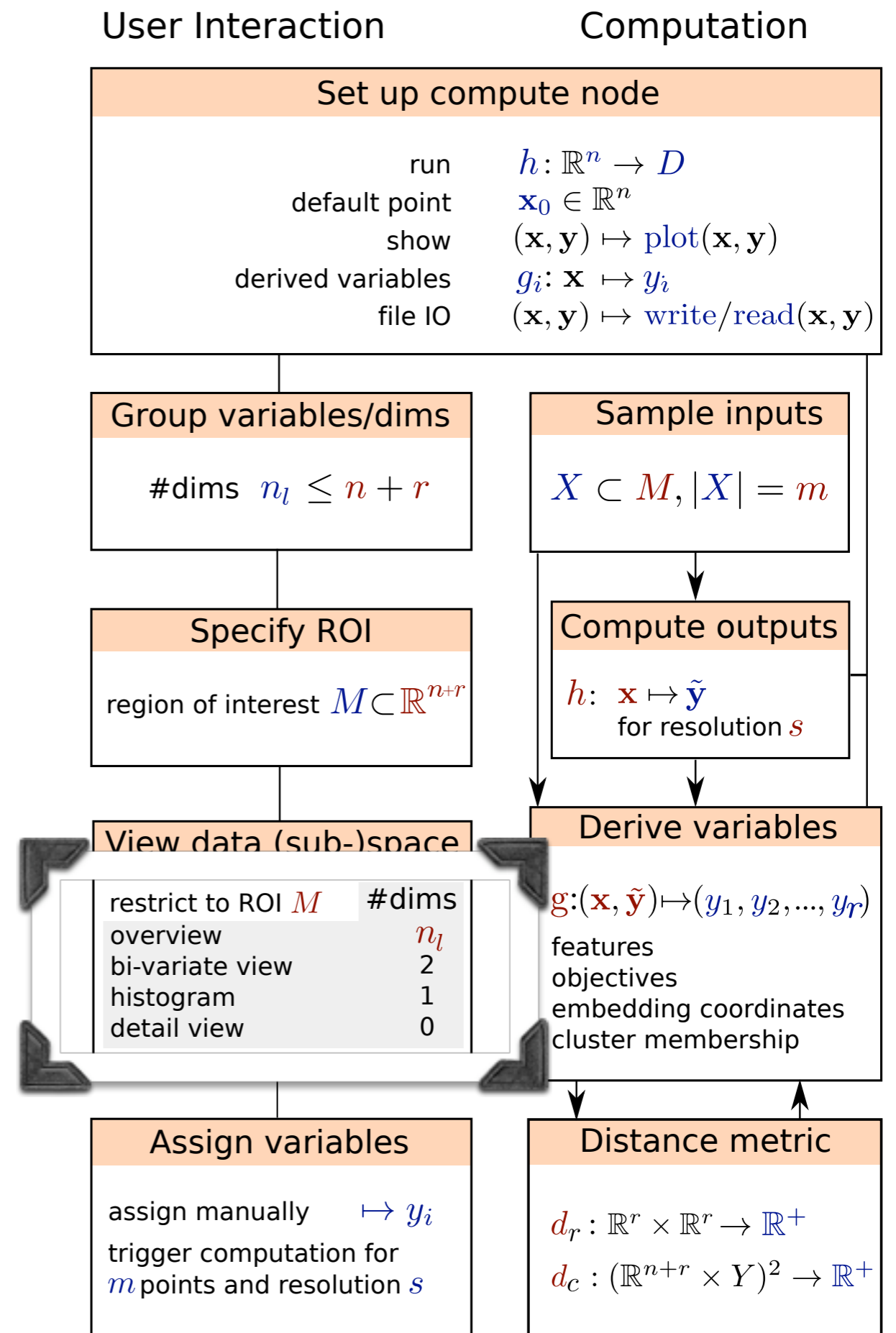
- Setup compute node
- Choose variables
- Choose region
- Sample and compute
- Compute features





# Paraglidge design

- Setup compute node
- Choose variables
- Choose region
- Sample and compute
- Compute features
- View, predict, diagnose



# Sampling the region of interest



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- Tensor product of value levels for each dimension
  - ▶ Nested *for*-loops
  - ▶ Cost is exponential in #dims



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# *Paraglide* summary

- Longitudinal study showed use of parameter space partitioning
- Requirements informed follow-up projects
- Alternative user interaction
  - ▶ Dimensionally reduced slider embedding
  - ▶ Mixing board
- Video demo



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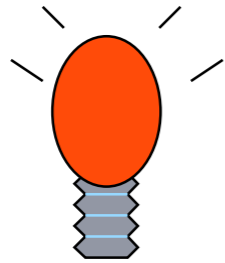




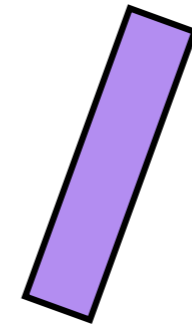
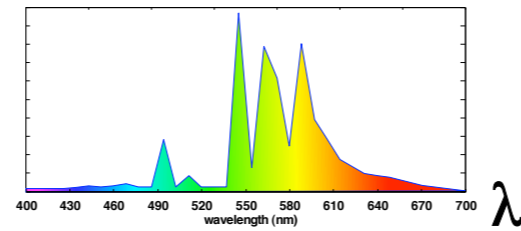
# Roadmap

- From light to colour
- Efficient light model
- Designing spectra for lights and materials
- Evaluation
- Applications

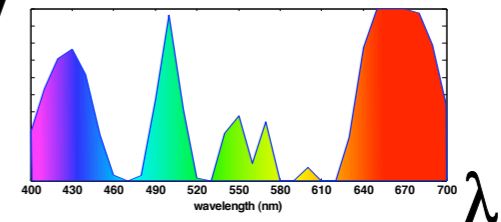
# From Light to Colour



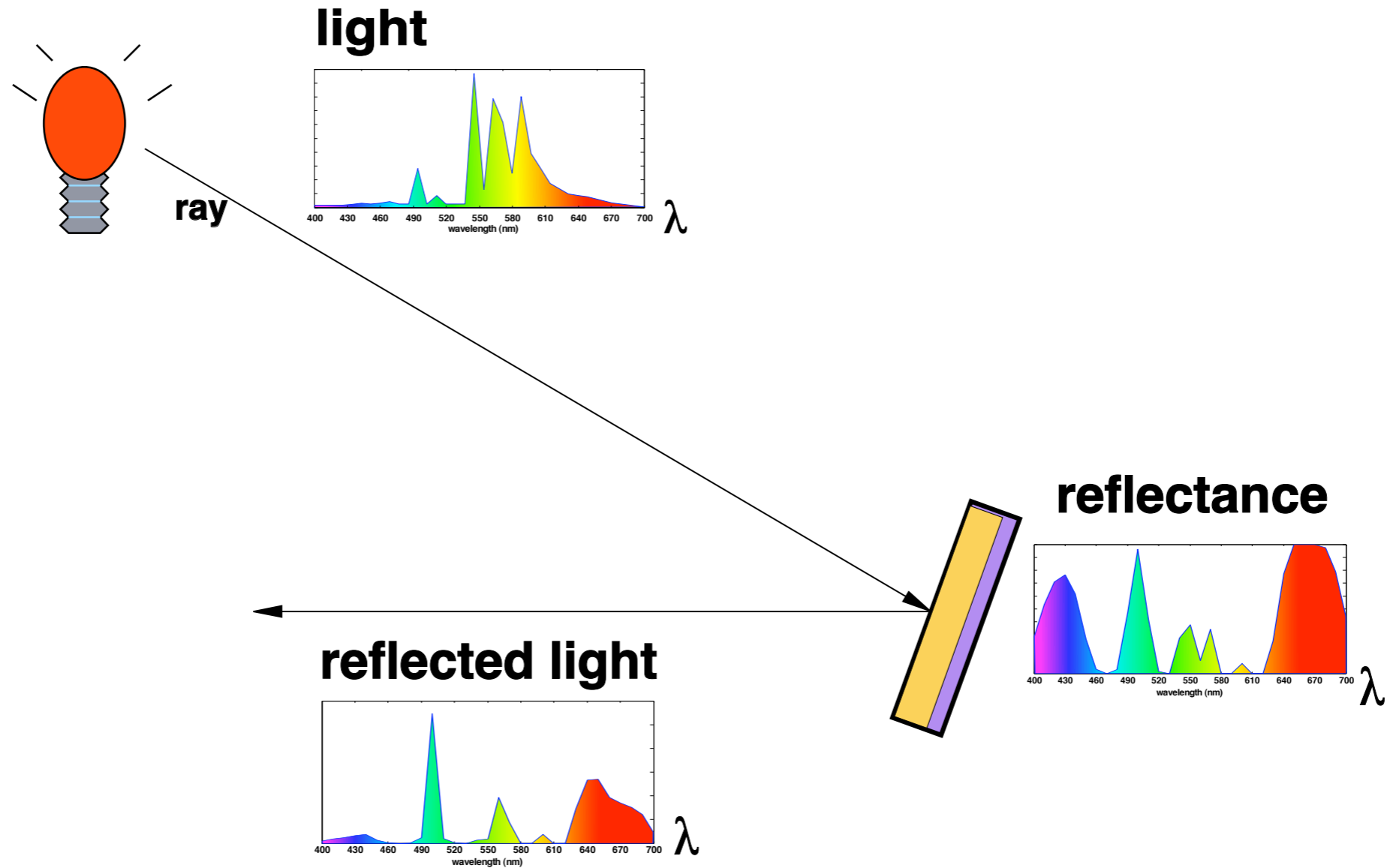
**light**



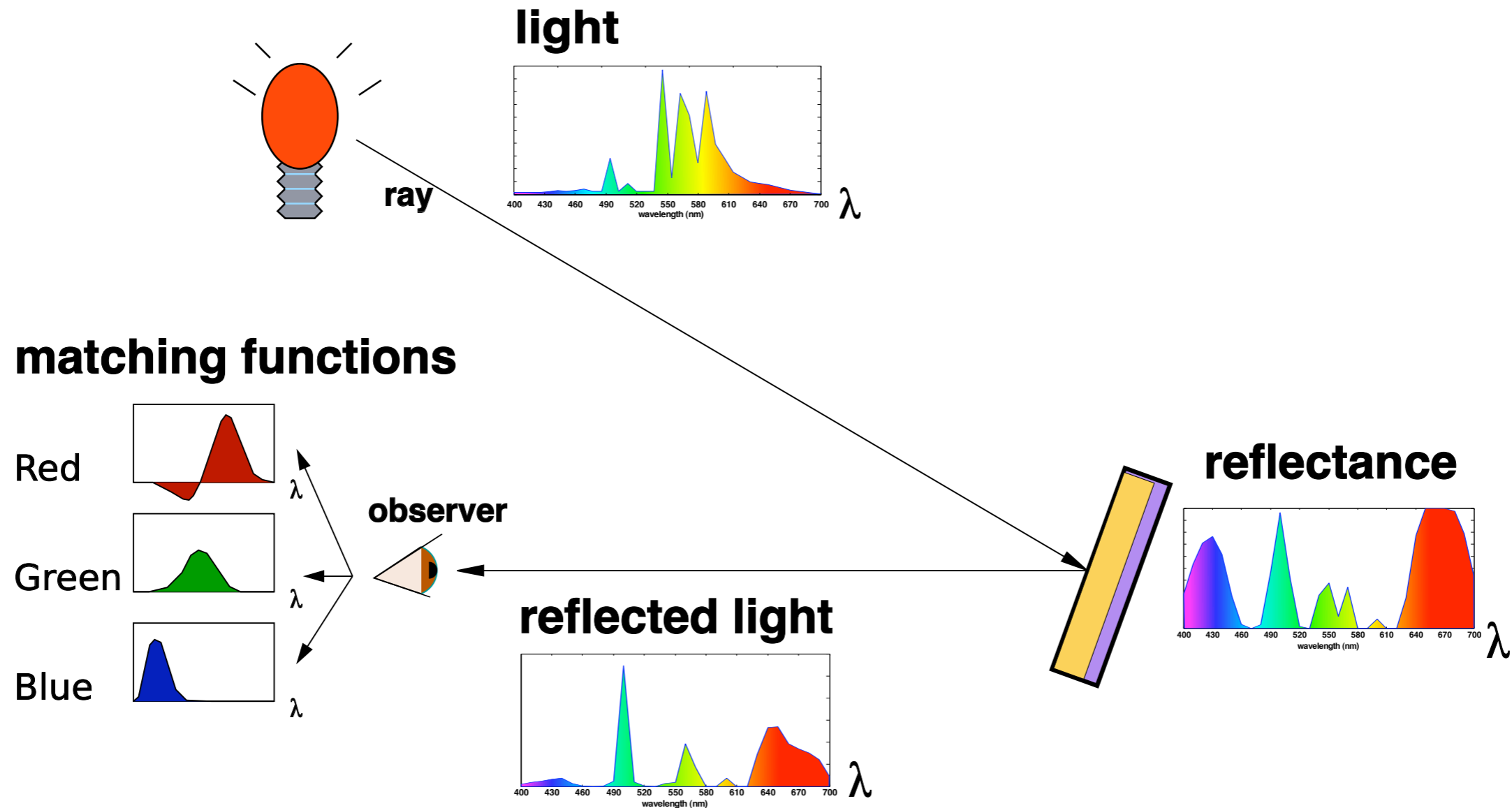
**reflectance**



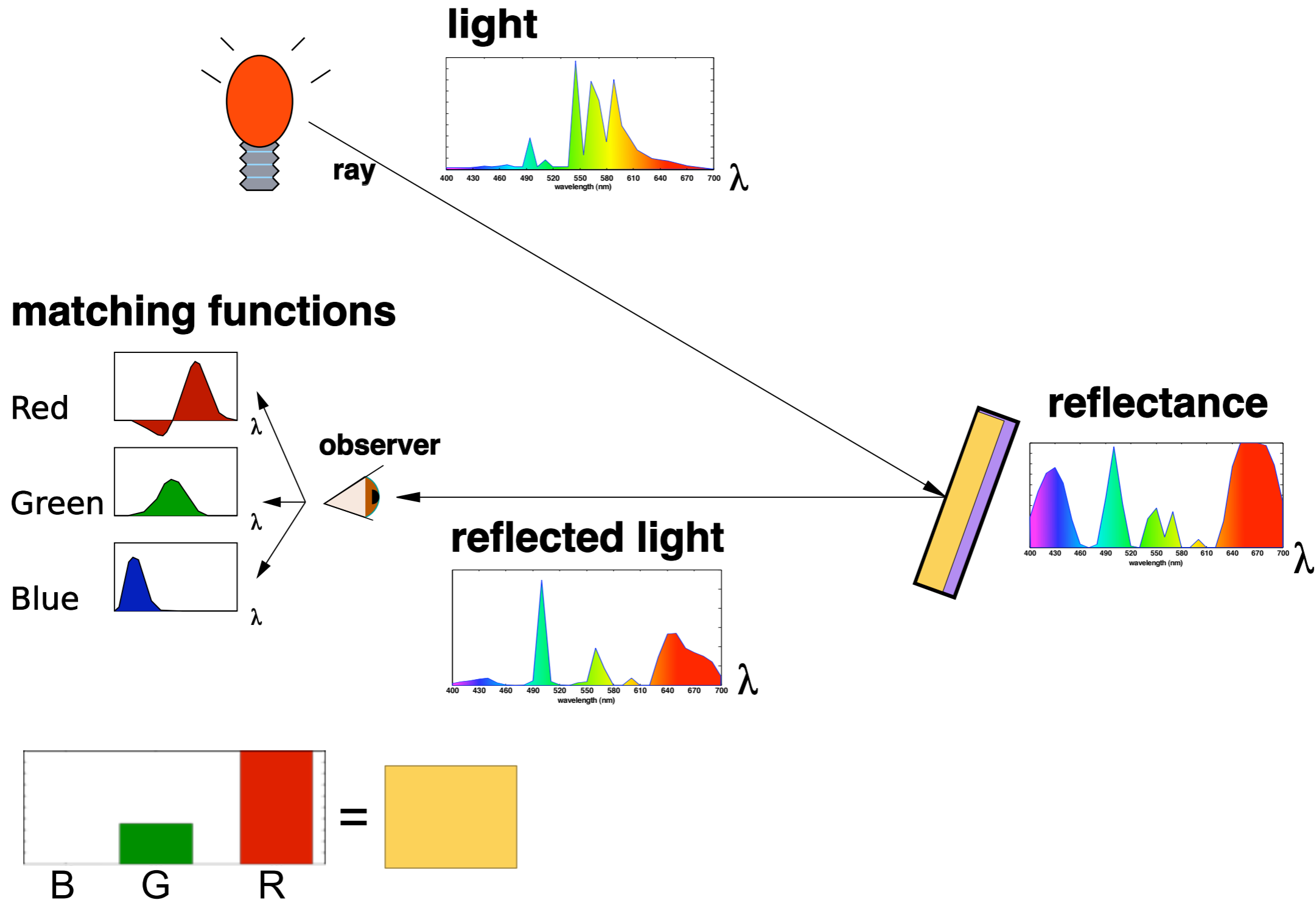
# From Light to Colour



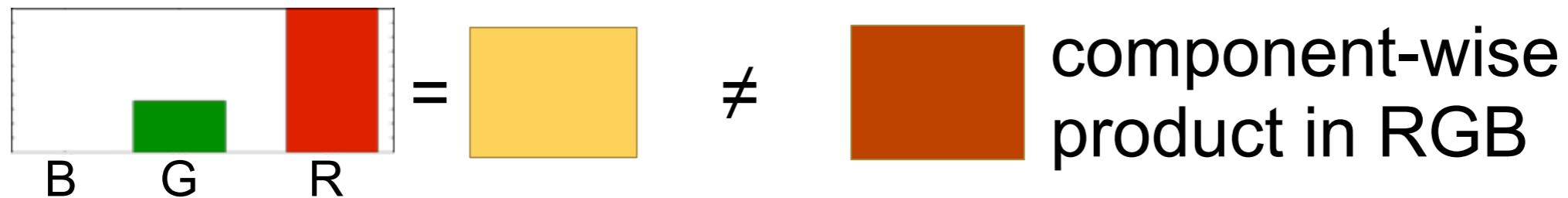
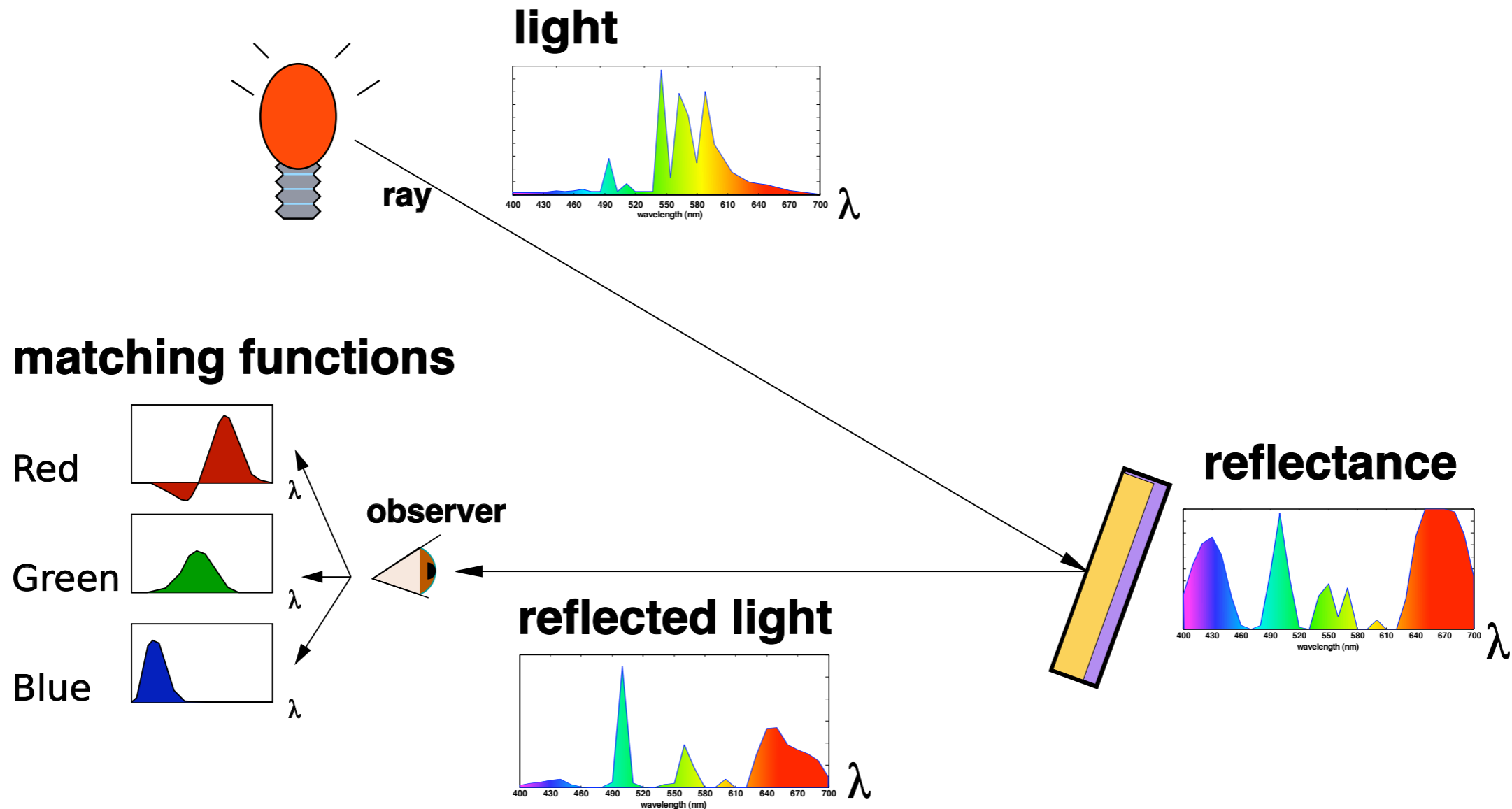
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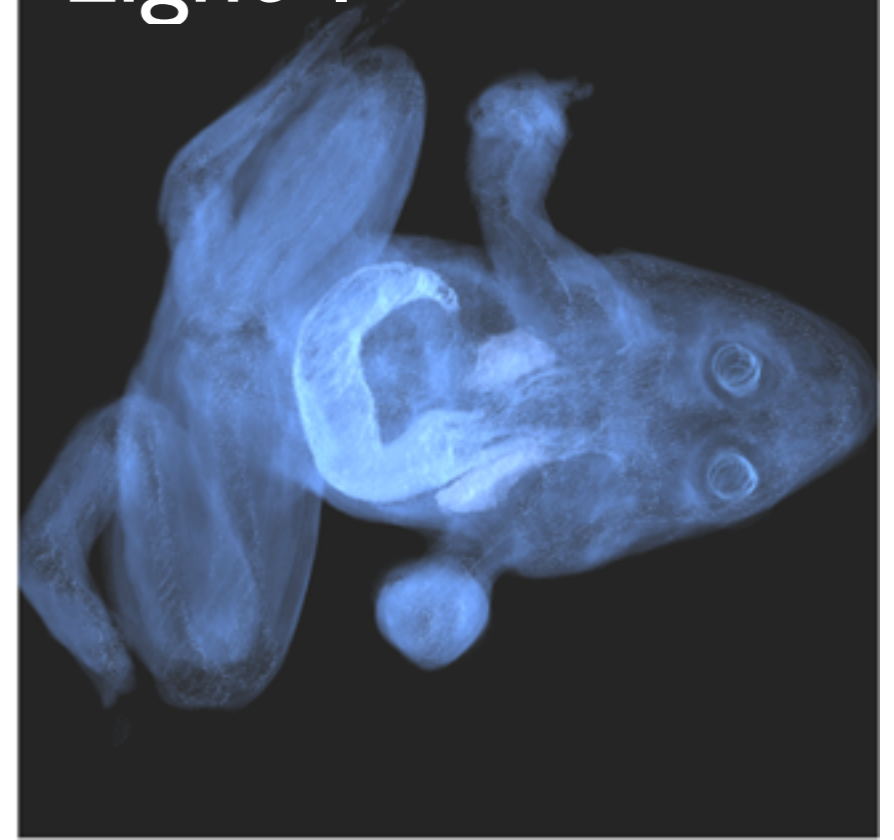


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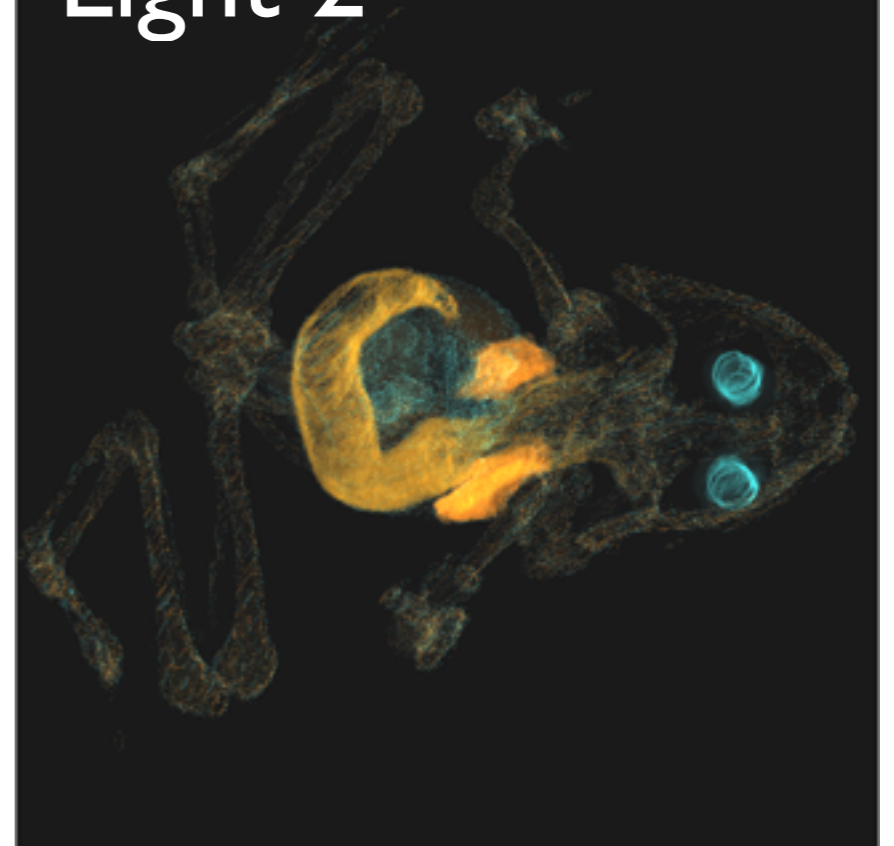


# Use for Visualization

Light 1



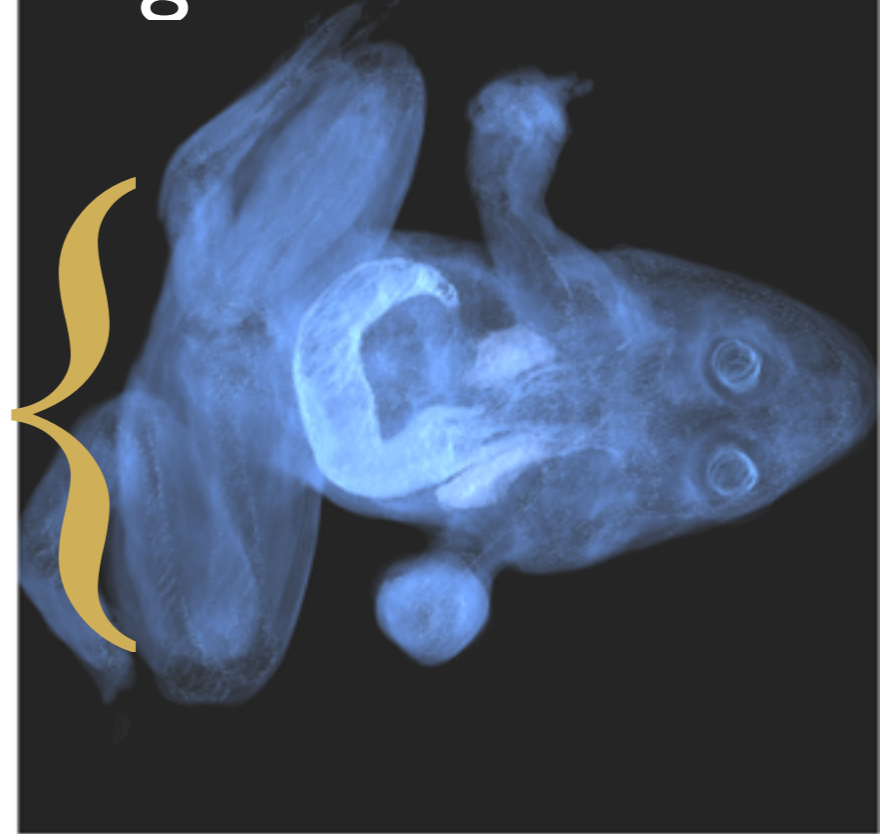
Light 2



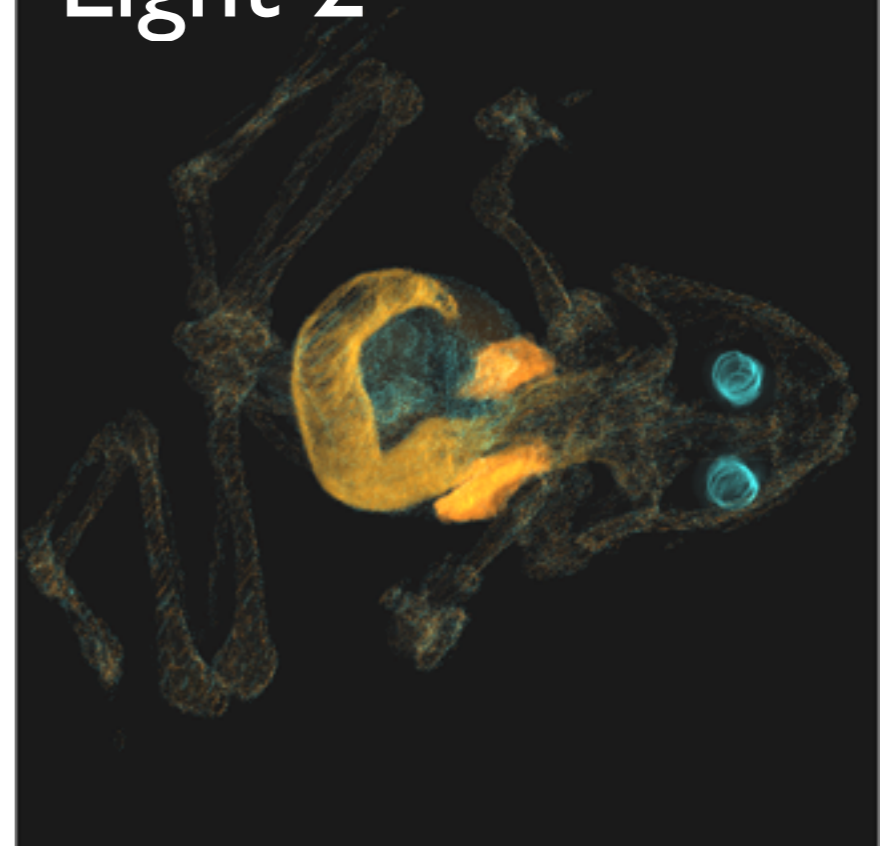
# Use for Visualization

- Metamers
  - ▶ Different Spectra give same RGB

Light 1



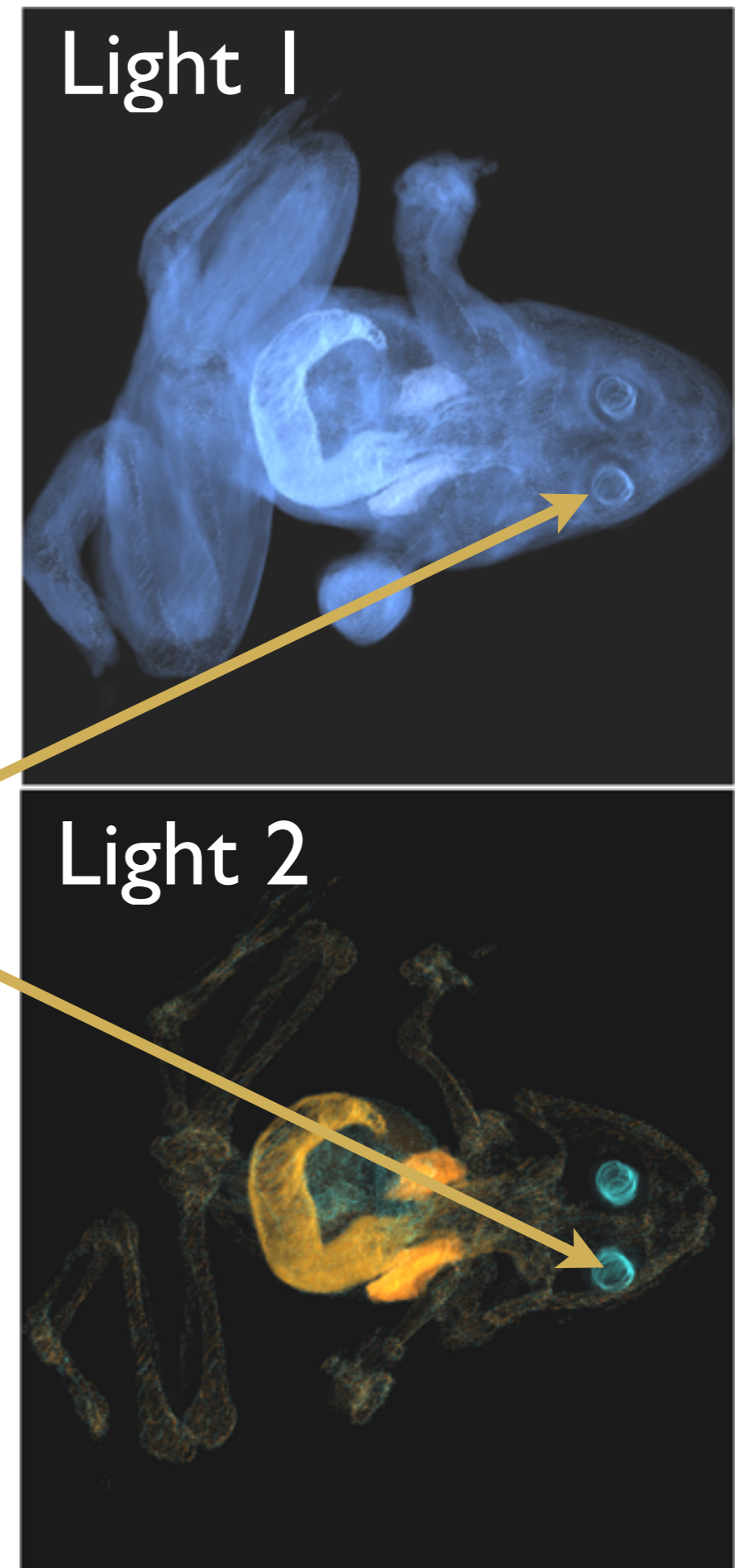
Light 2





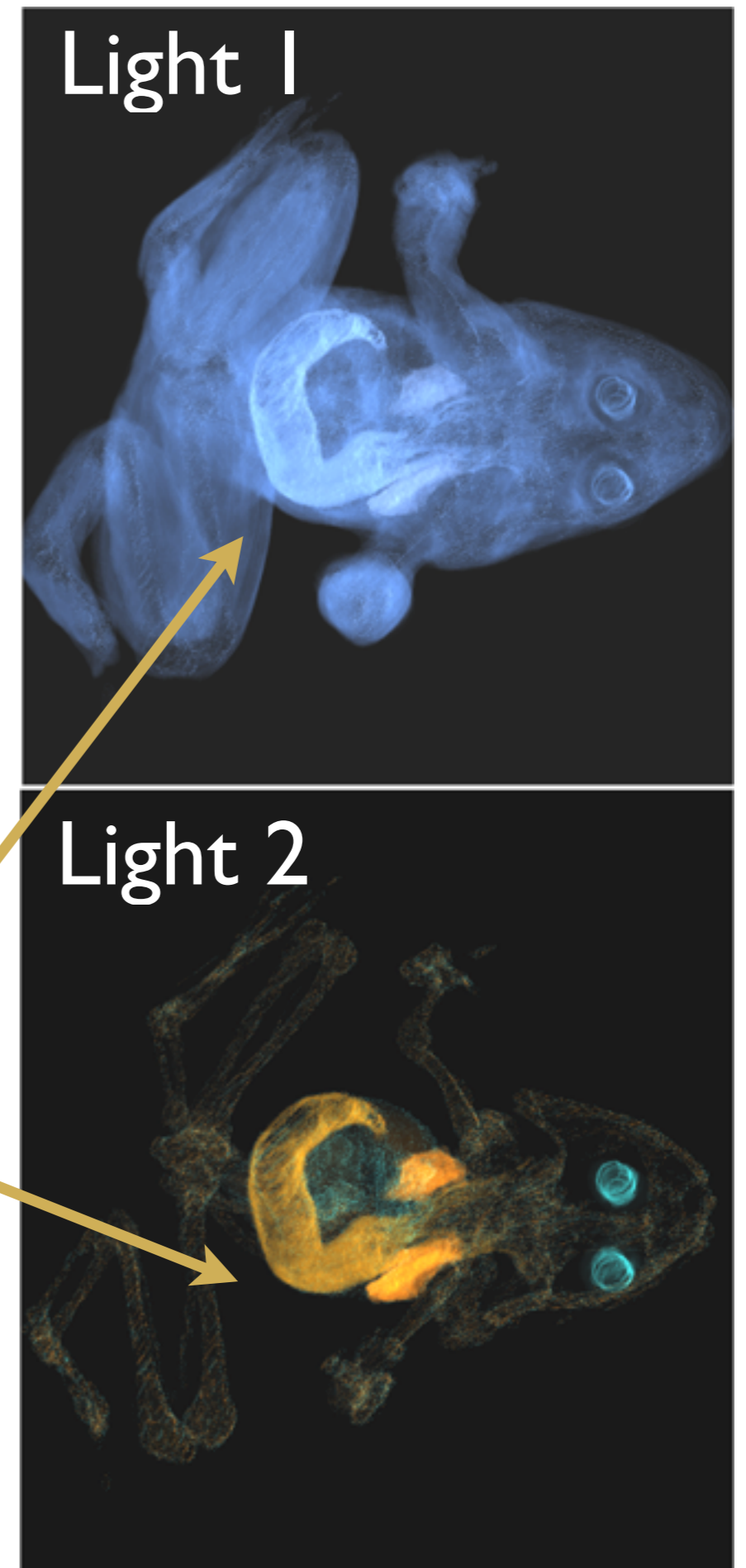
# Use for Visualization

- Metamers
  - ▶ Different Spectra give same RGB
- Constant Colours
  - ▶ Metamers under changing light



# Use for Visualization

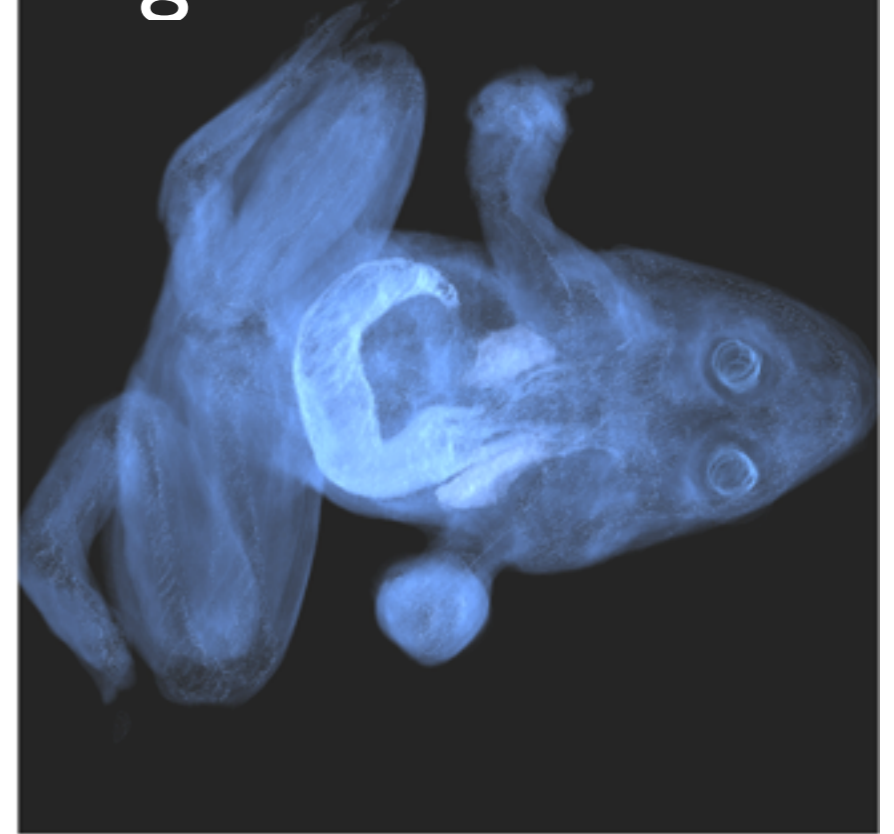
- Metamers
  - ▶ Different Spectra give same RGB
- Constant Colours
  - ▶ Metamers under changing light
- Metameric Blacks
  - ▶ Spectra give RGB triple = 0



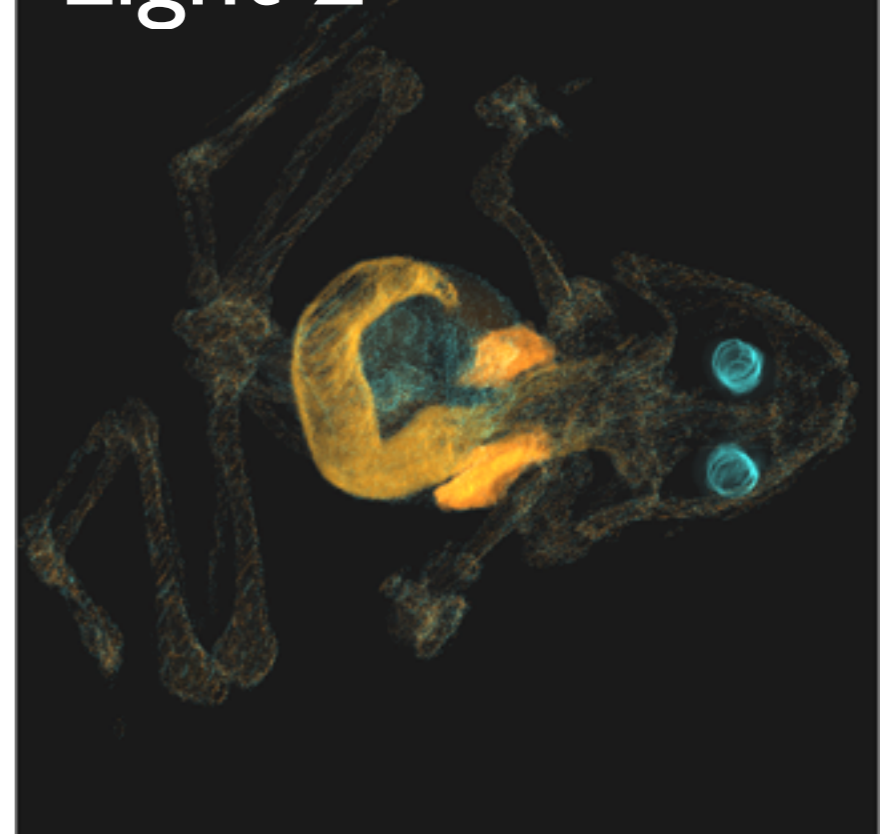
# Use for Visualization

- Metamers
  - ▶ Different Spectra give same RGB
- Constant Colours
  - ▶ Metamers under changing light
- Metameric Blacks
  - ▶ Spectra give RGB triple = 0
- Effective choice of light & material palette needed!

Light 1



Light 2



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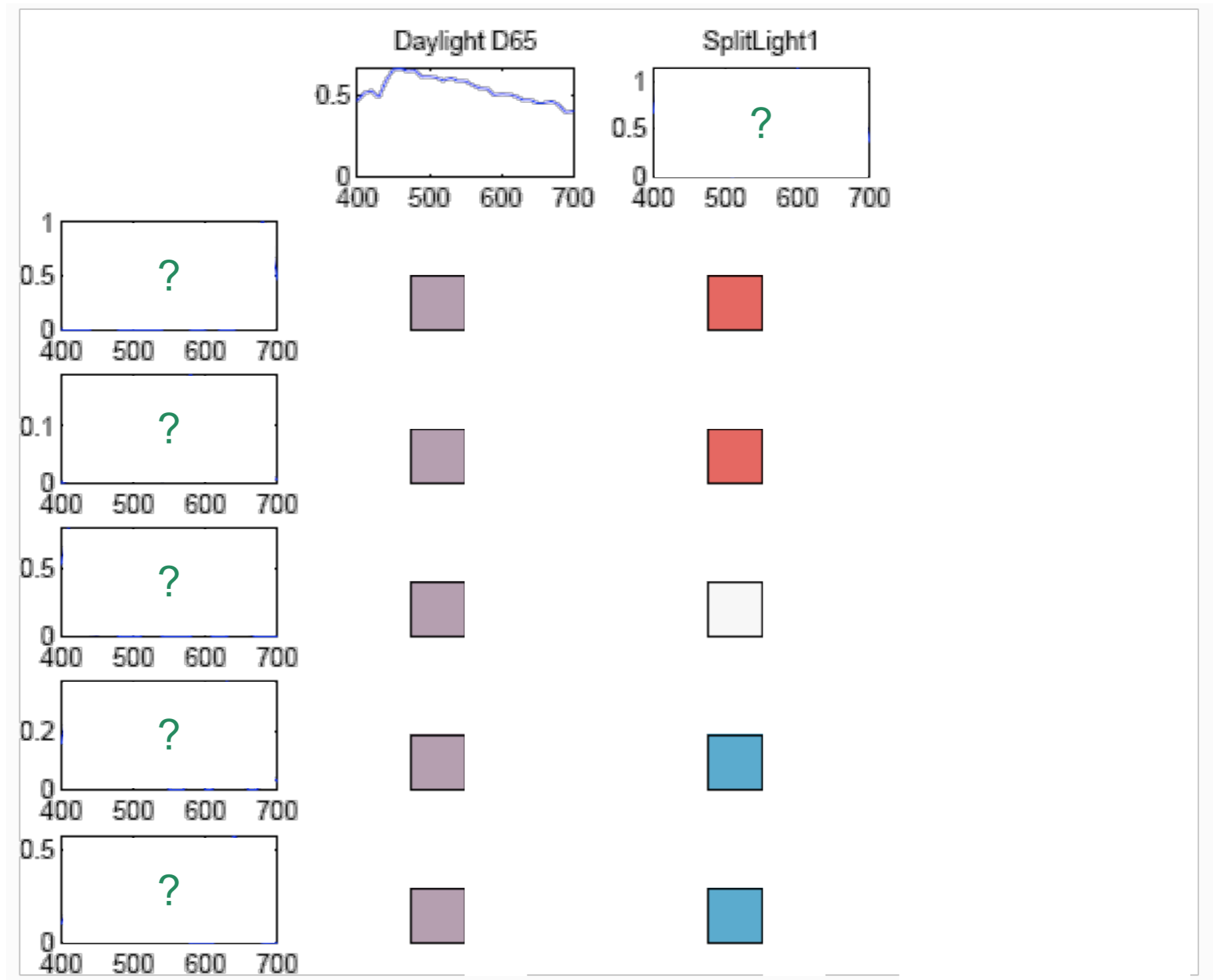
# Illumination Dependent Colour Picker



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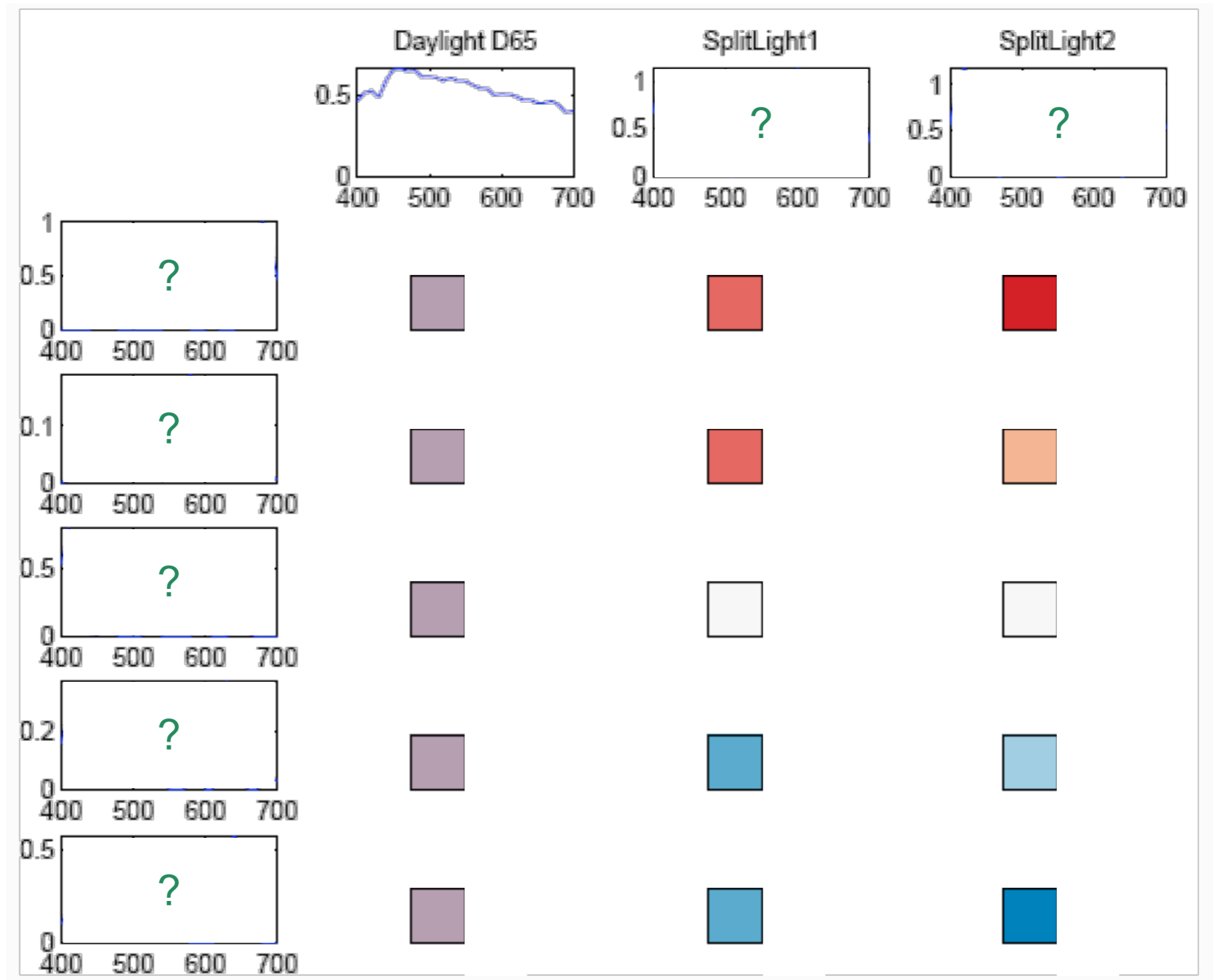


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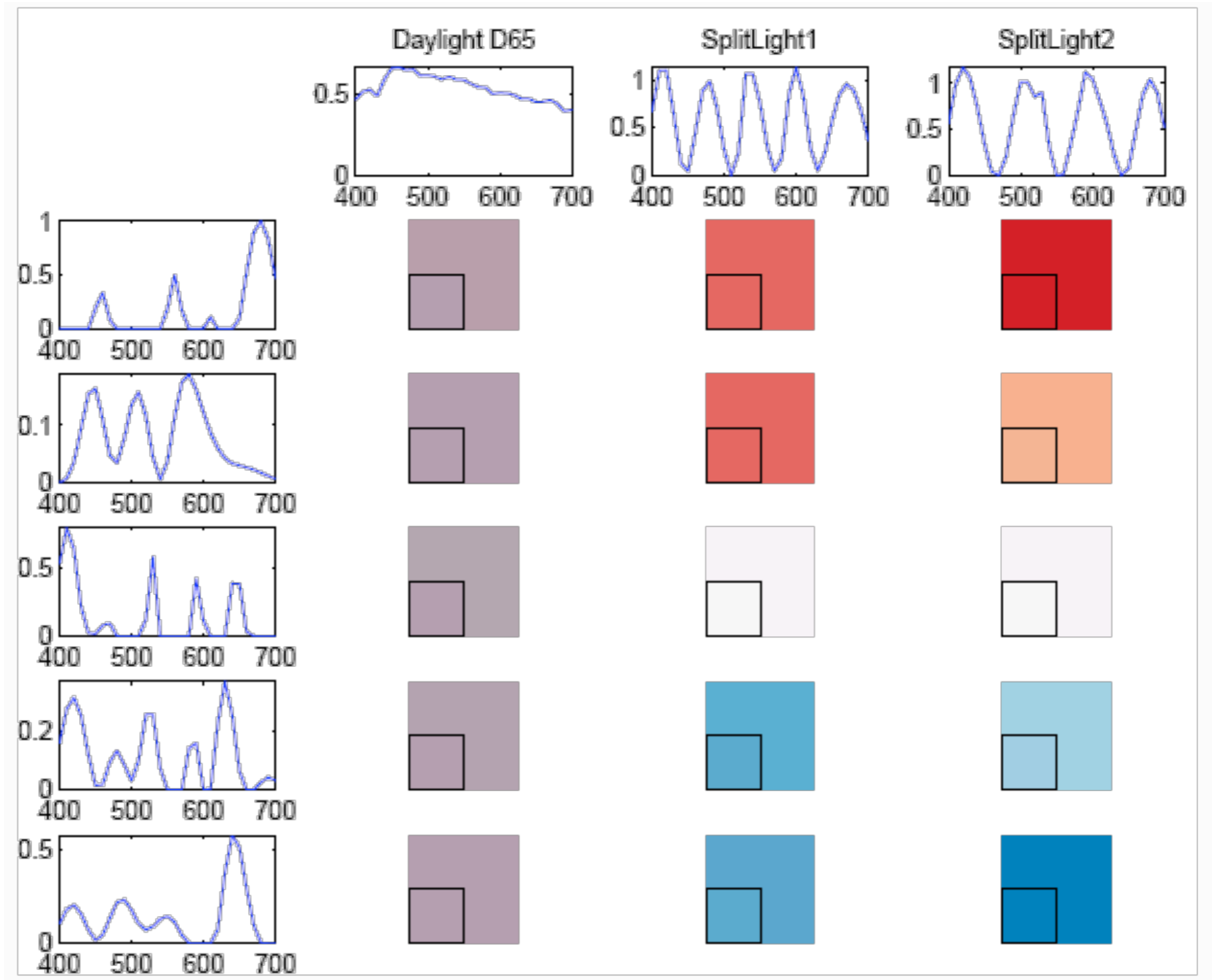




# Illumination Dependent Colour Picker



# Illumination Dependent Colour Picker



# Quality Criteria

- Colour

- Fit the desired colour or metamer

- Smoothness

- Regularize solution and reduce extrema

- Minimal error in linear model

- Minimal colour difference when illumination bounce is computed in linear subspace

- Positivity

- Produce physically plausible spectra

# Quality Criteria

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- Instead of equation system  $\mathbf{M}\vec{x} = \vec{y}$  for spectrum  $\vec{x}$   
Solve normal equation  $\operatorname{argmin}_{\vec{x}} \|\mathbf{M}\vec{x} - \vec{y}\|$

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– Colour:  $\operatorname{argmin}_{\vec{x}} \left\| \begin{bmatrix} \mathbf{m}_{red} \\ \mathbf{m}_{green} \\ \mathbf{m}_{blue} \end{bmatrix} \operatorname{diag}(\vec{S})\vec{x} - \begin{bmatrix} c_r \\ c_g \\ c_b \end{bmatrix} \right\|$

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– Smoothness:  $\operatorname{argmin}_{\vec{x}} \left\| \begin{bmatrix} -1 & 2 & -1 & 0 & \dots & 0 \\ 0 & -1 & 2 & -1 & \dots & 0 \\ & & & \ddots & & \\ 0 & 0 & \dots & -1 & 2 & -1 \end{bmatrix} \vec{x} - \begin{bmatrix} 0 \\ 0 \\ \vdots \\ 0 \end{bmatrix} \right\|$

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- Weight the criteria and combine as stacked matrix
  - Global minimum error solution via pseudo-inverse of  $\mathbf{M}$
  - Positivity through quadratic programming



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# Materials and lighting

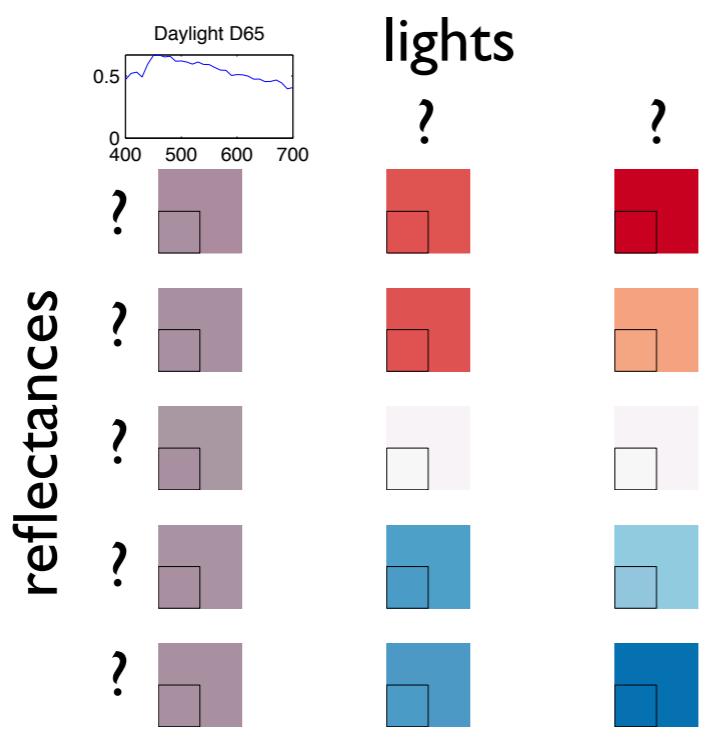


# Materials and lighting

Given: Output	Goal: Input

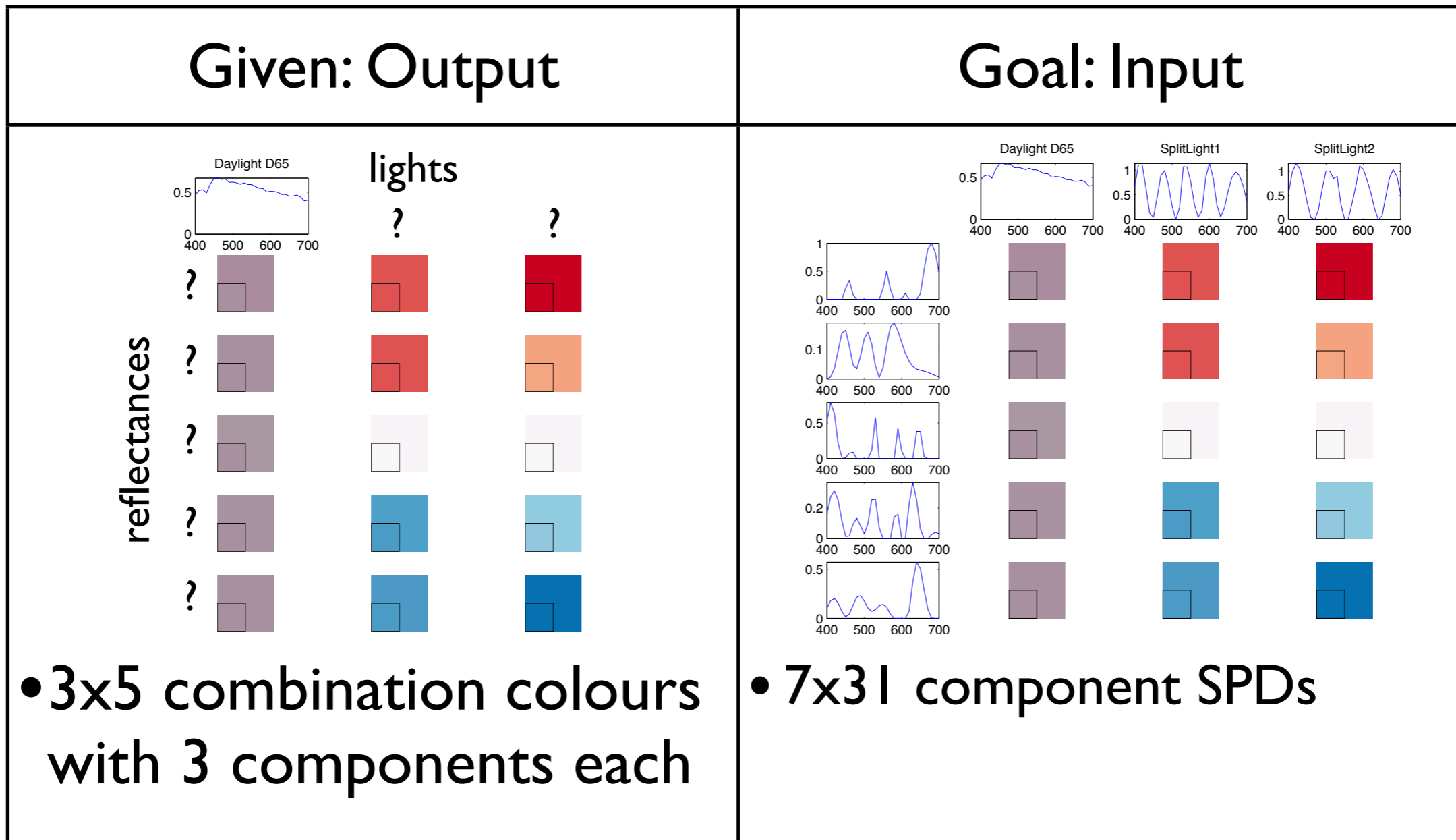


# Materials and lighting

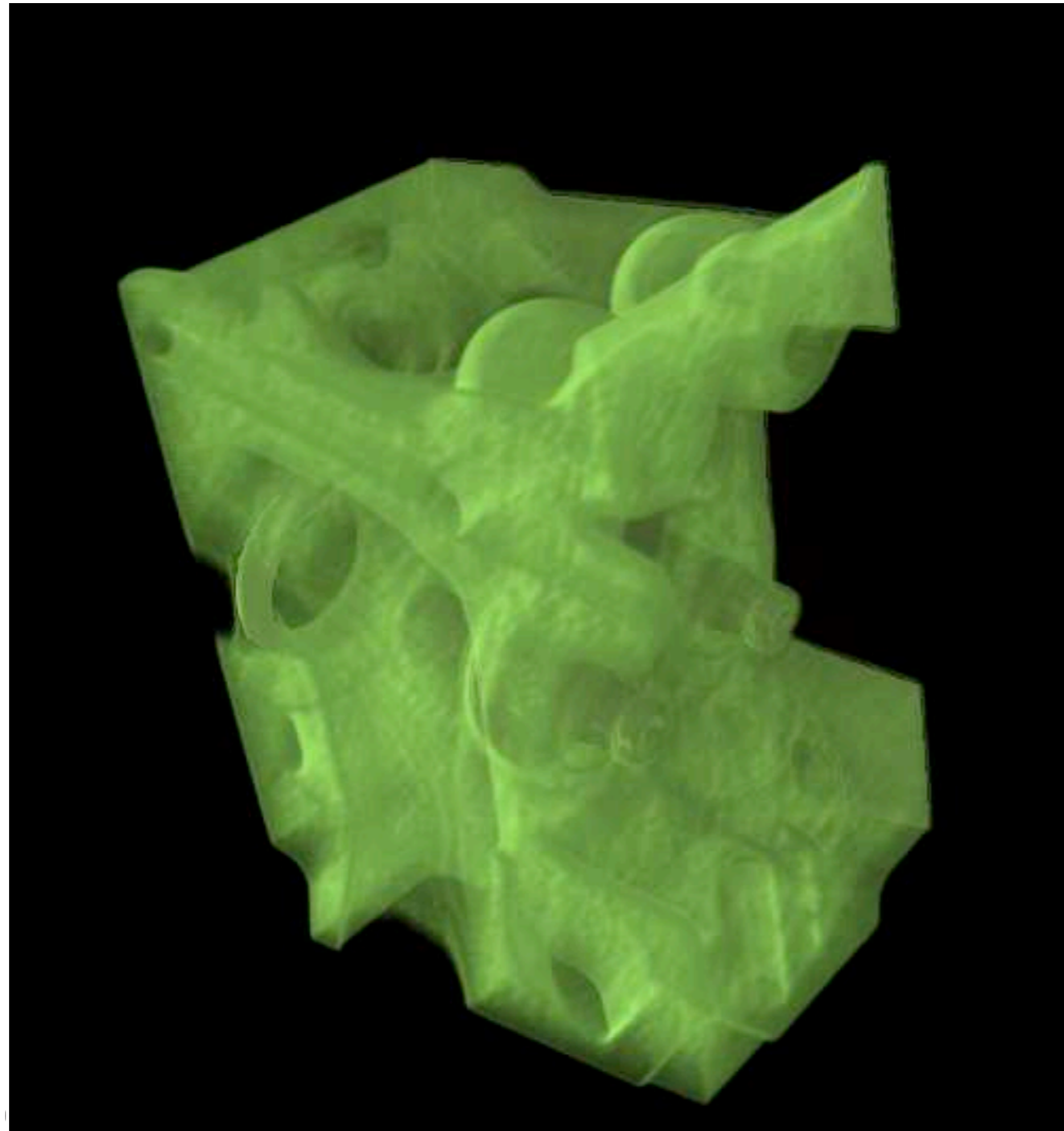
Given: Output	Goal: Input	
 <p>Daylight D65</p> <p>reflectances</p> <p>lights</p> <ul style="list-style-type: none"> <li>• 3x5 combination colours with 3 components each</li> </ul>		



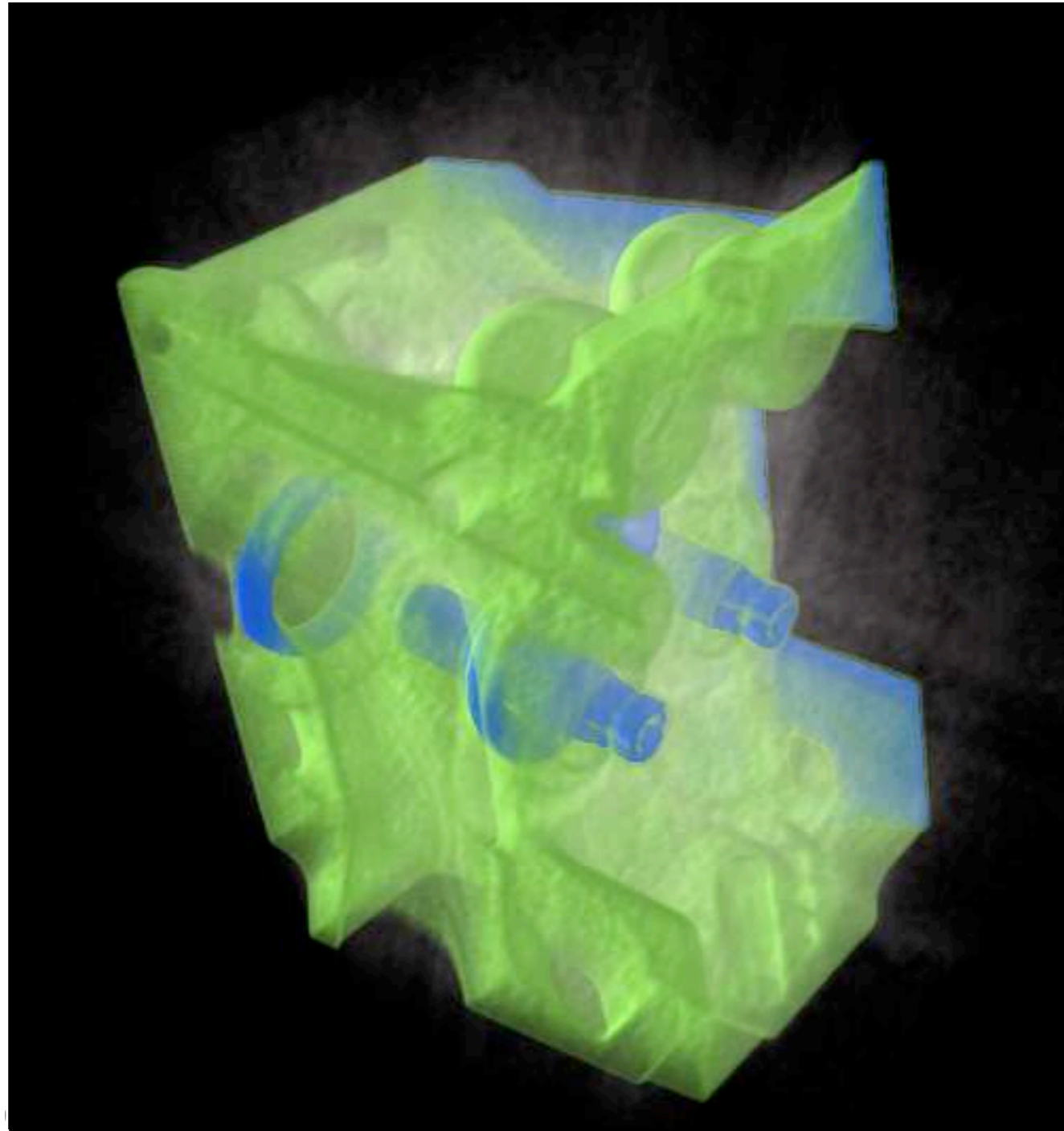
# Materials and lighting



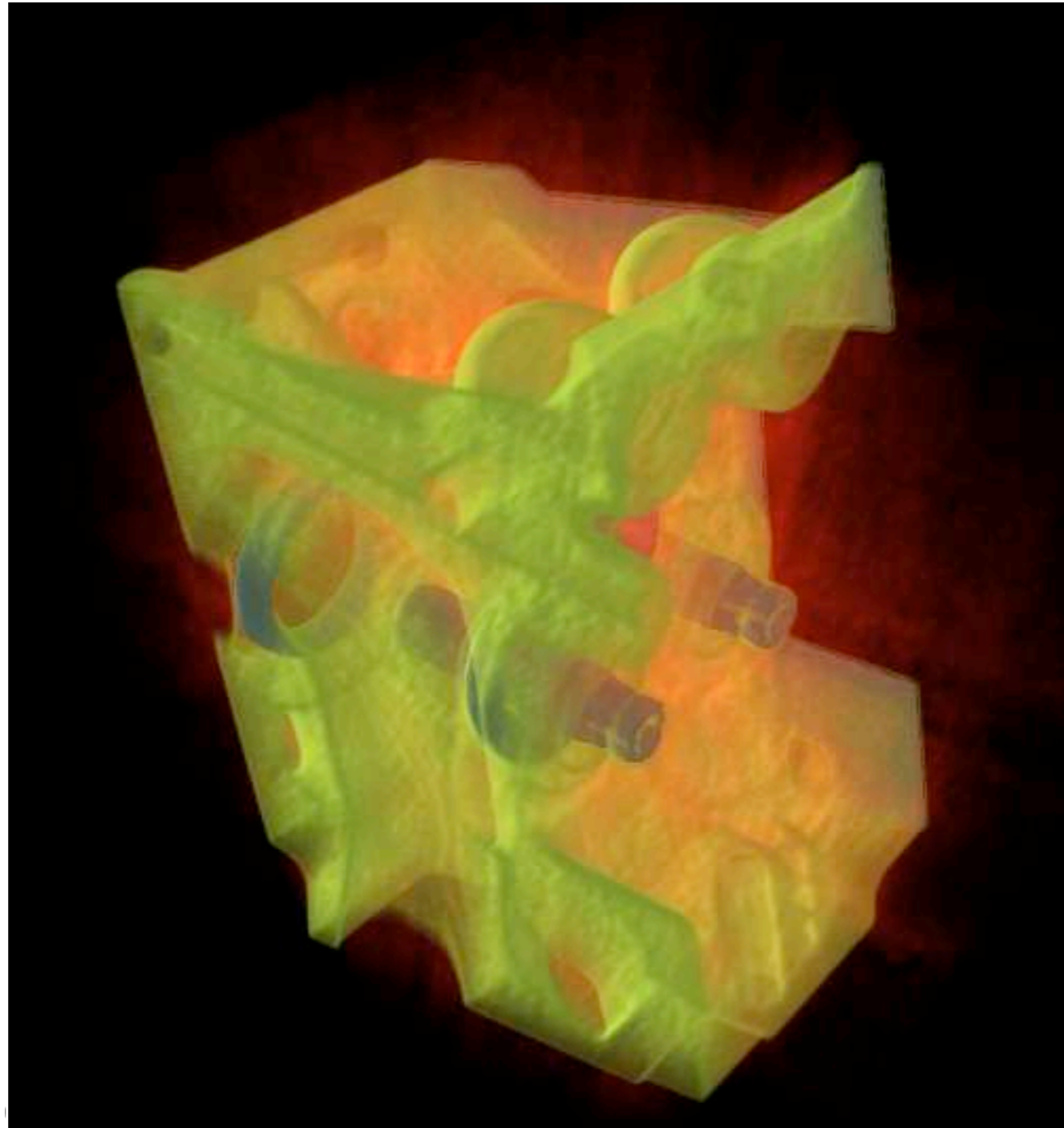
# Image based re-lighting



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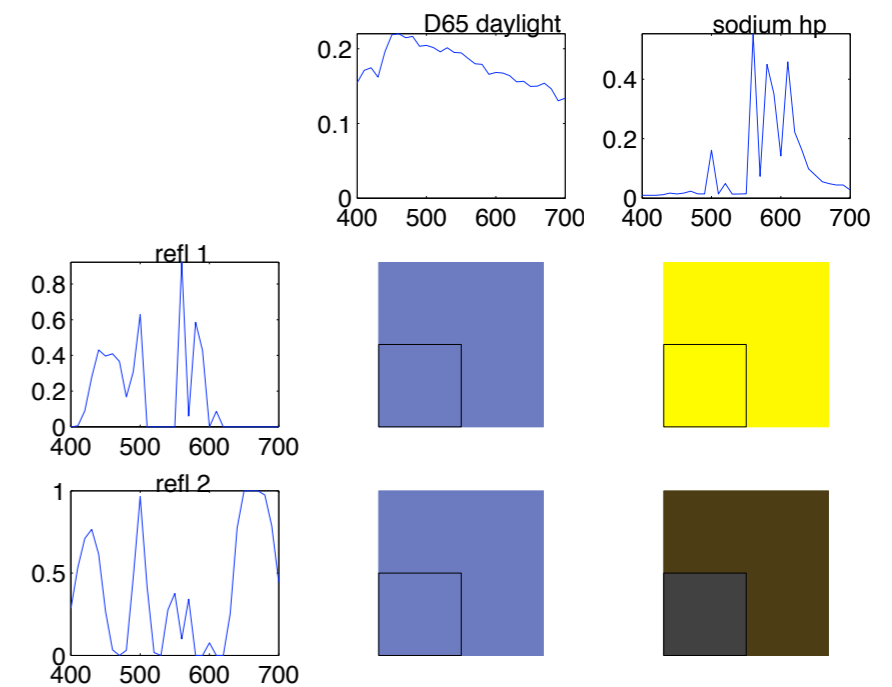
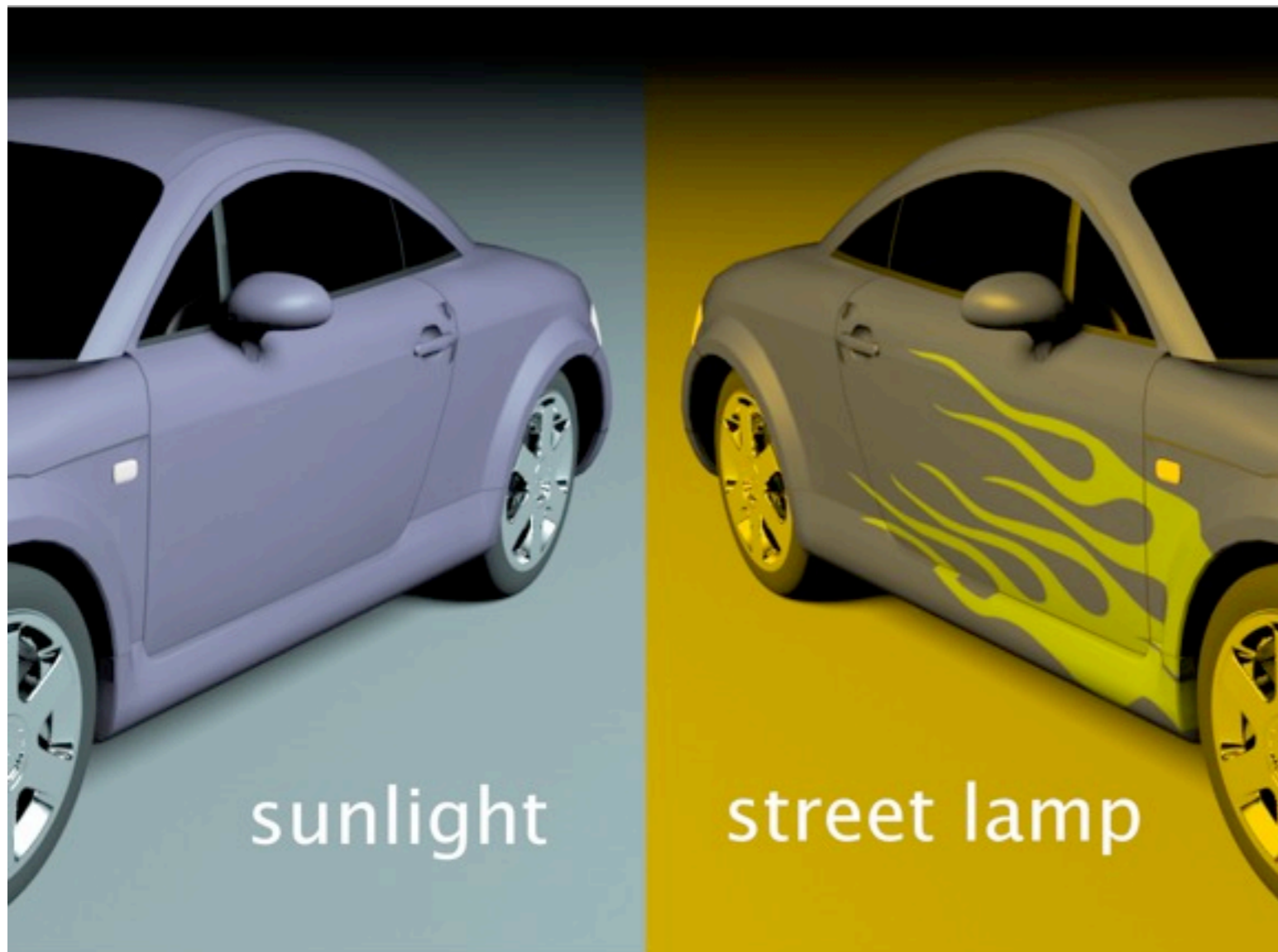


# Image based re-lighting





# Applications in Graphics and Visualization



- Additional texture details appear under changing illumination

# Model adjustment at different levels

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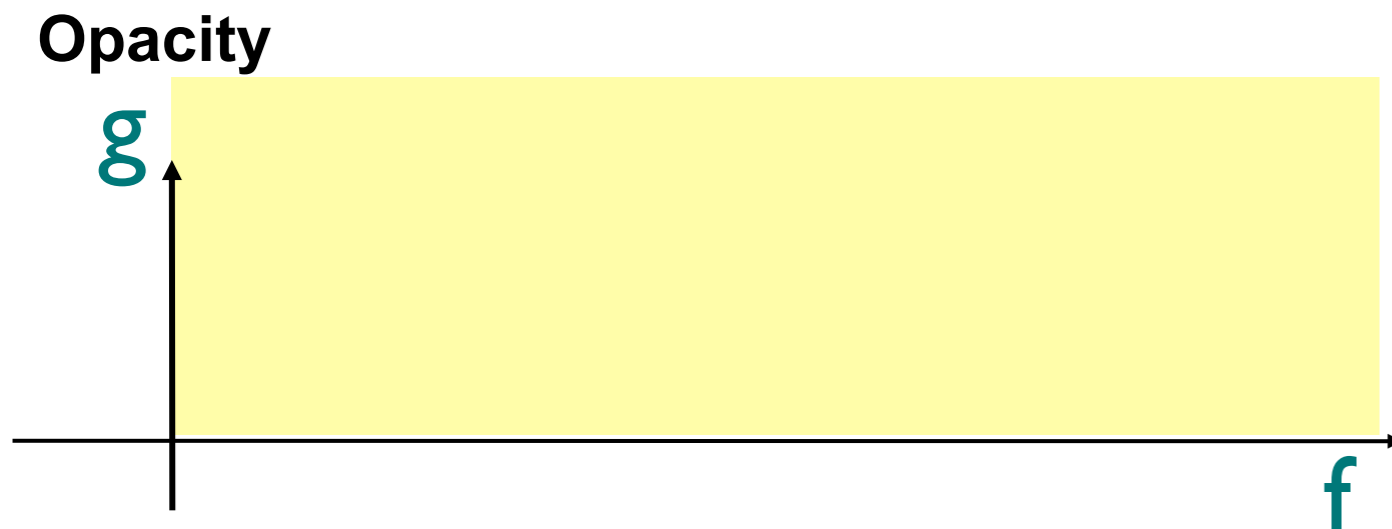


# Volume Rendering

- Map data value  $f$  to optical properties using a transfer function  $g(f(x))$

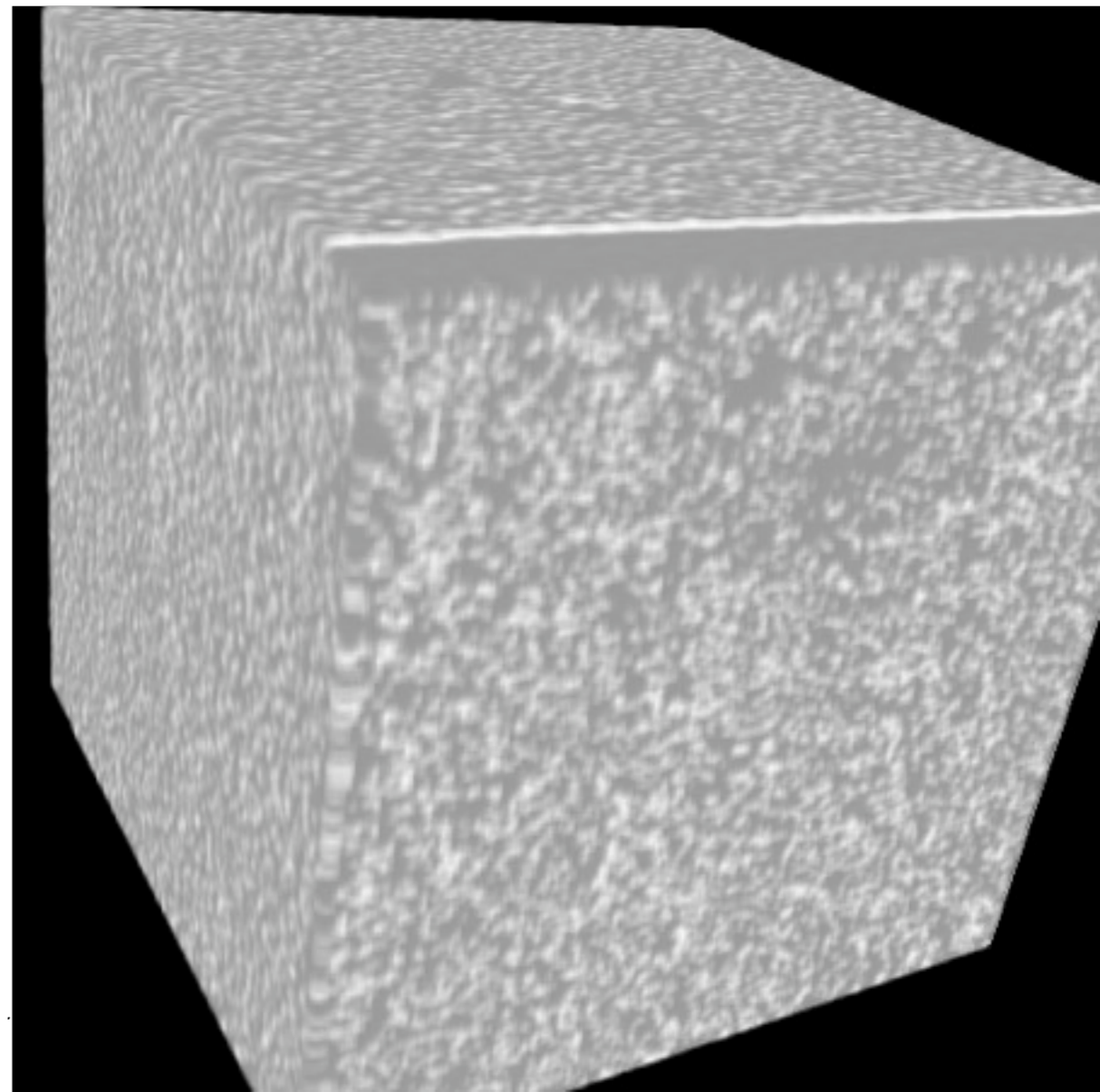
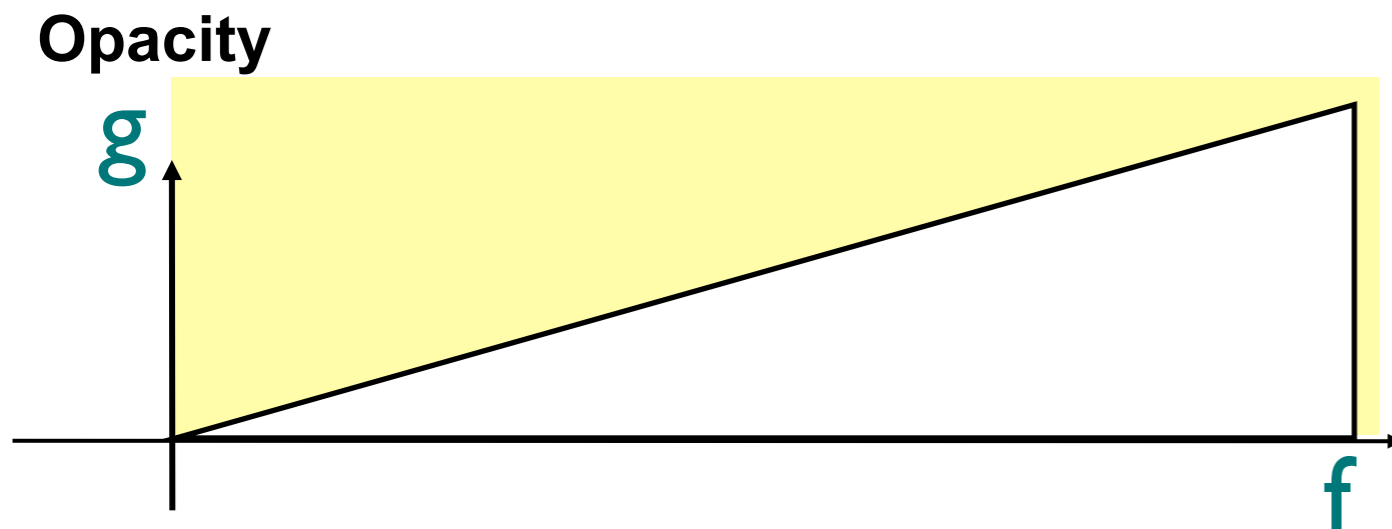
# Volume Rendering

- Map data value  $f$  to optical properties using a transfer function  $g(f(x))$
- Then shading+compositing



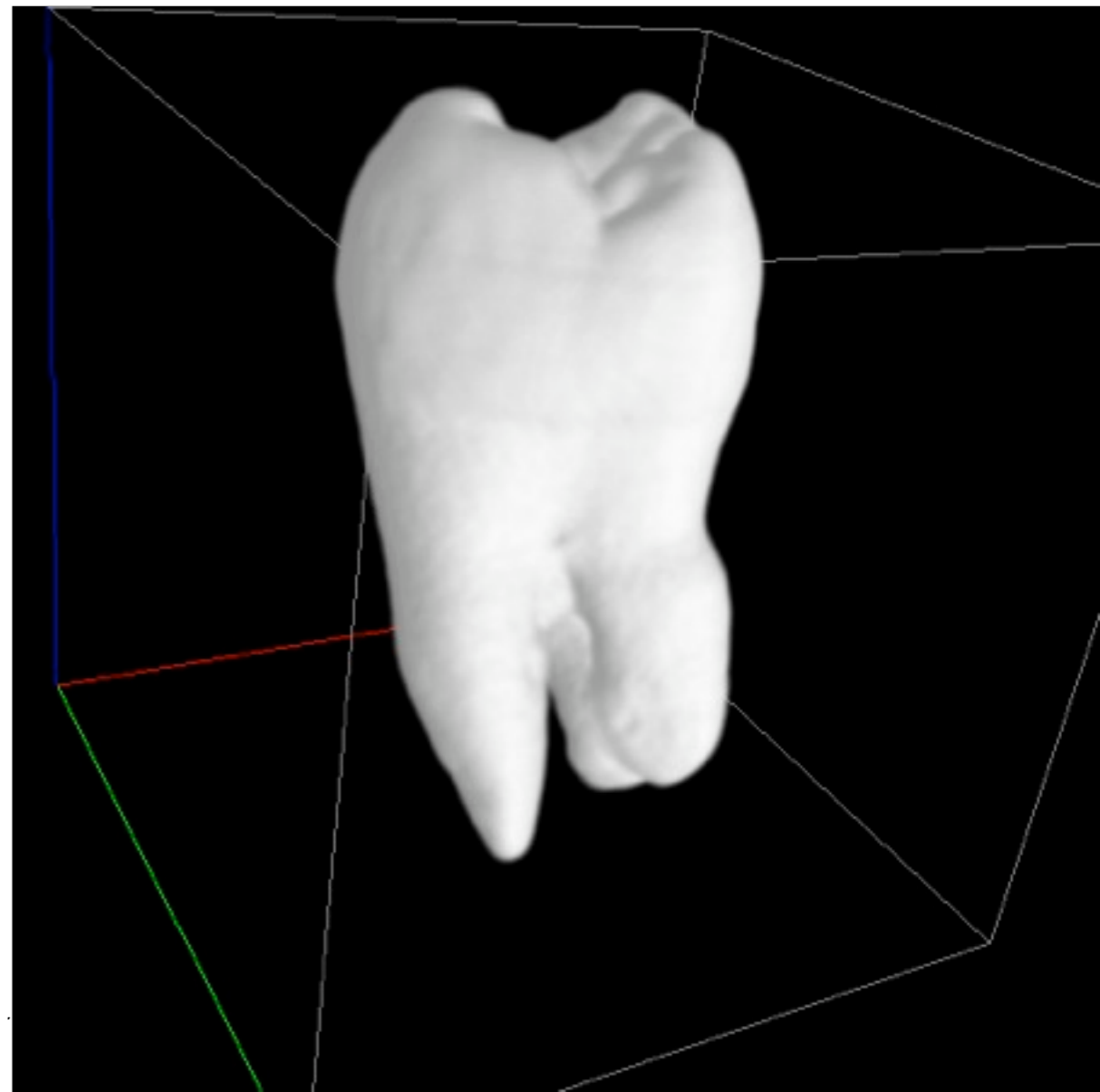
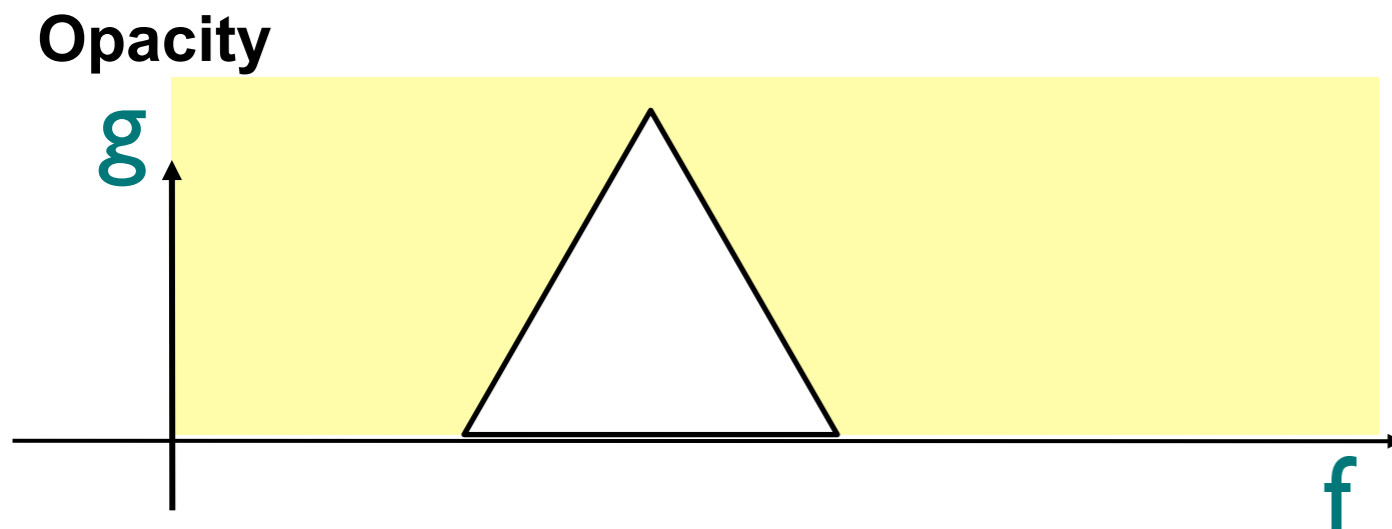
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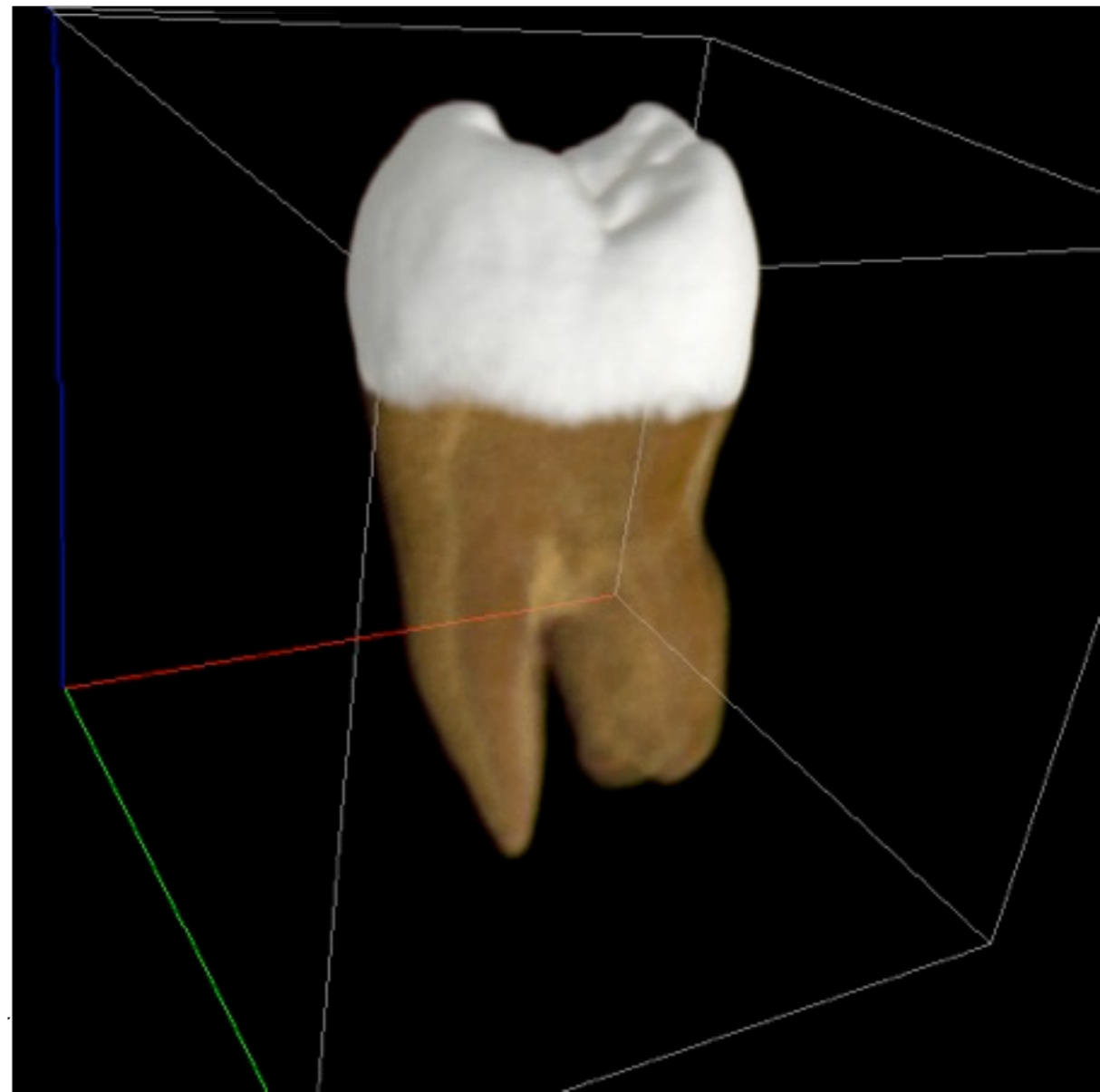
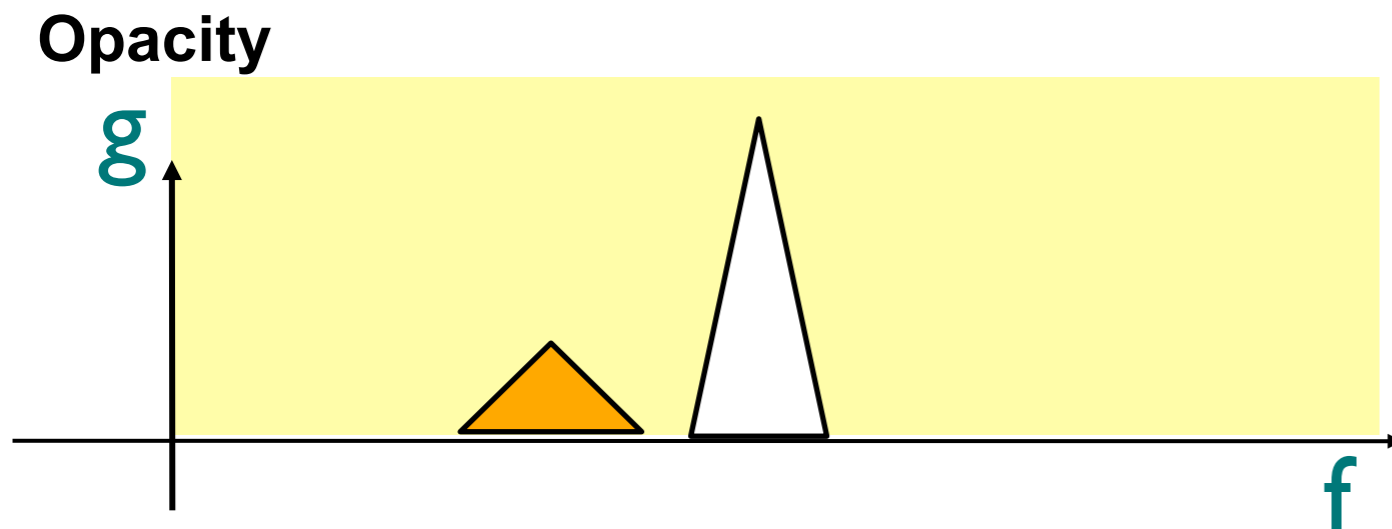
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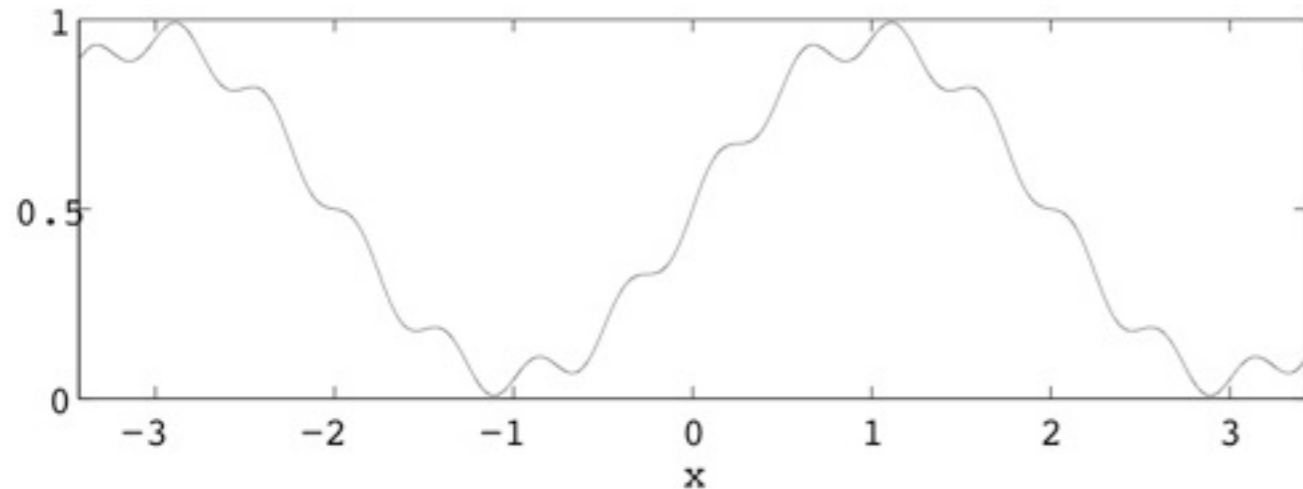




# Example of $g(f(x))$



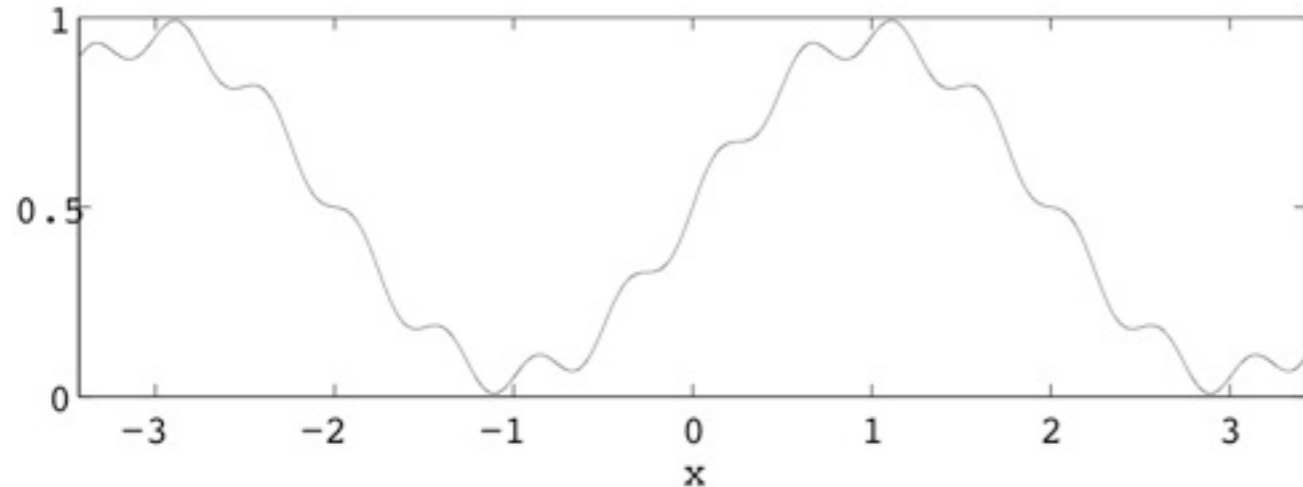
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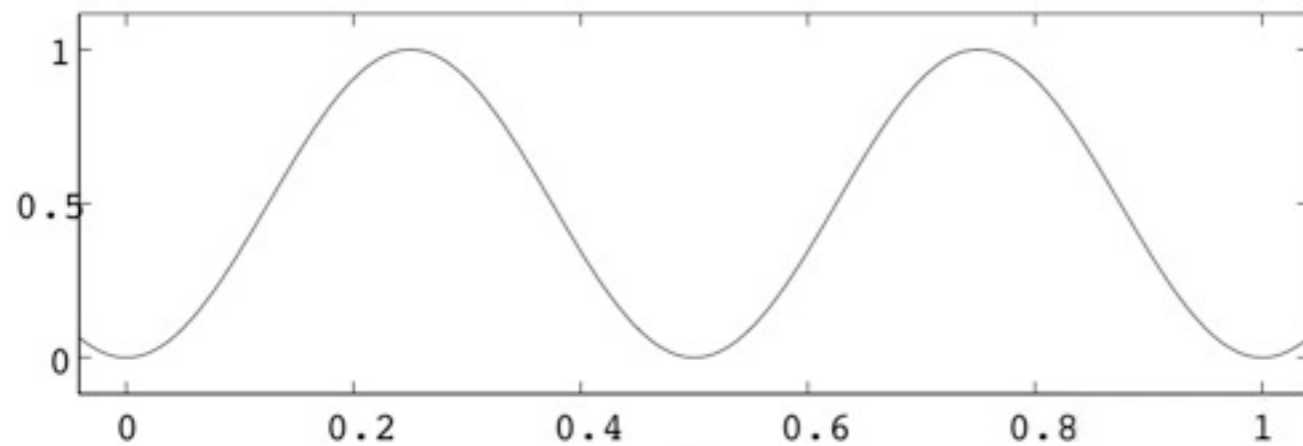
Original function  $f(x)$



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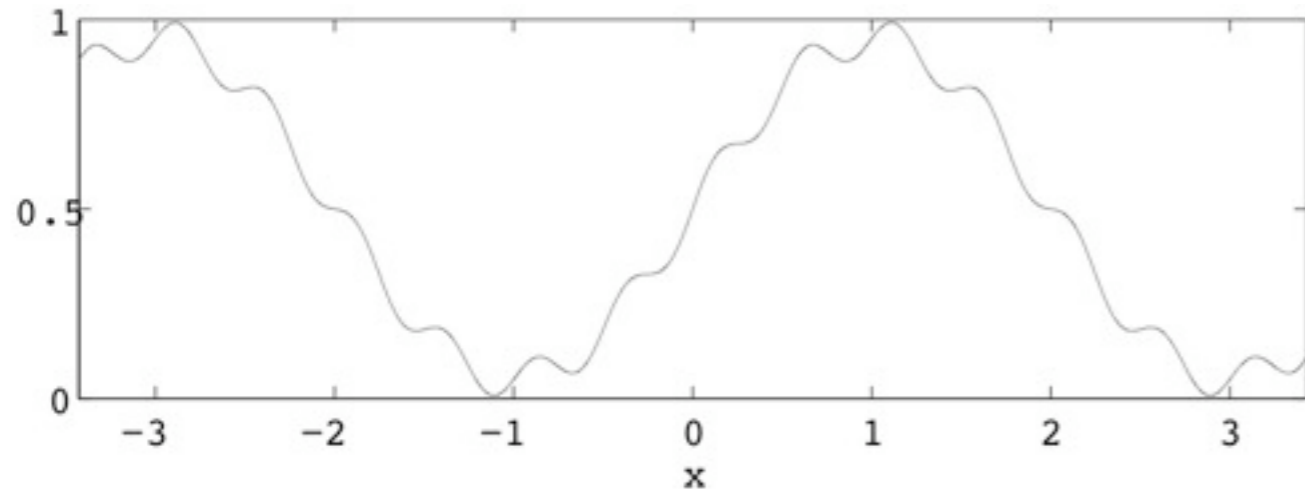
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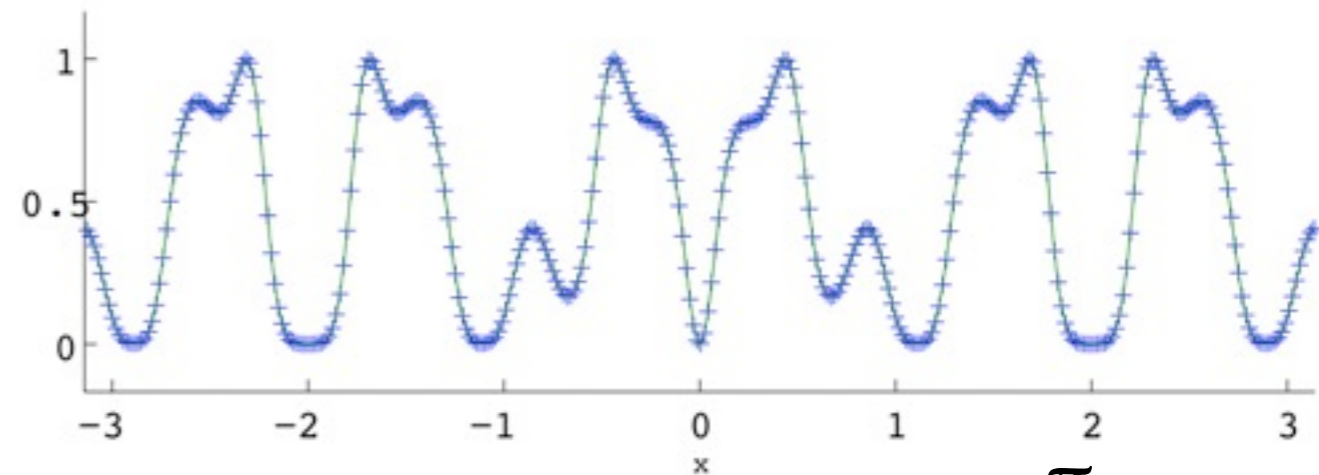
Transfer function  $g(y)$



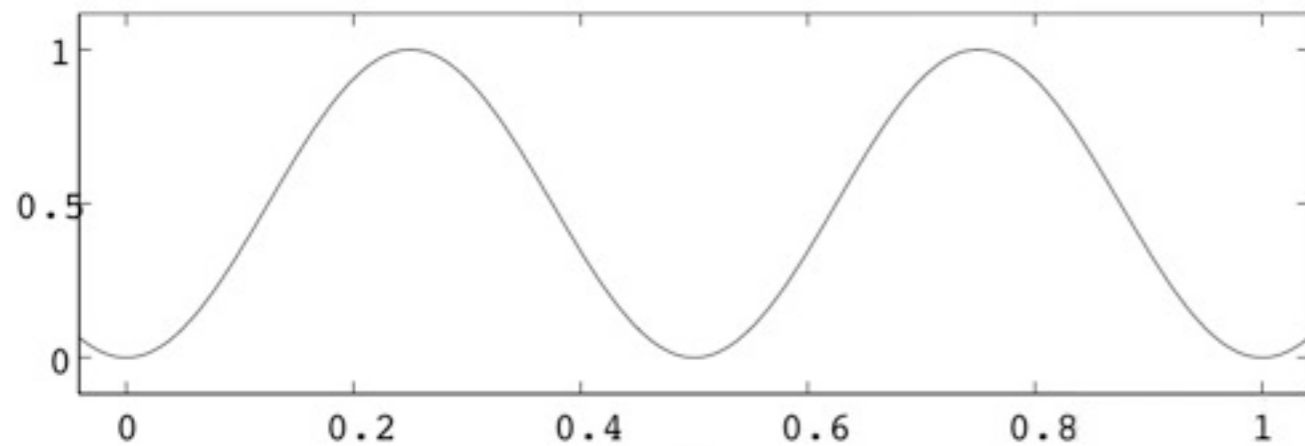
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Original function  $f(x)$



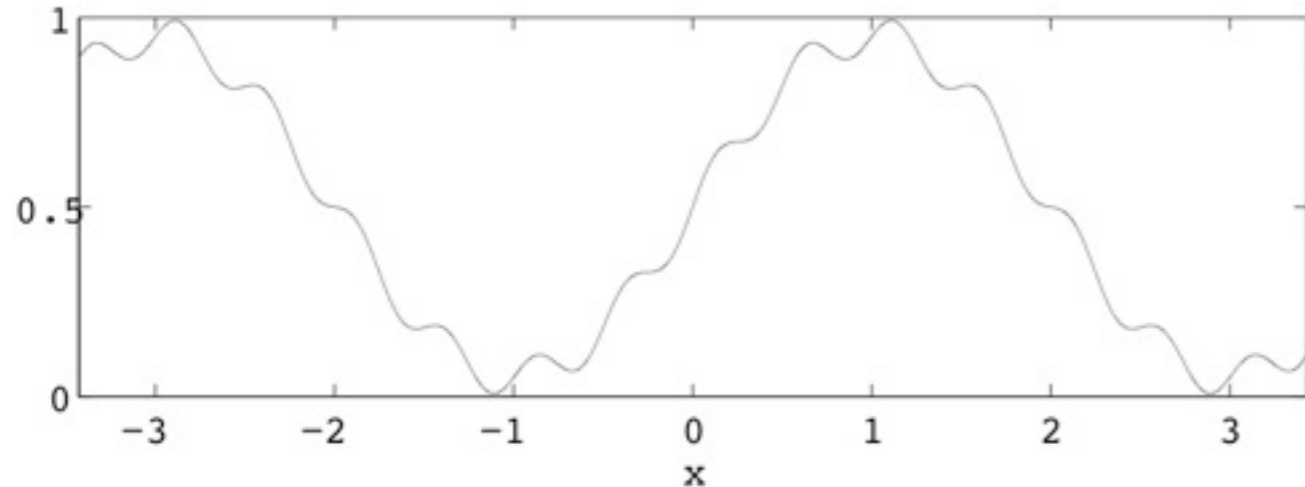
$g(f(x))$  sampled by  $\frac{\pi}{2} \nu_f \nu_g$



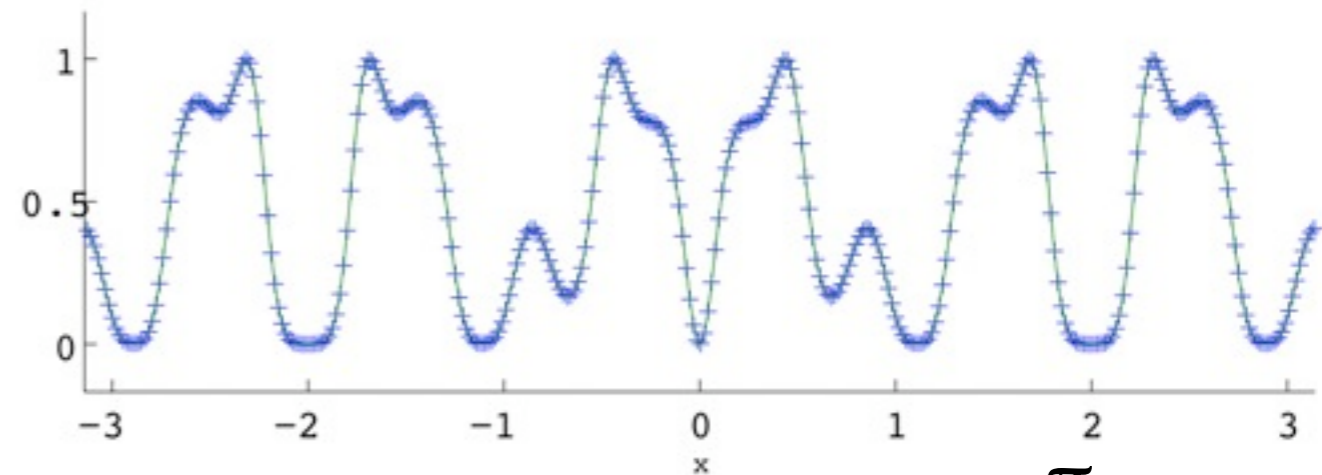
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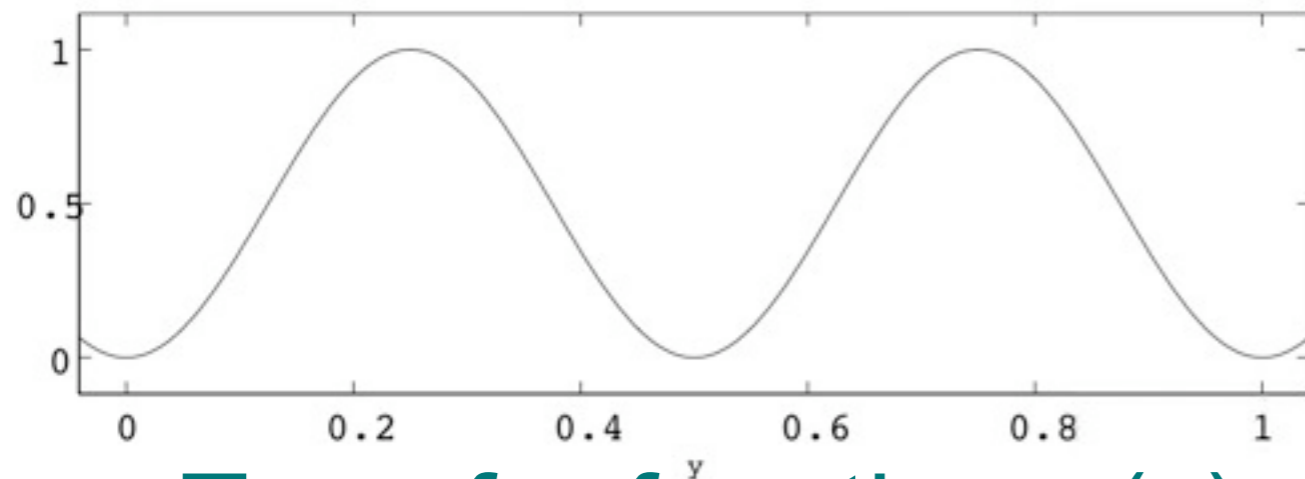
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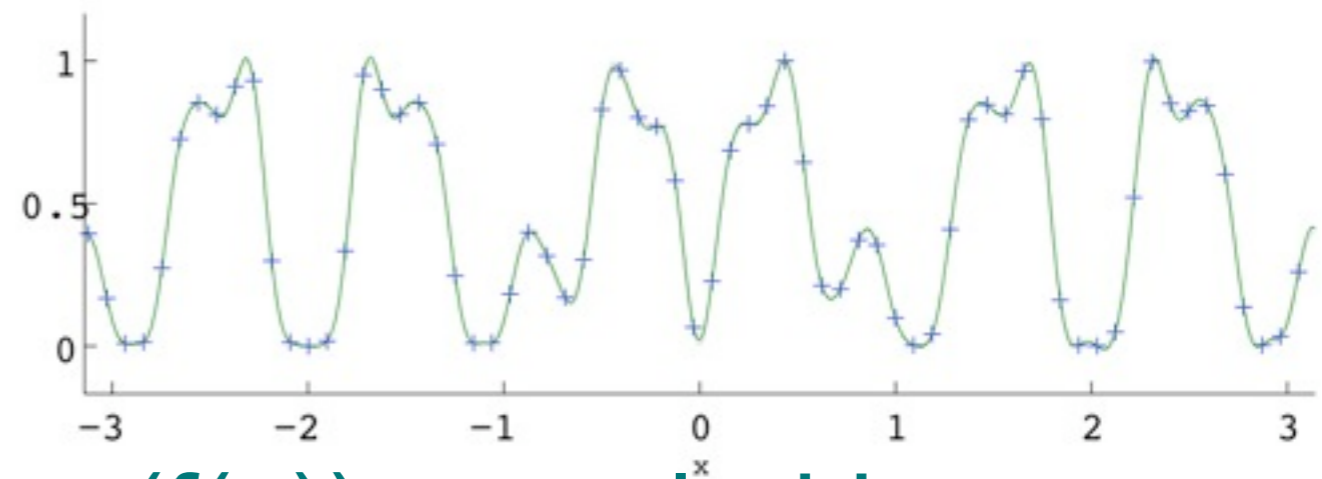
Original function  $f(x)$



$g(f(x))$  sampled by  $\frac{\pi}{2} \nu_f \nu_g$



Transfer function  $g(y)$



$g(f(x))$  sampled by  $\max |f'| \nu_g$



# Composition in Frequency Domain

$$g(y) = \frac{1}{\sqrt{2\pi}} \int_{\mathbb{R}} G(l) e^{il \cdot y} dl$$



# Composition in Frequency Domain

$$h(x) = g(f(x)) = \frac{1}{\sqrt{2\pi}} \int_{\mathbb{R}} G(l) e^{il \cdot f(x)} dl$$



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$H(k)$

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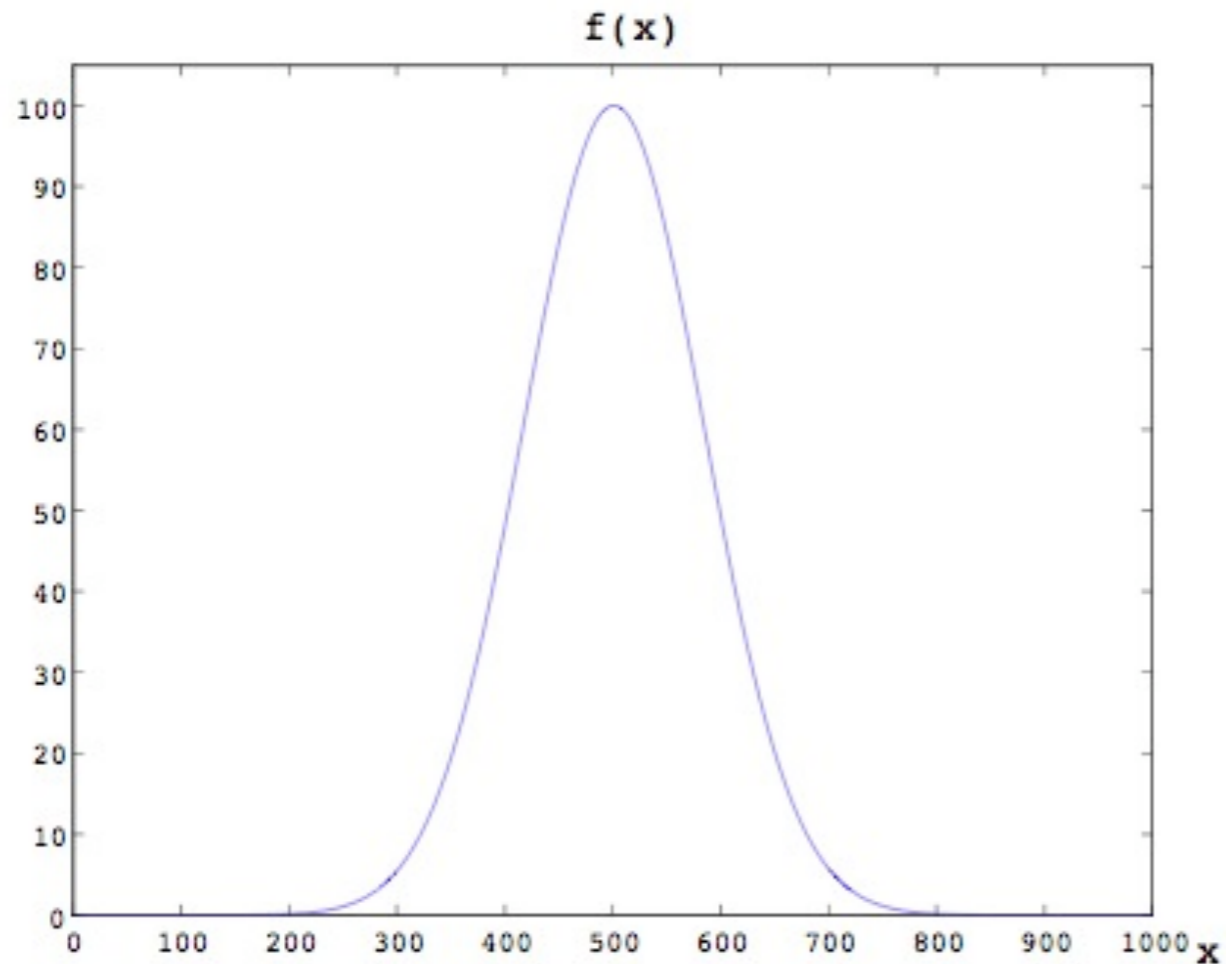
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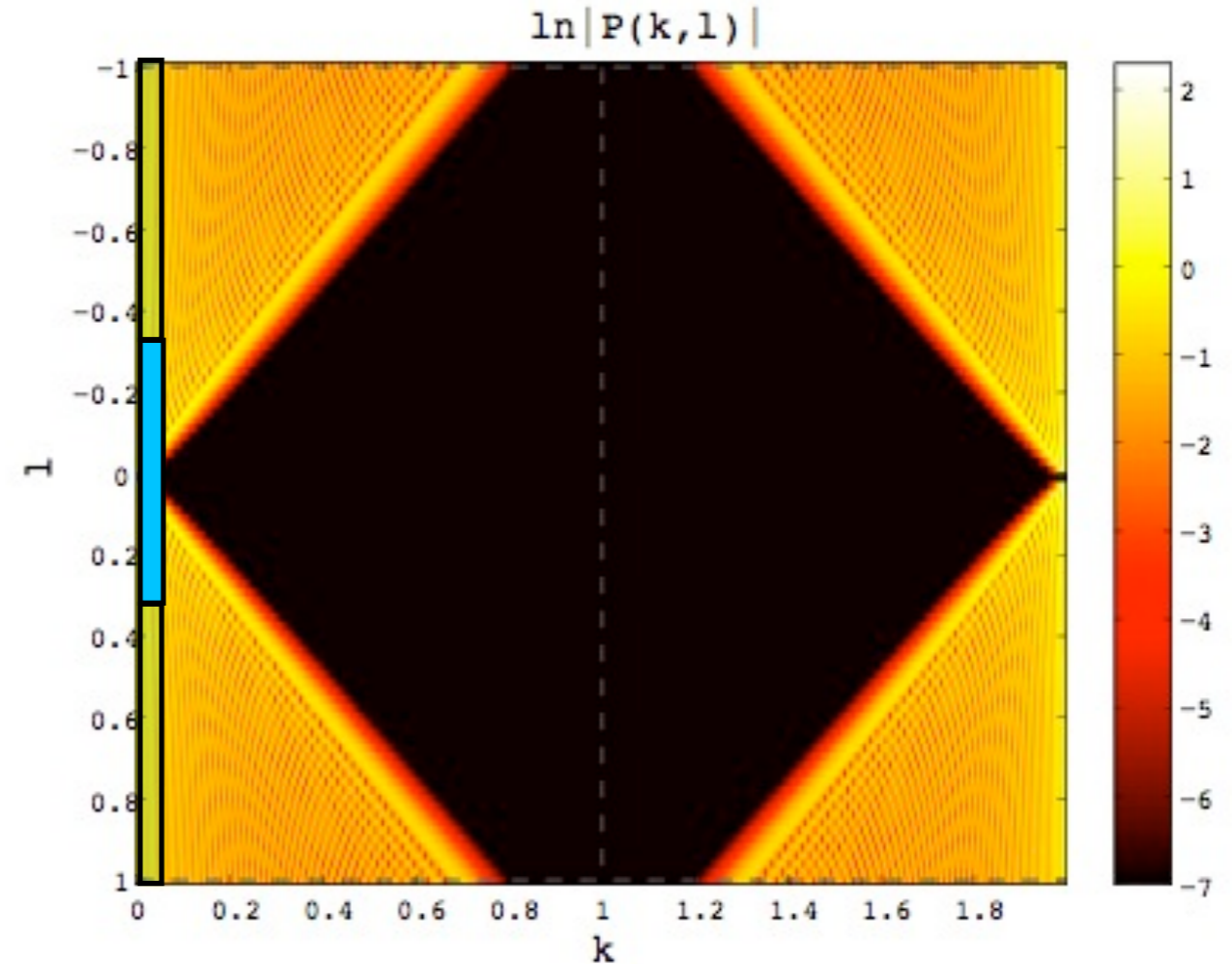
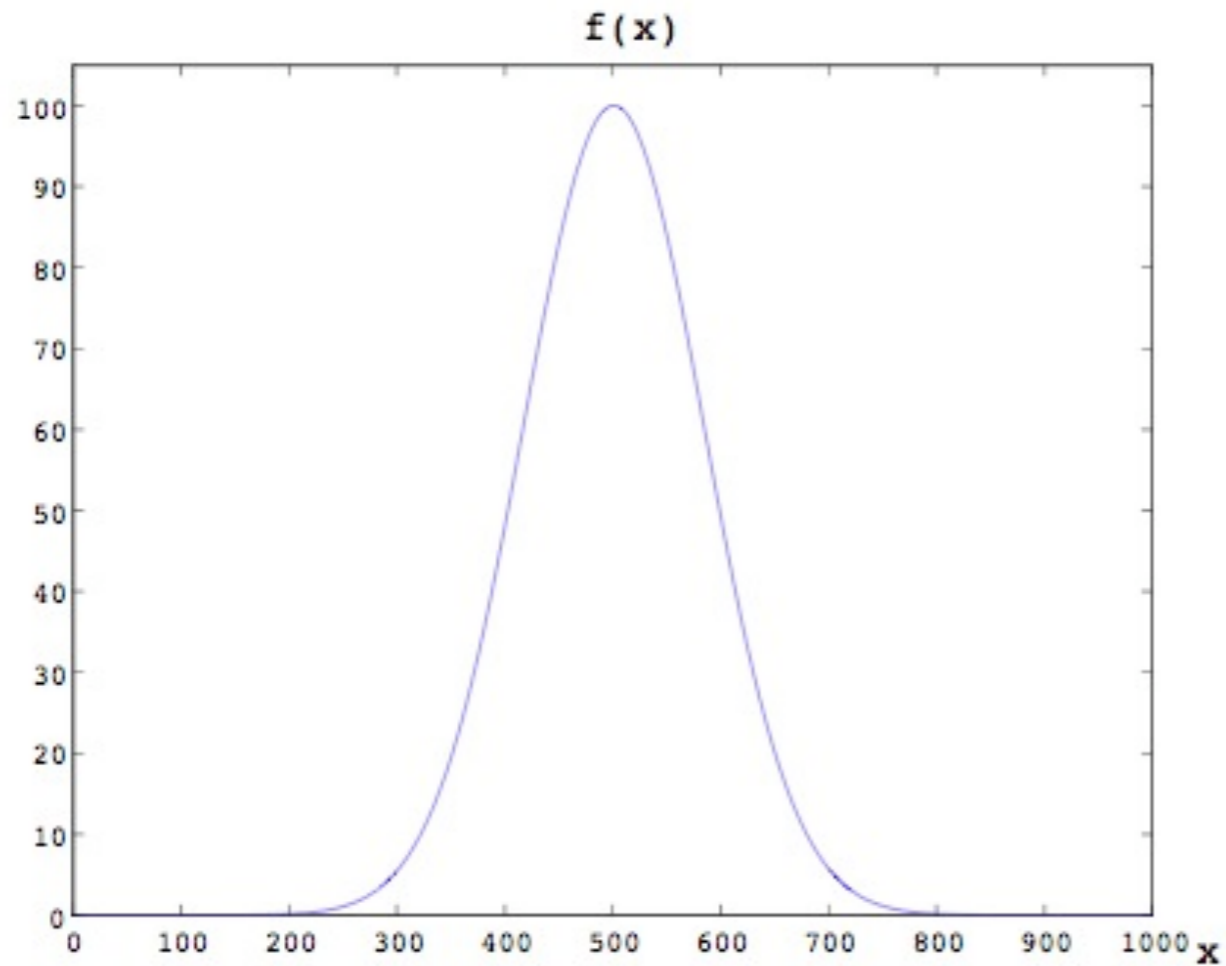
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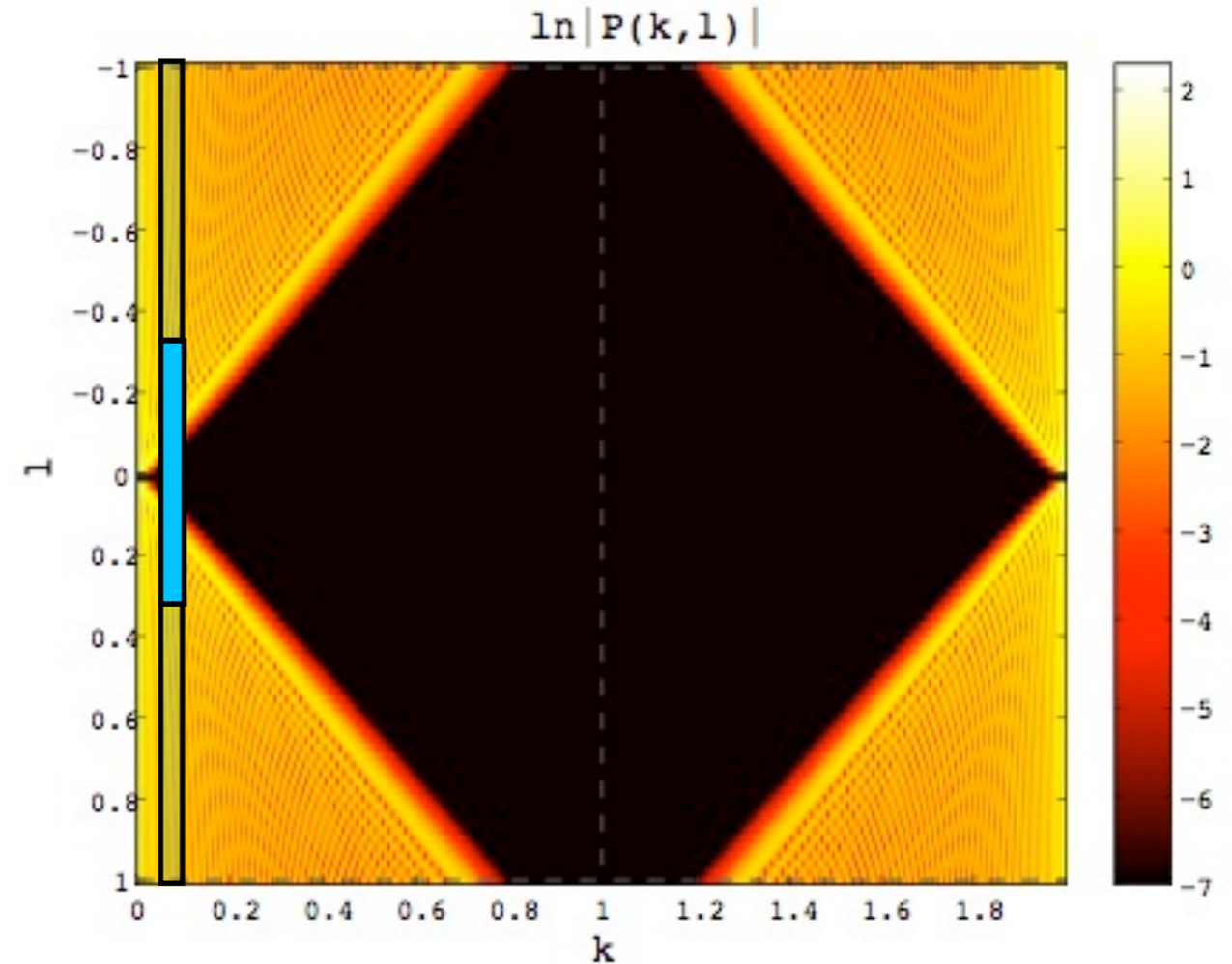
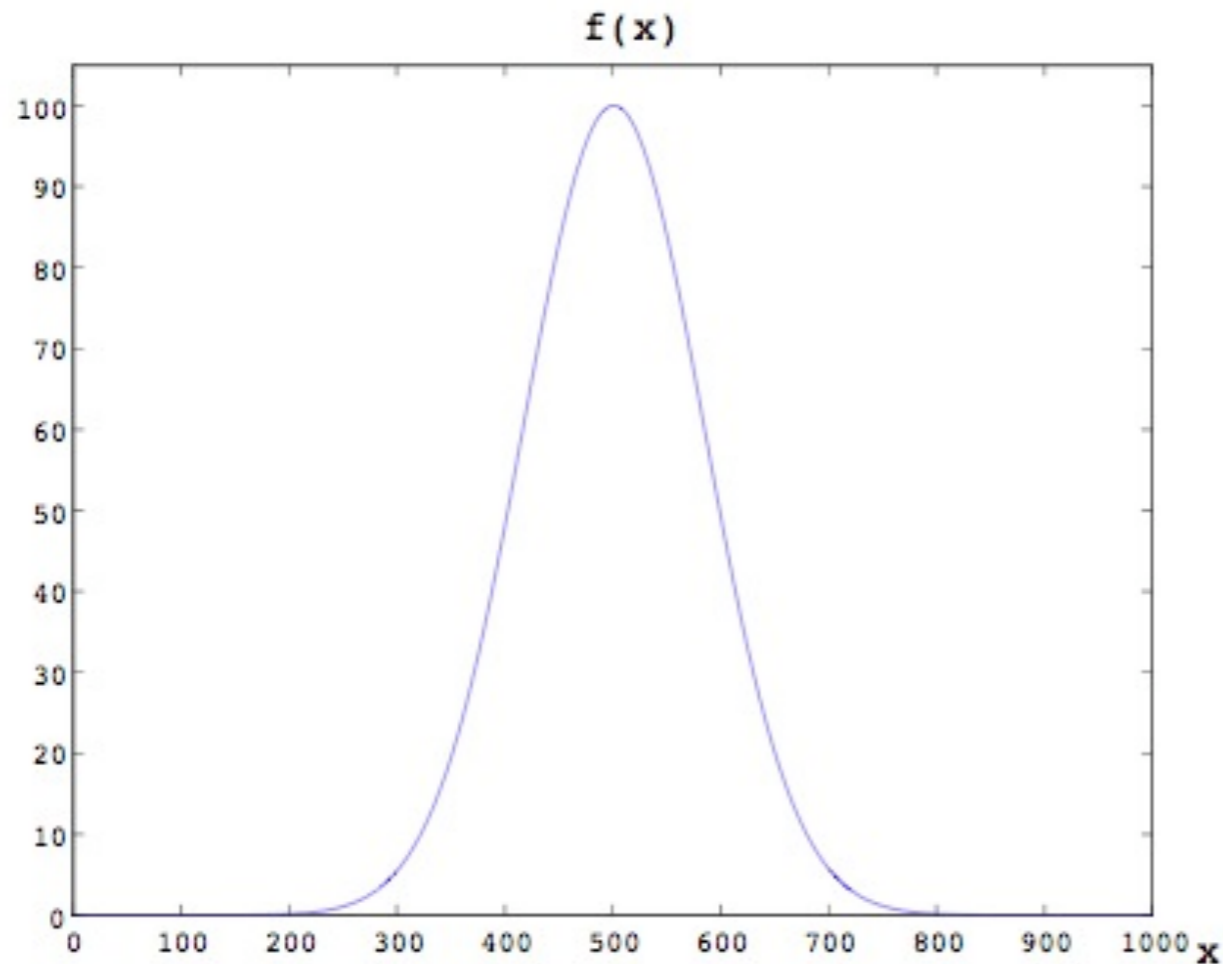
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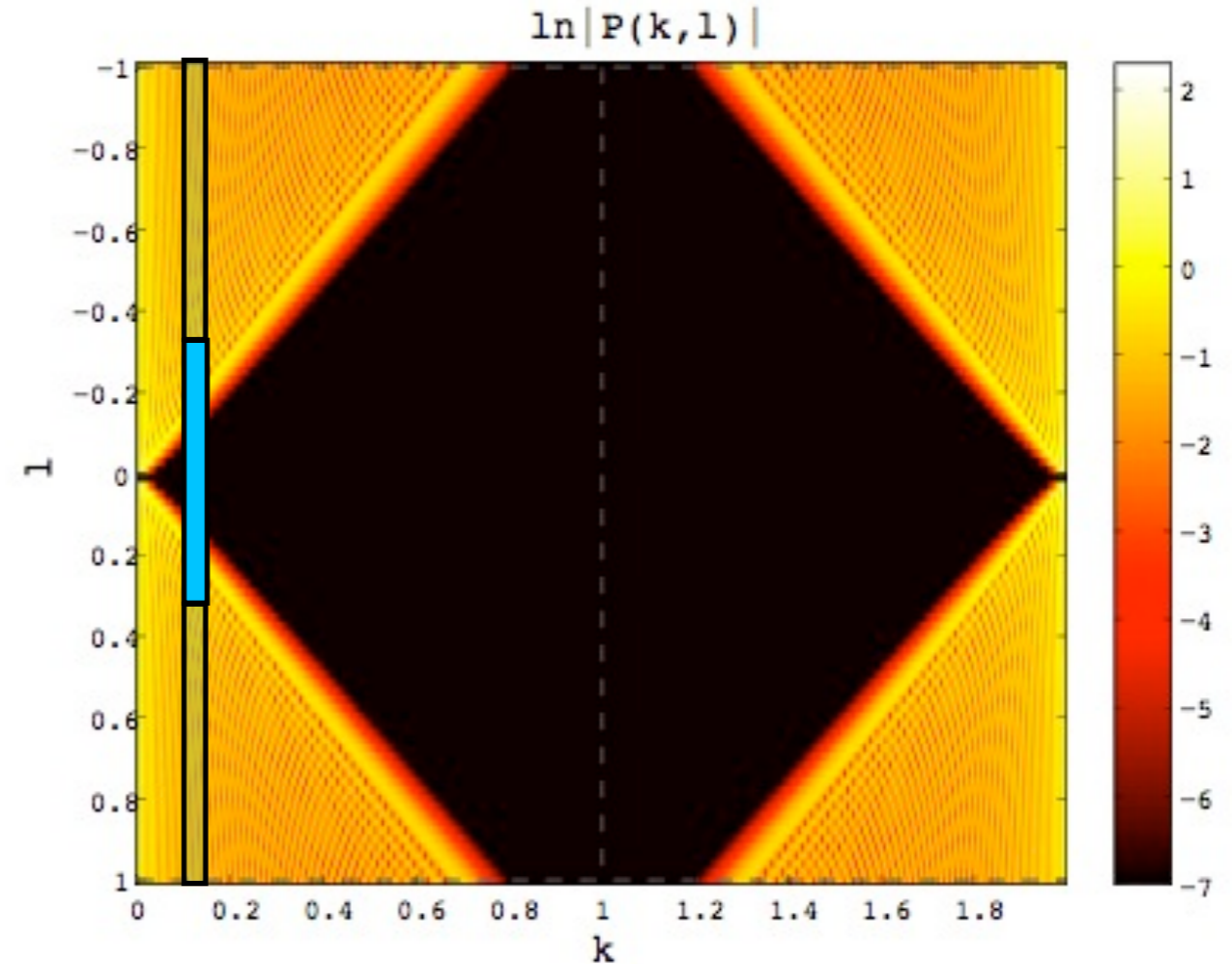
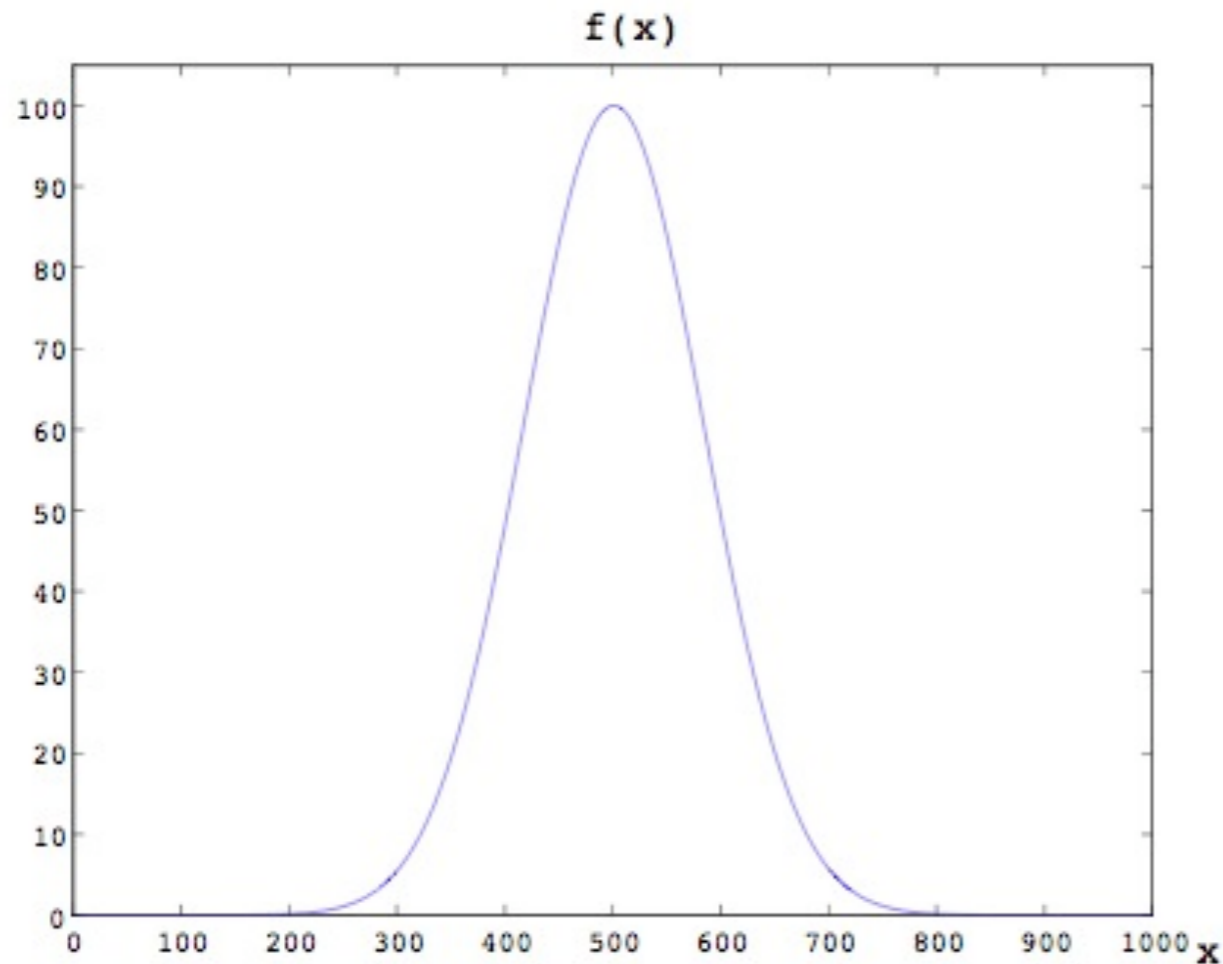
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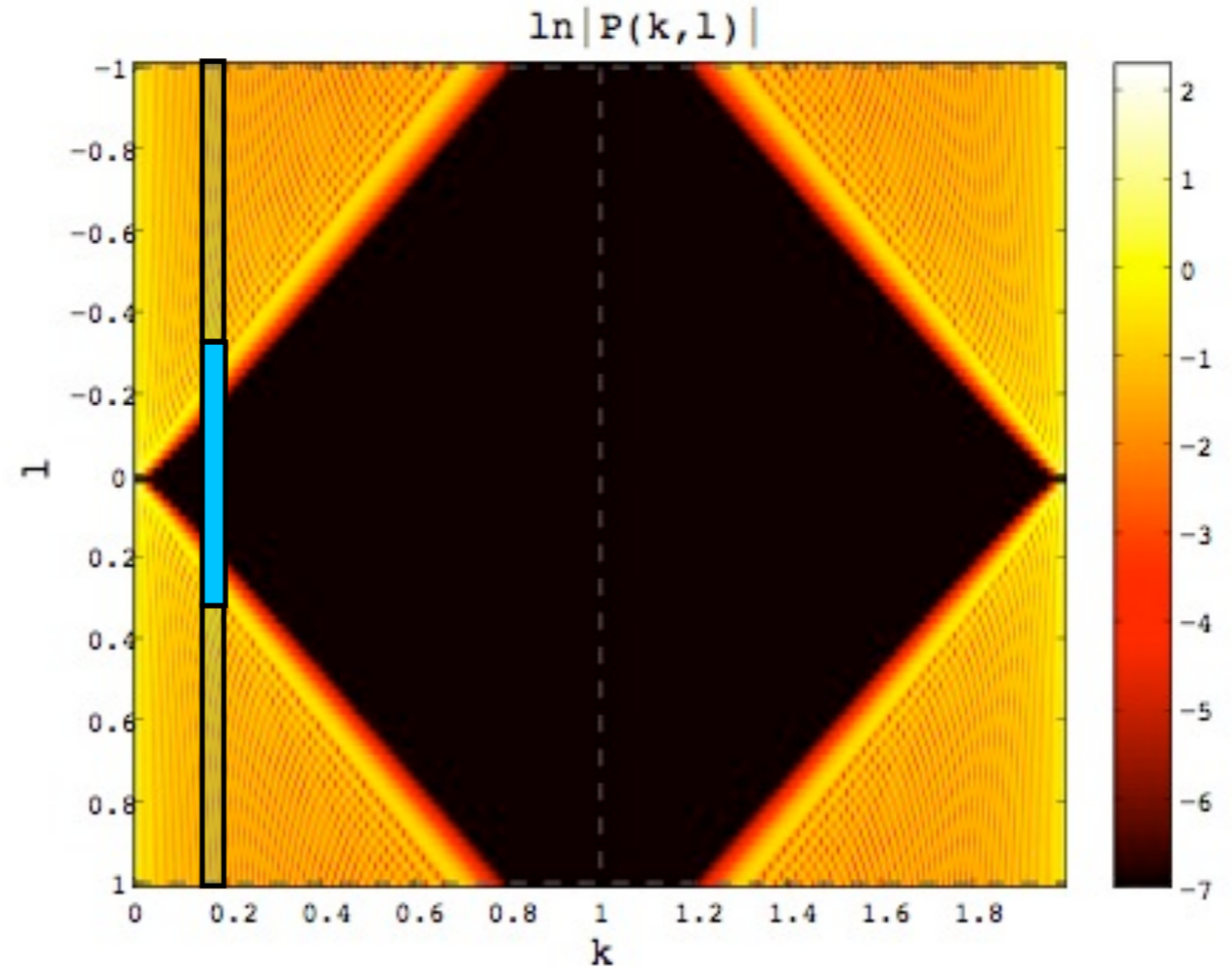
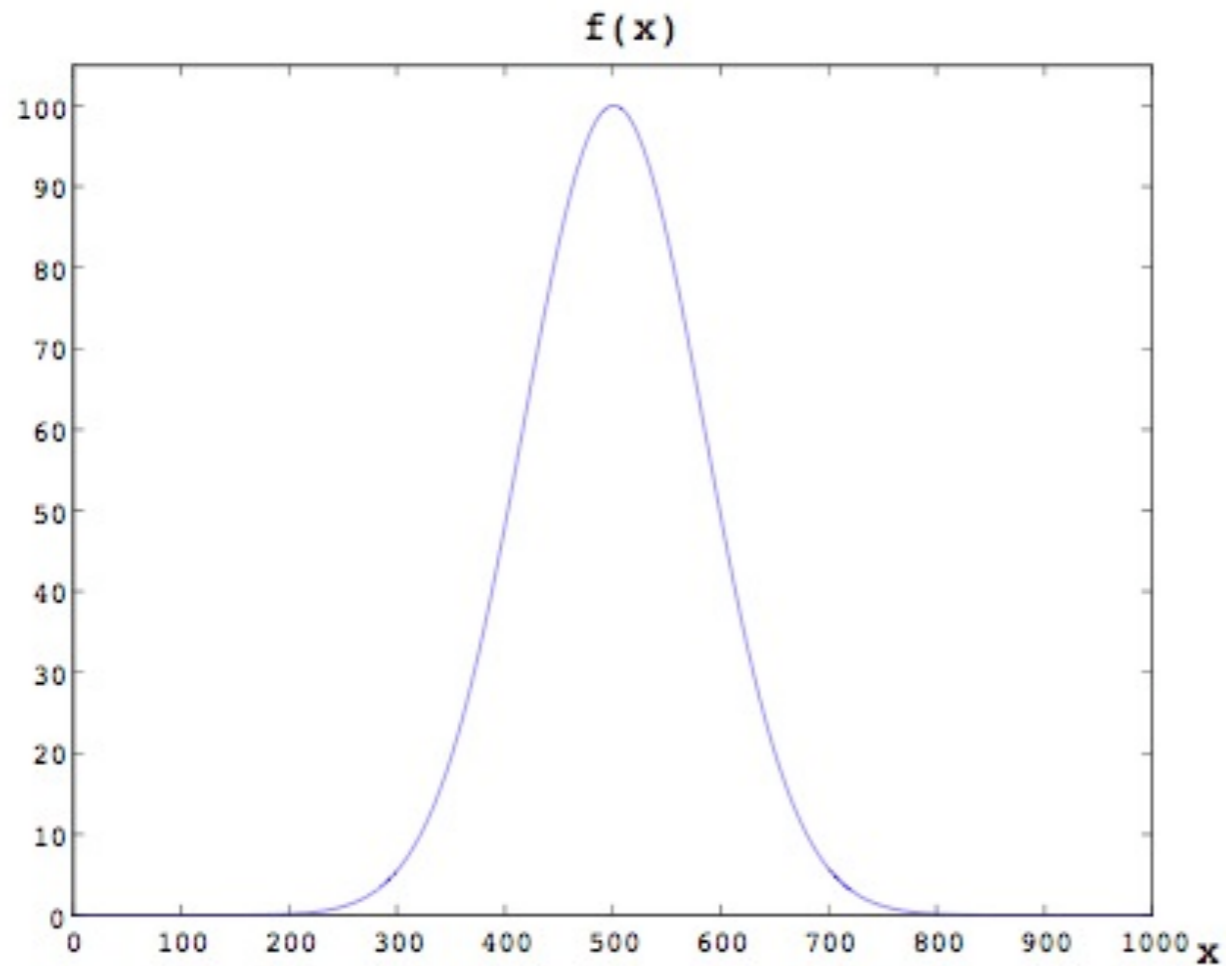
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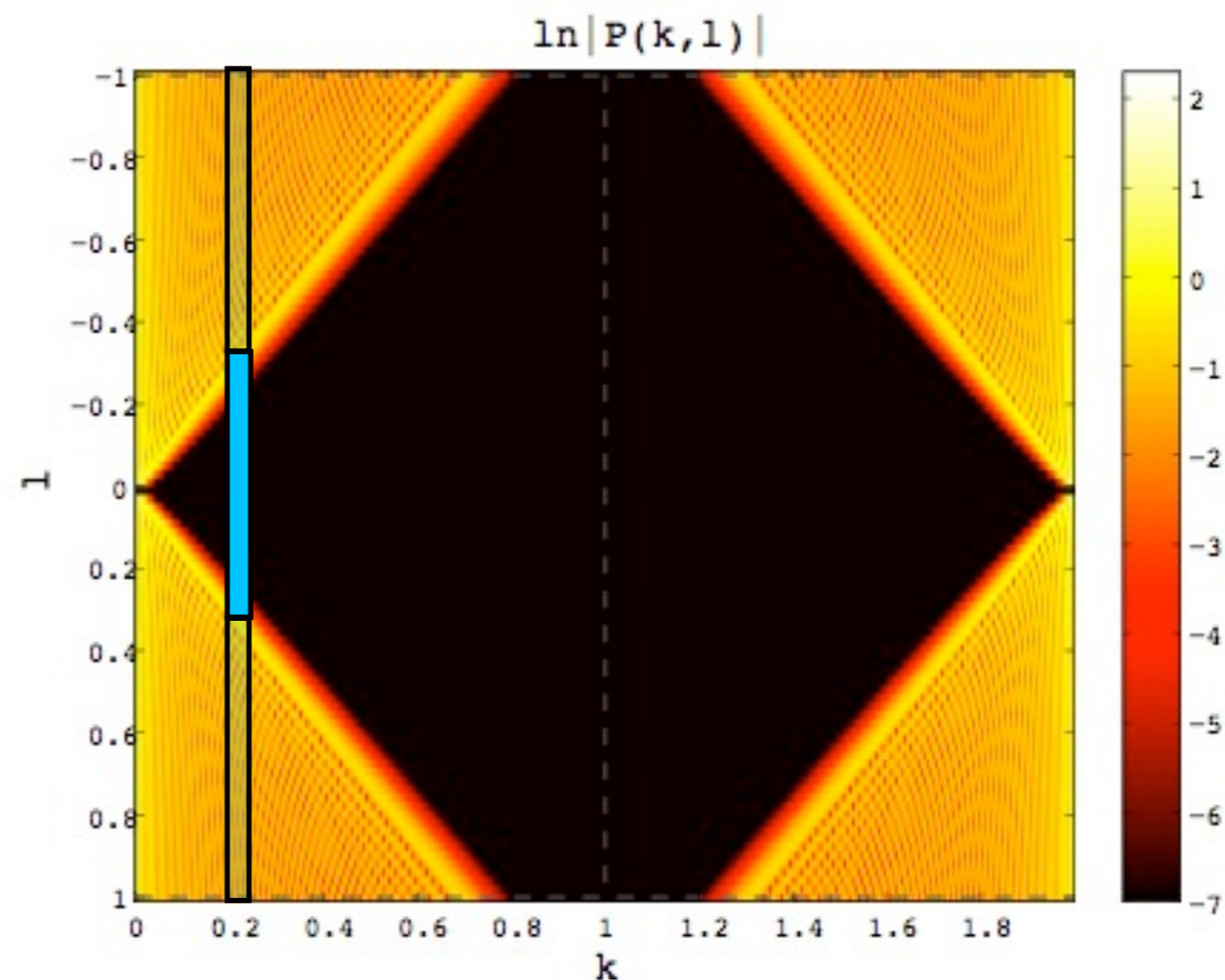
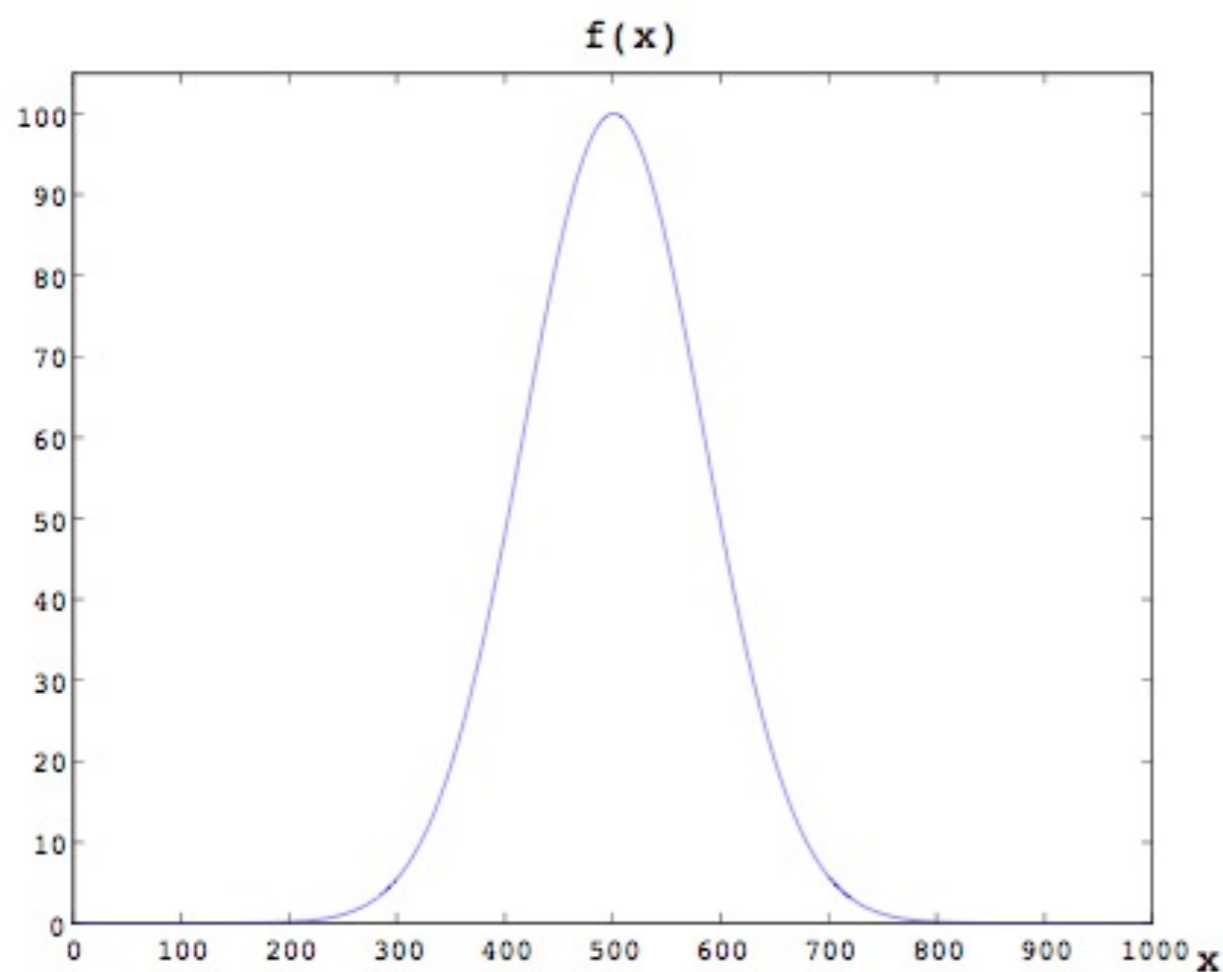
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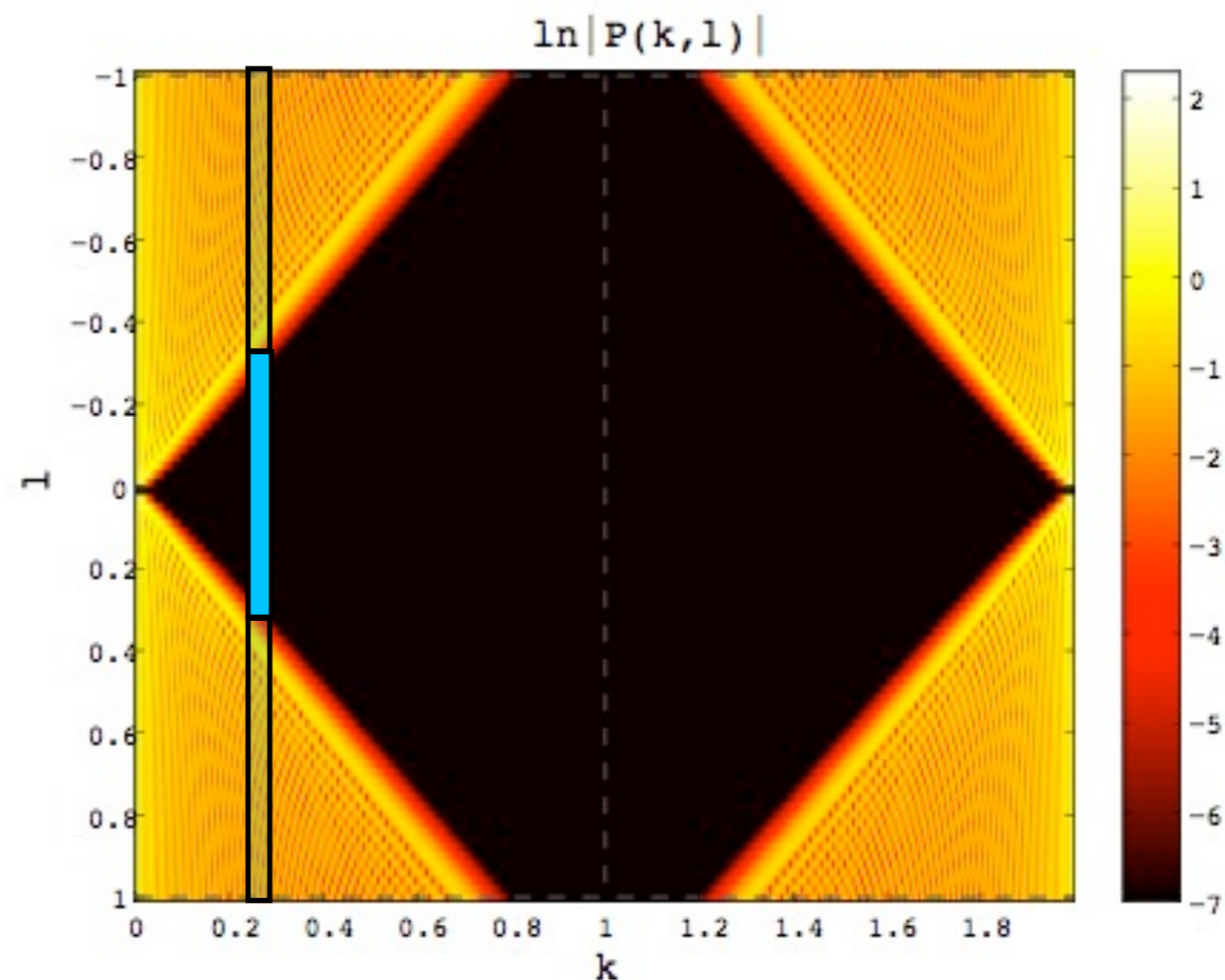
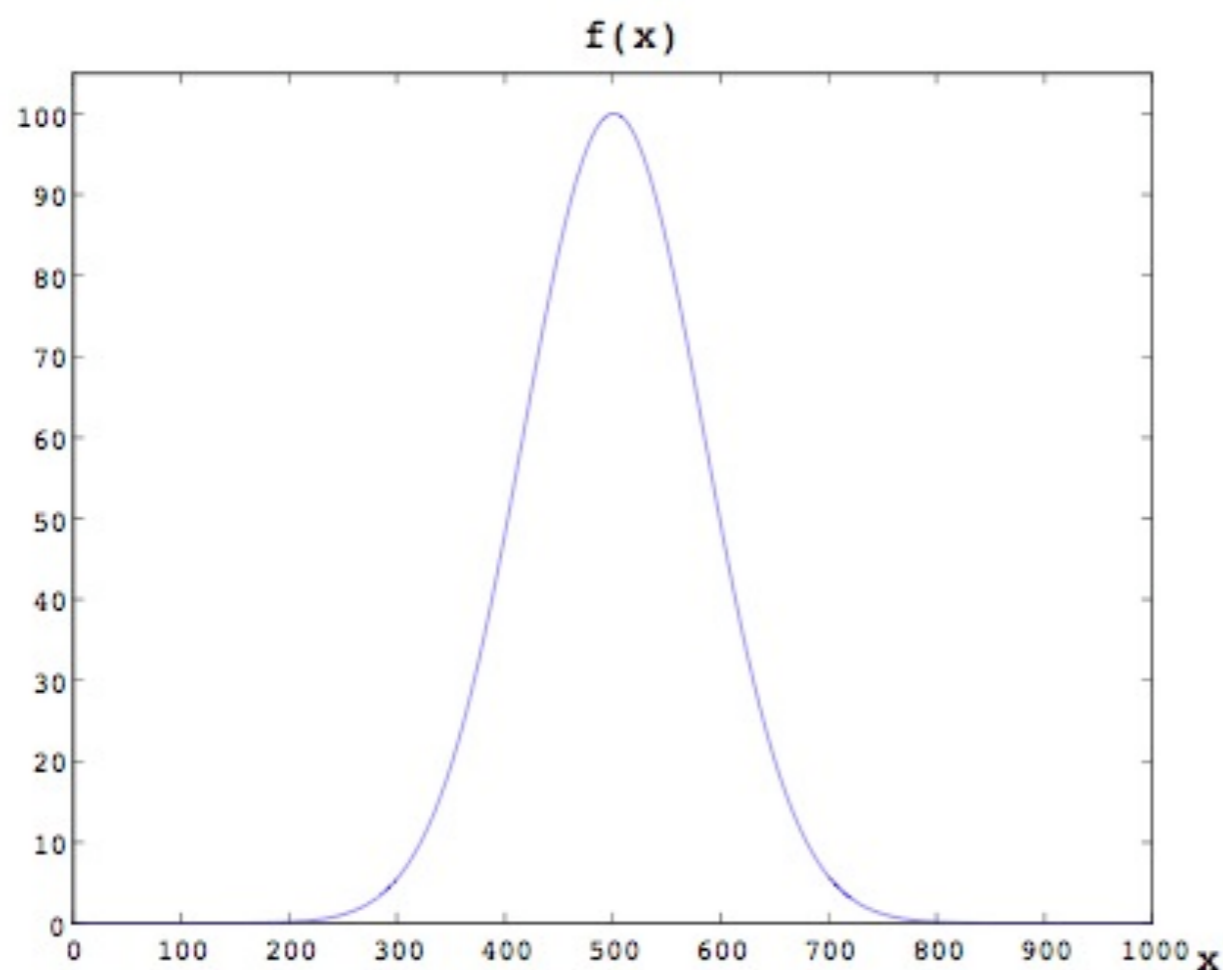
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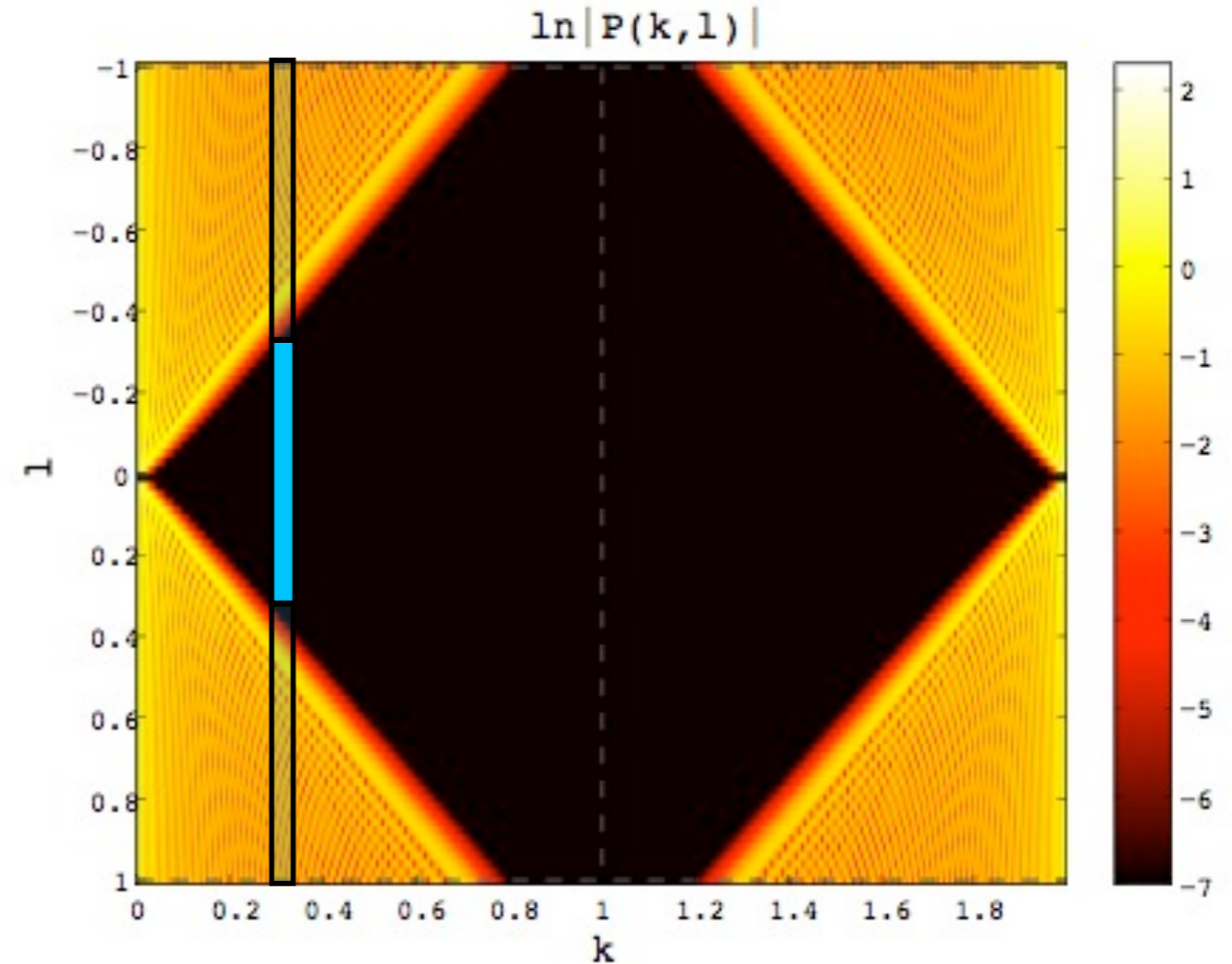
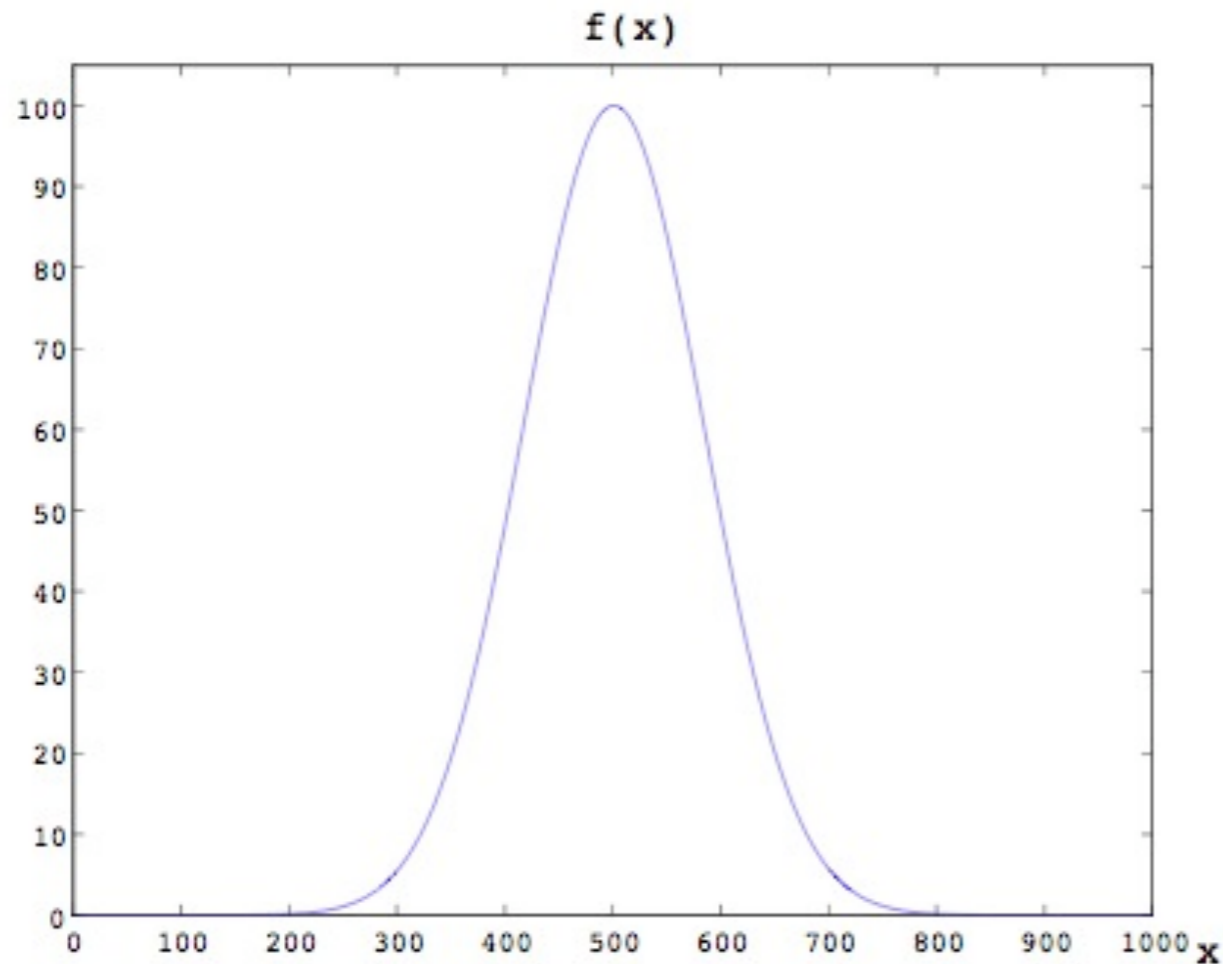
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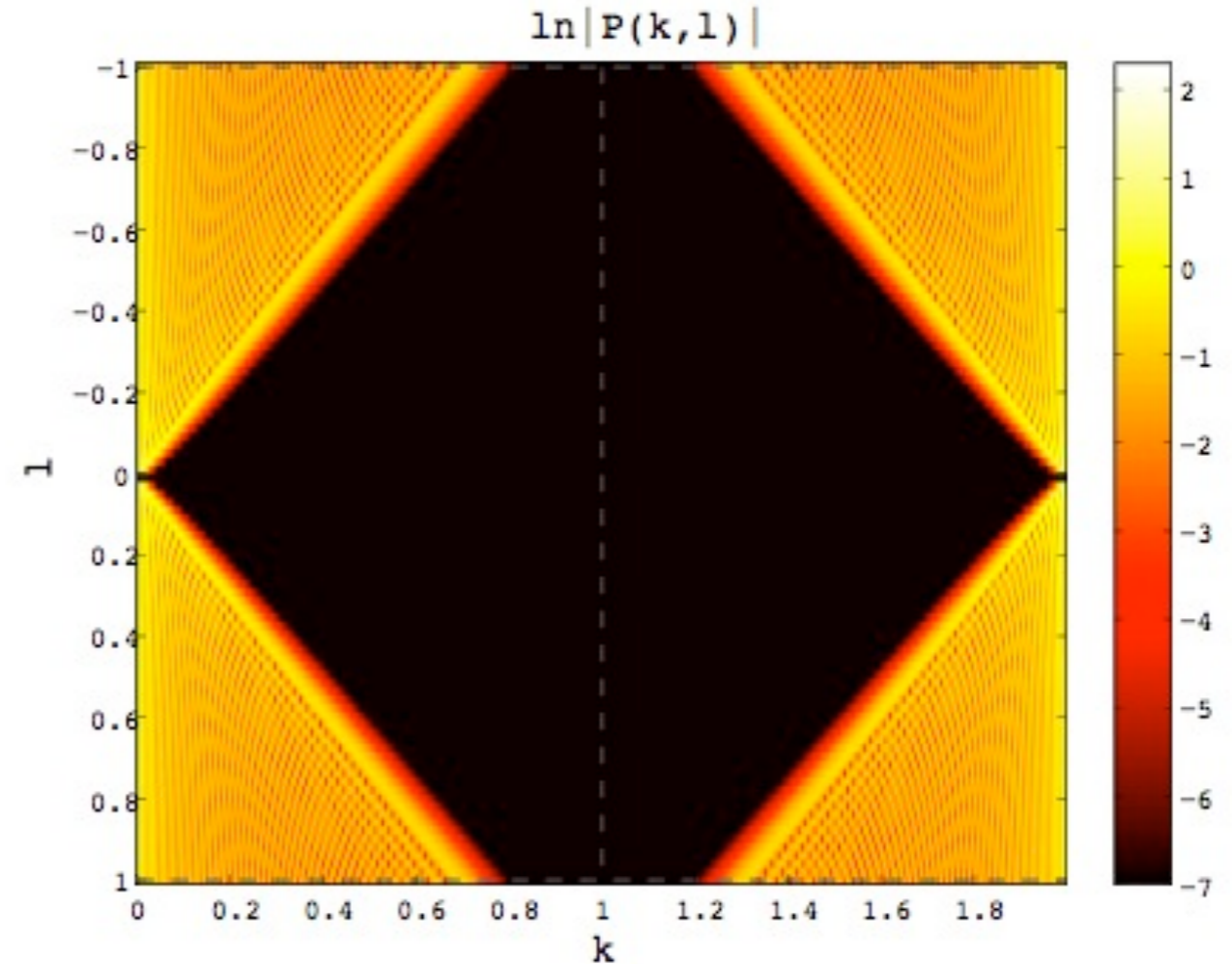
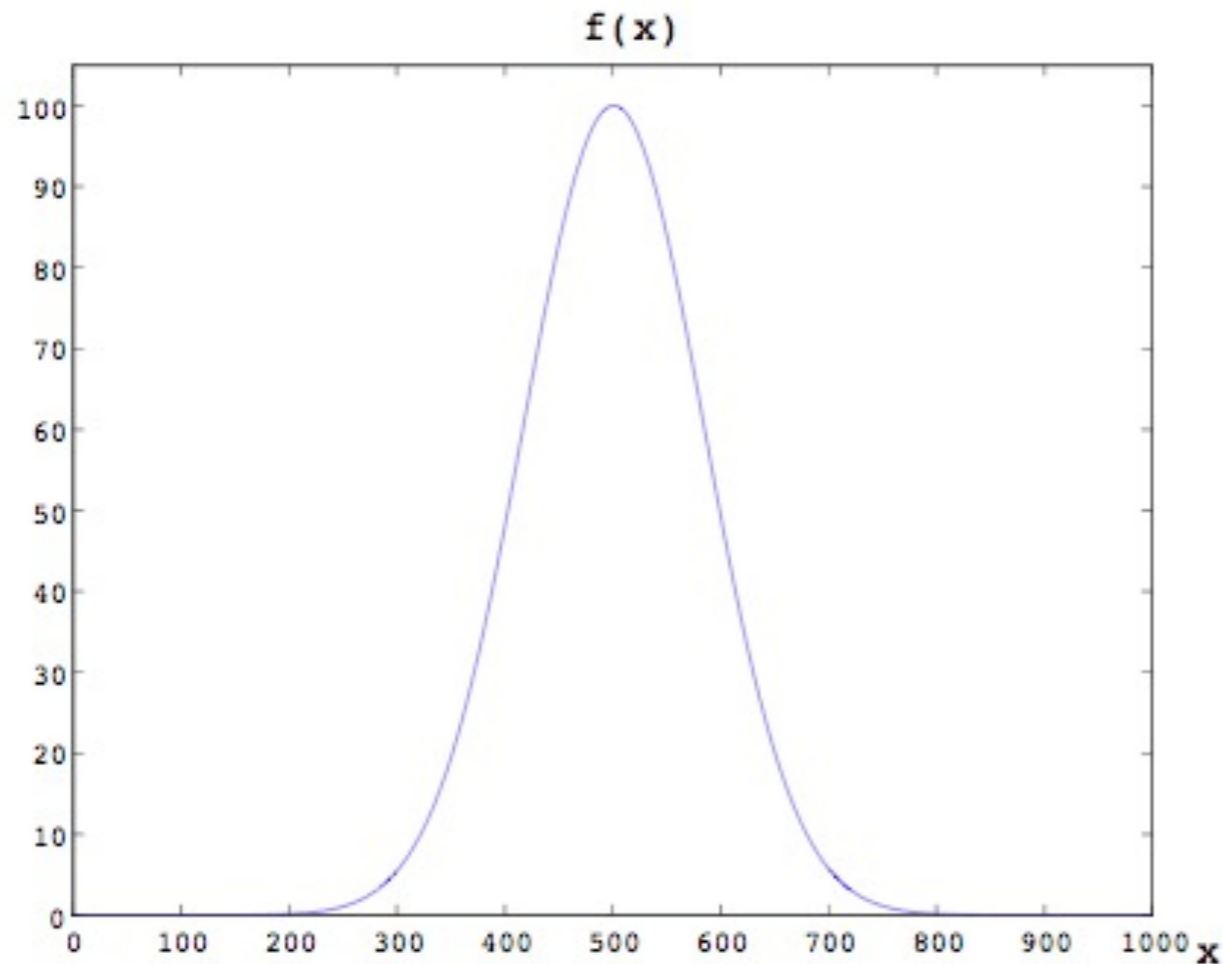
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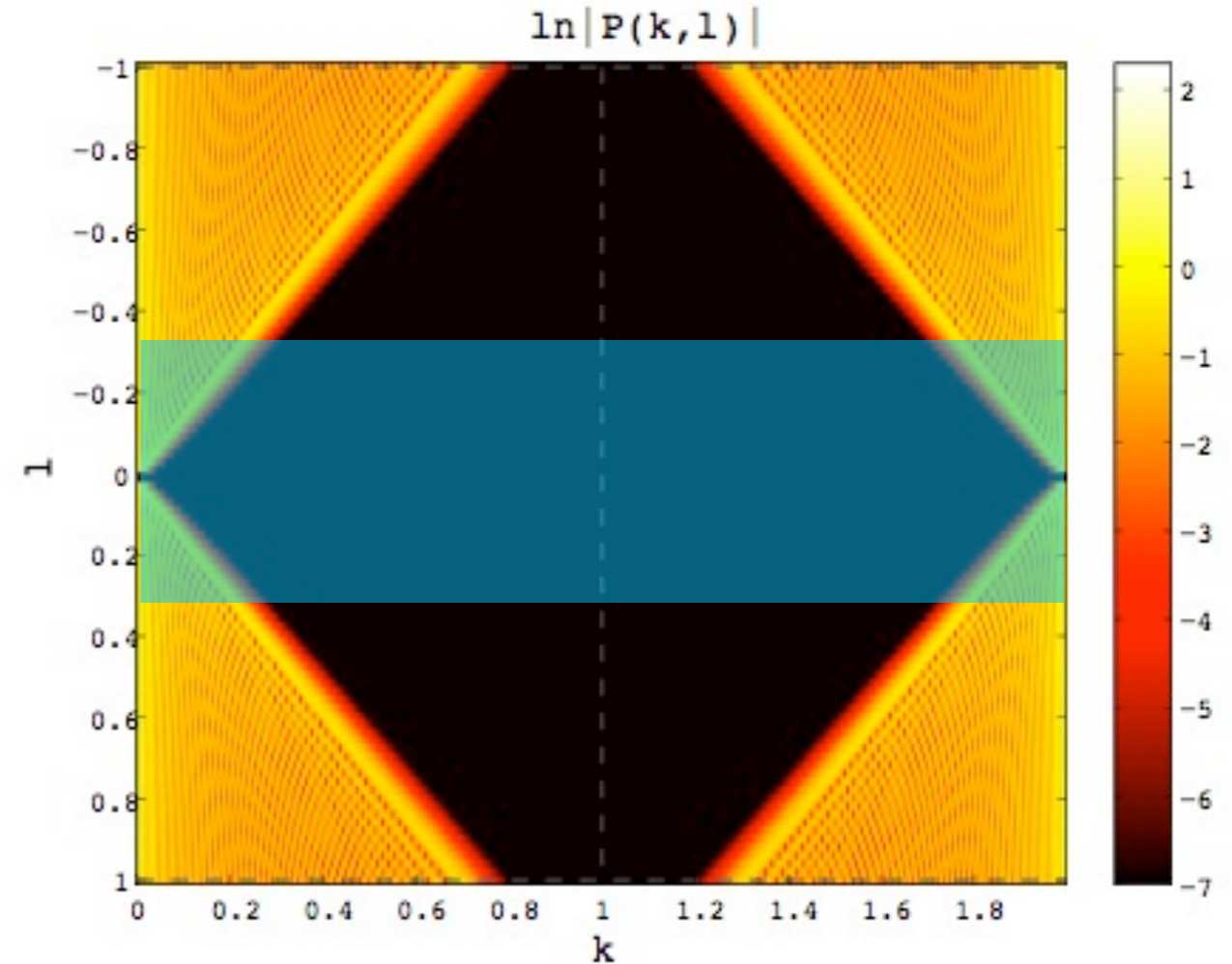
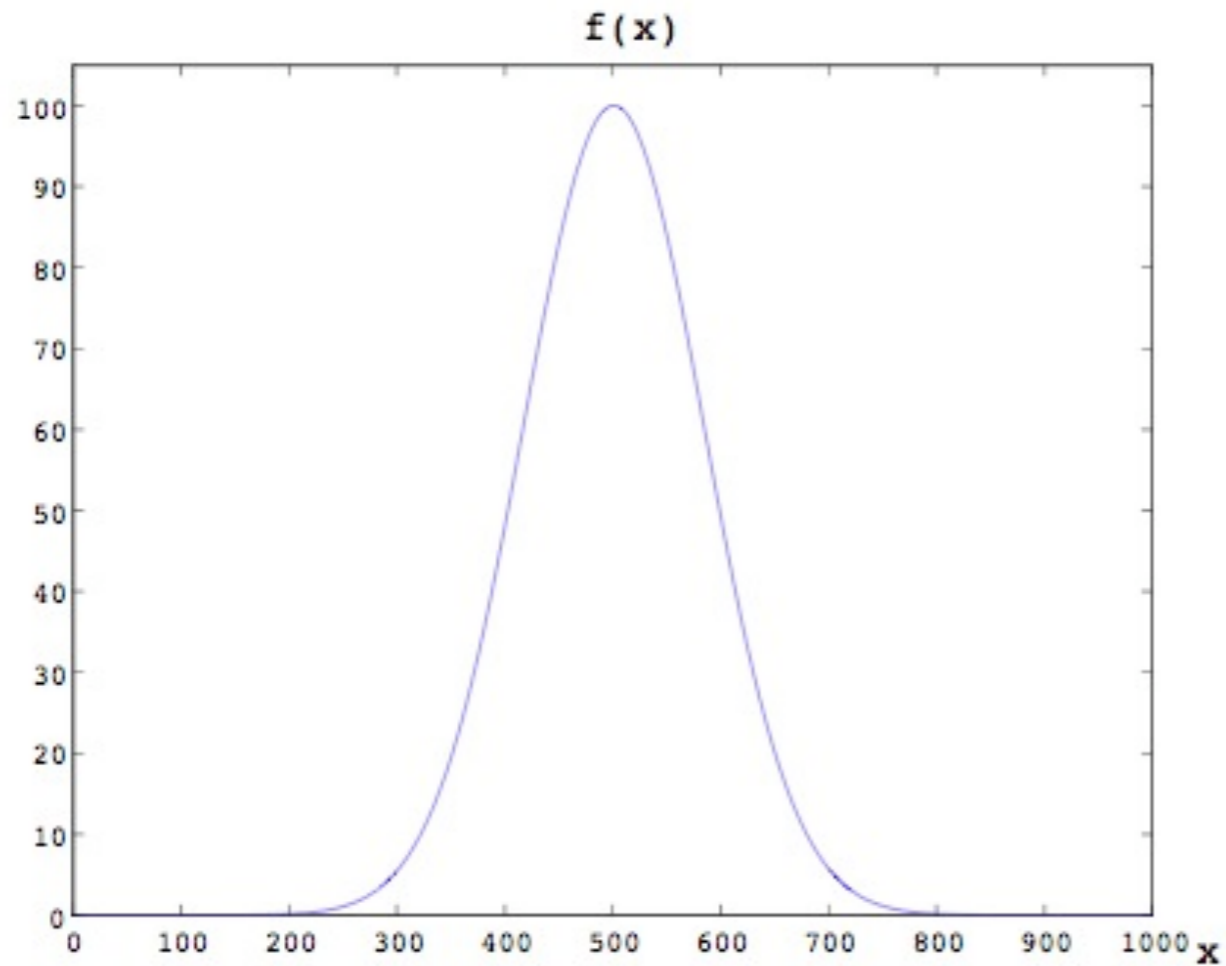
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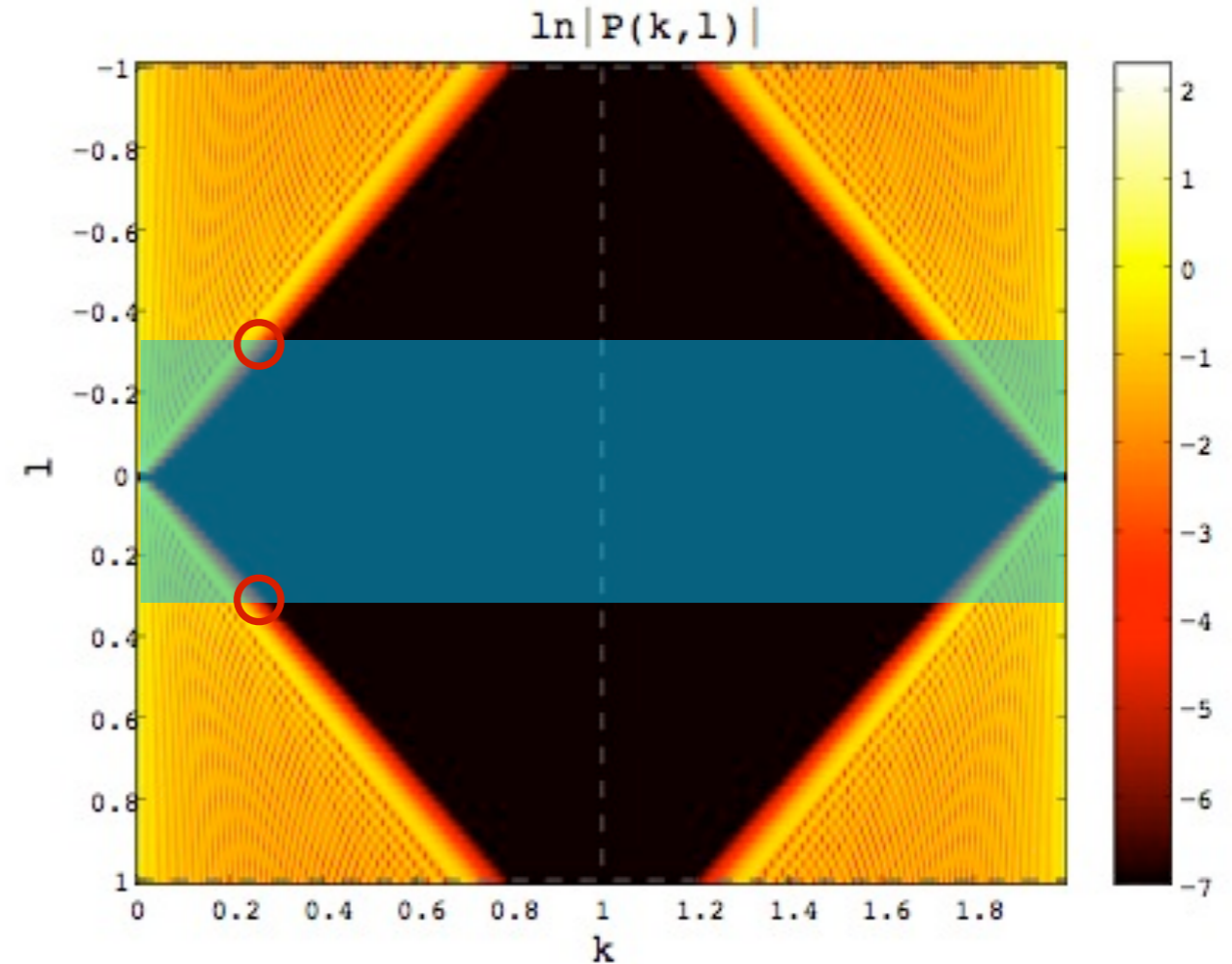
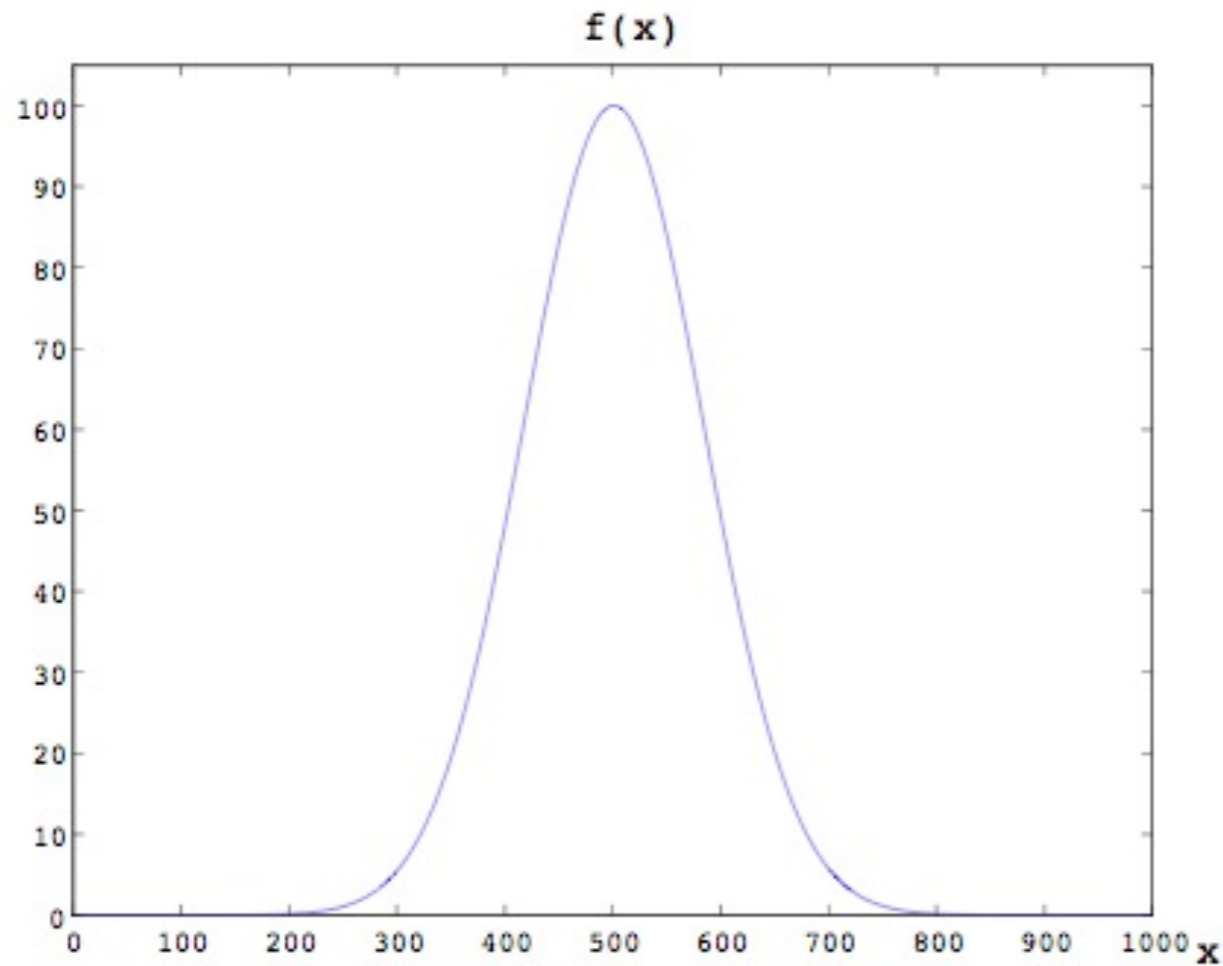
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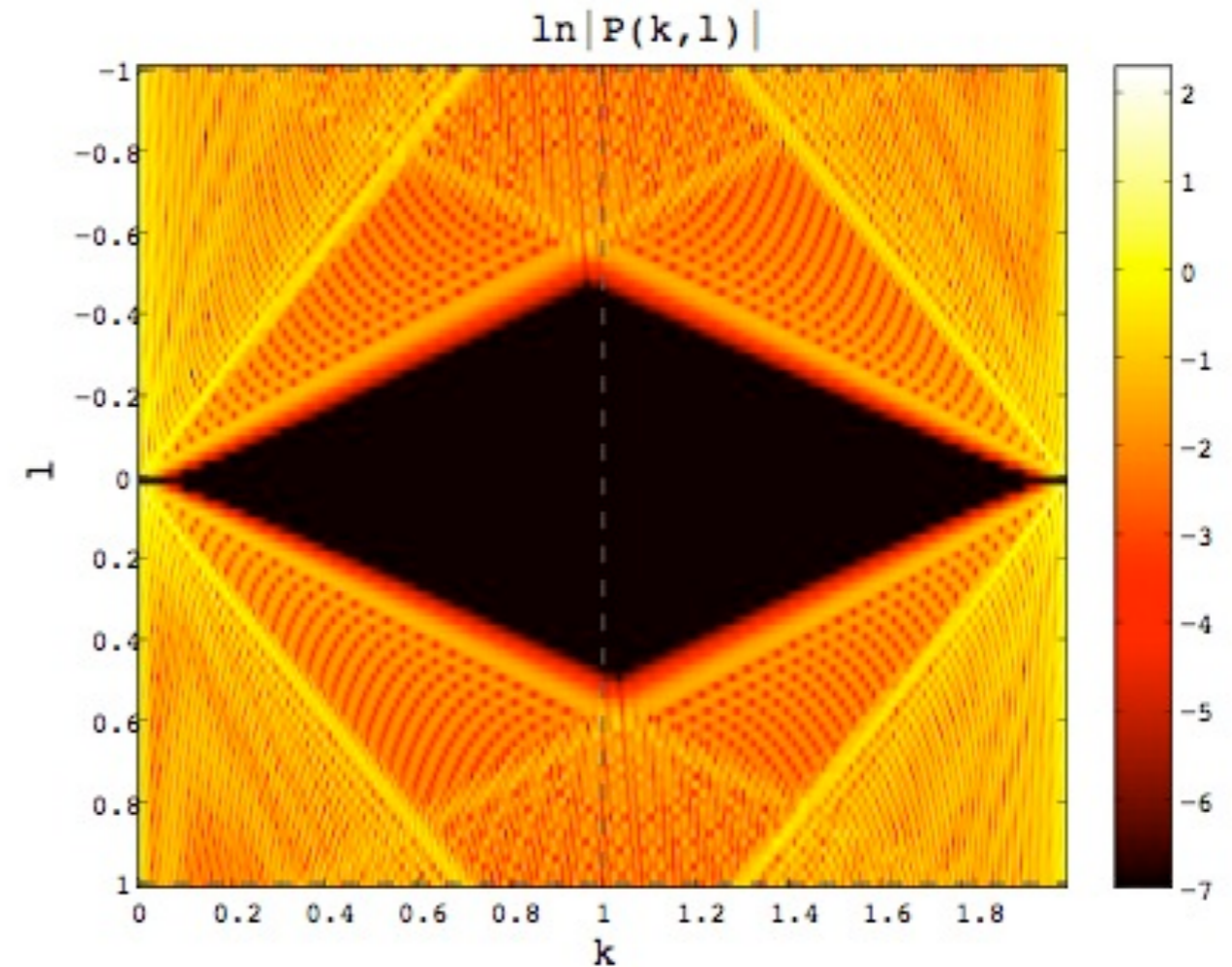
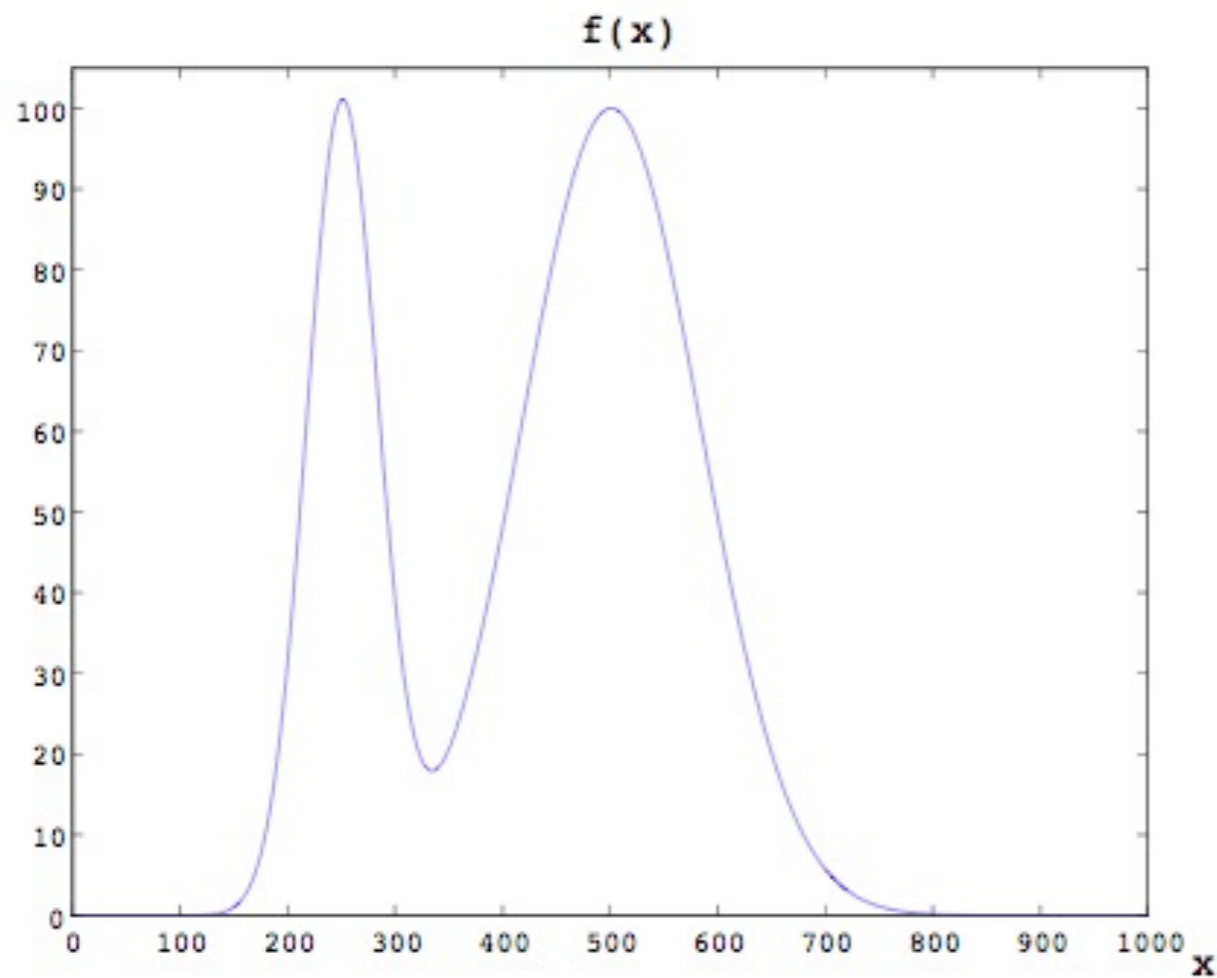
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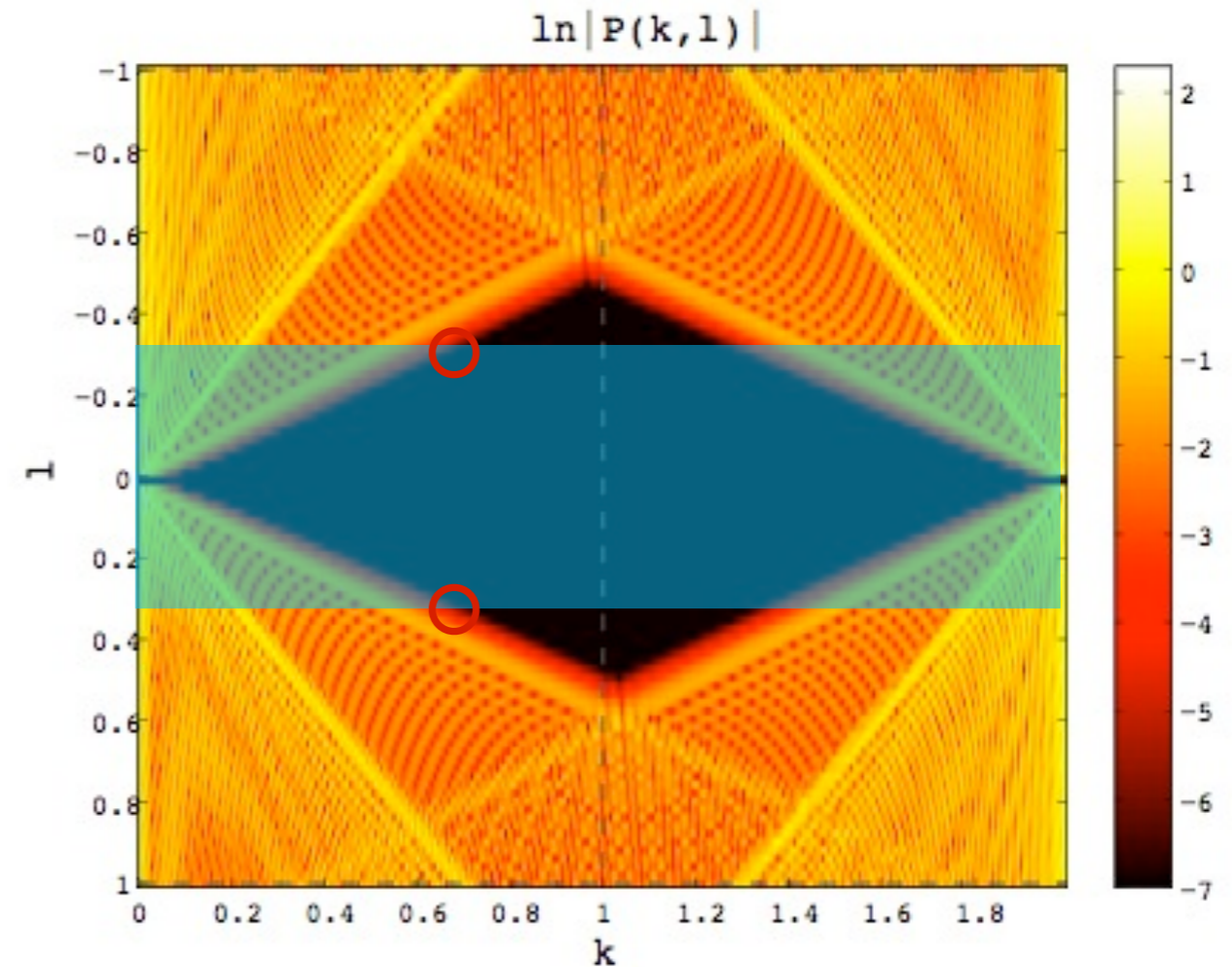
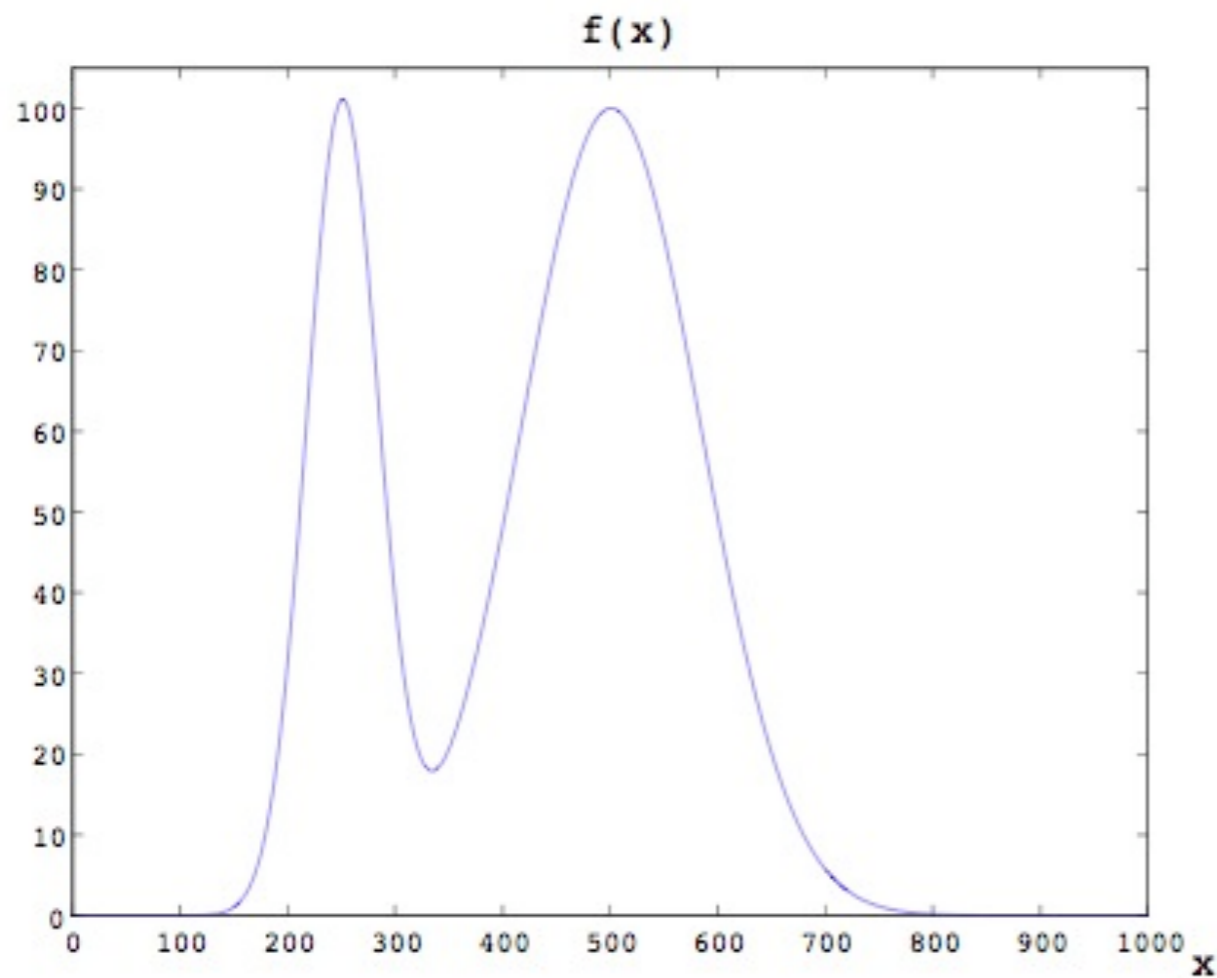




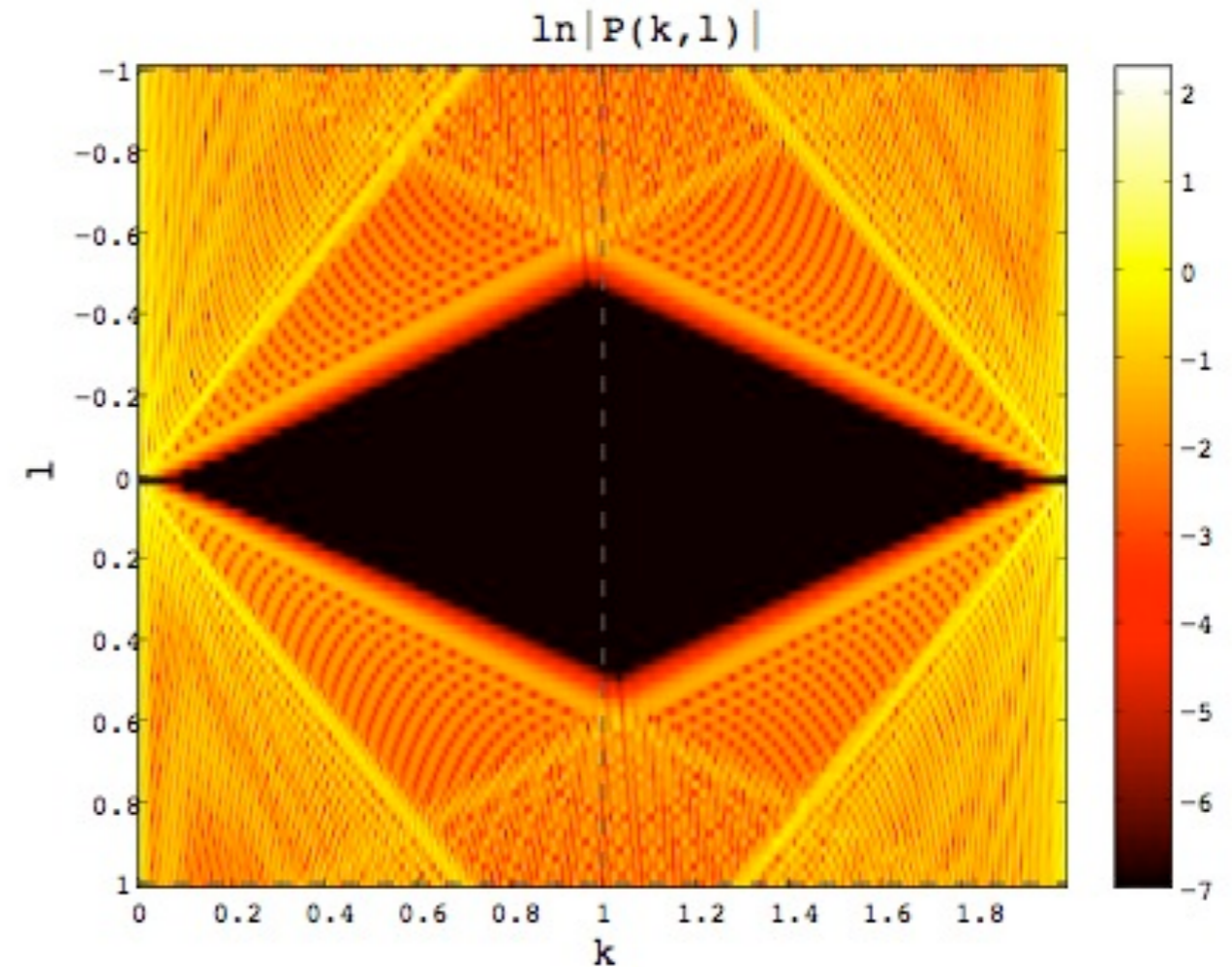
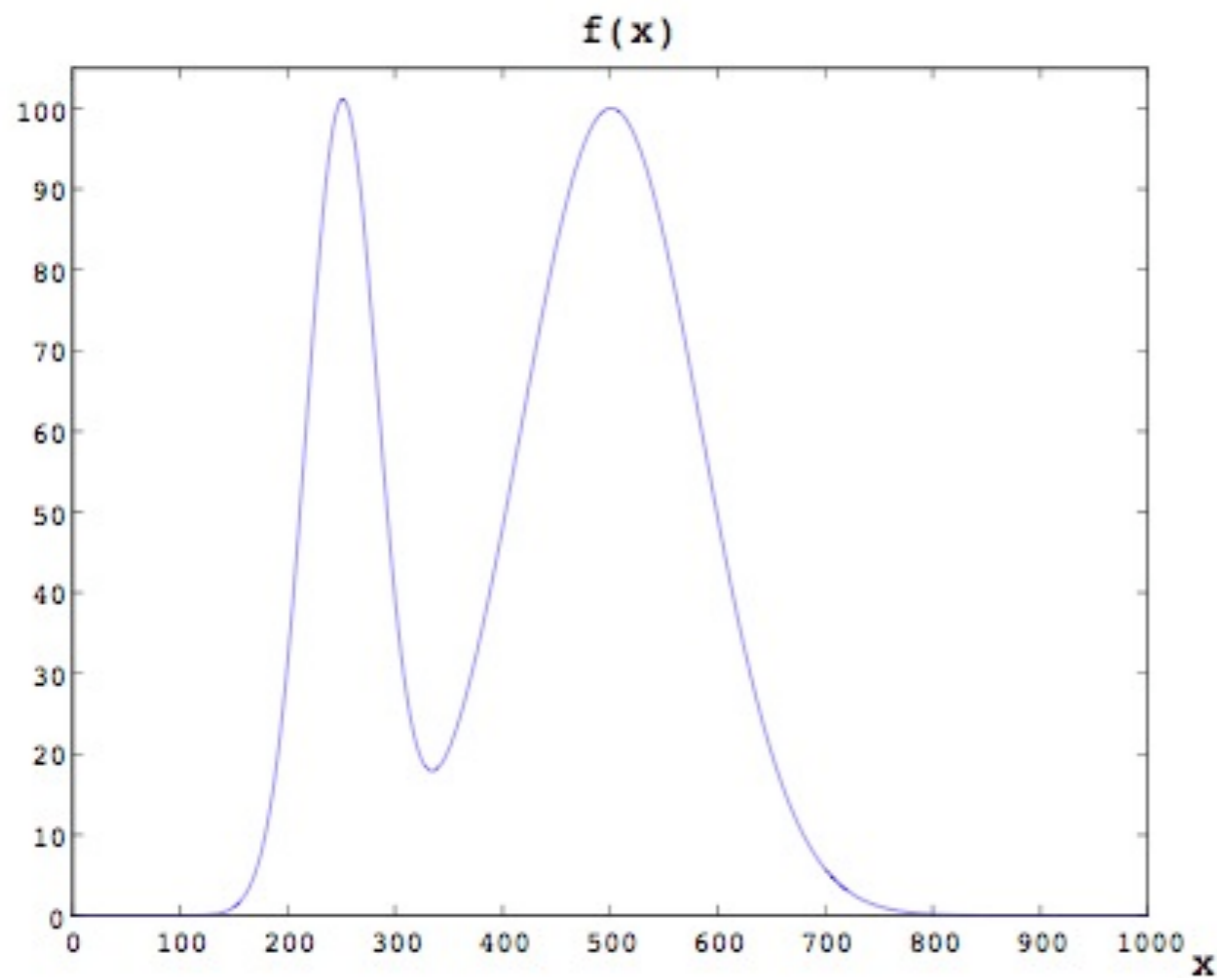
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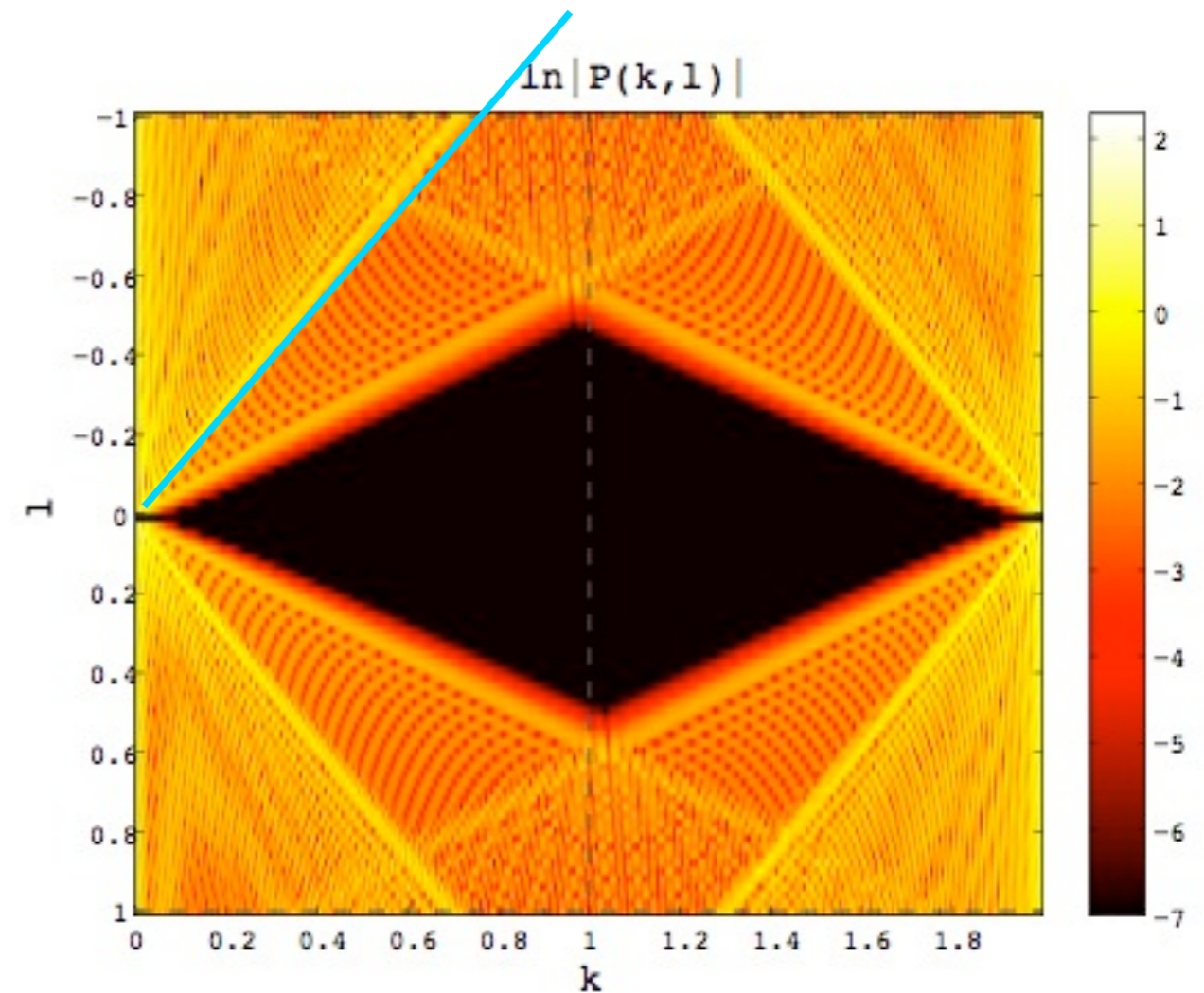
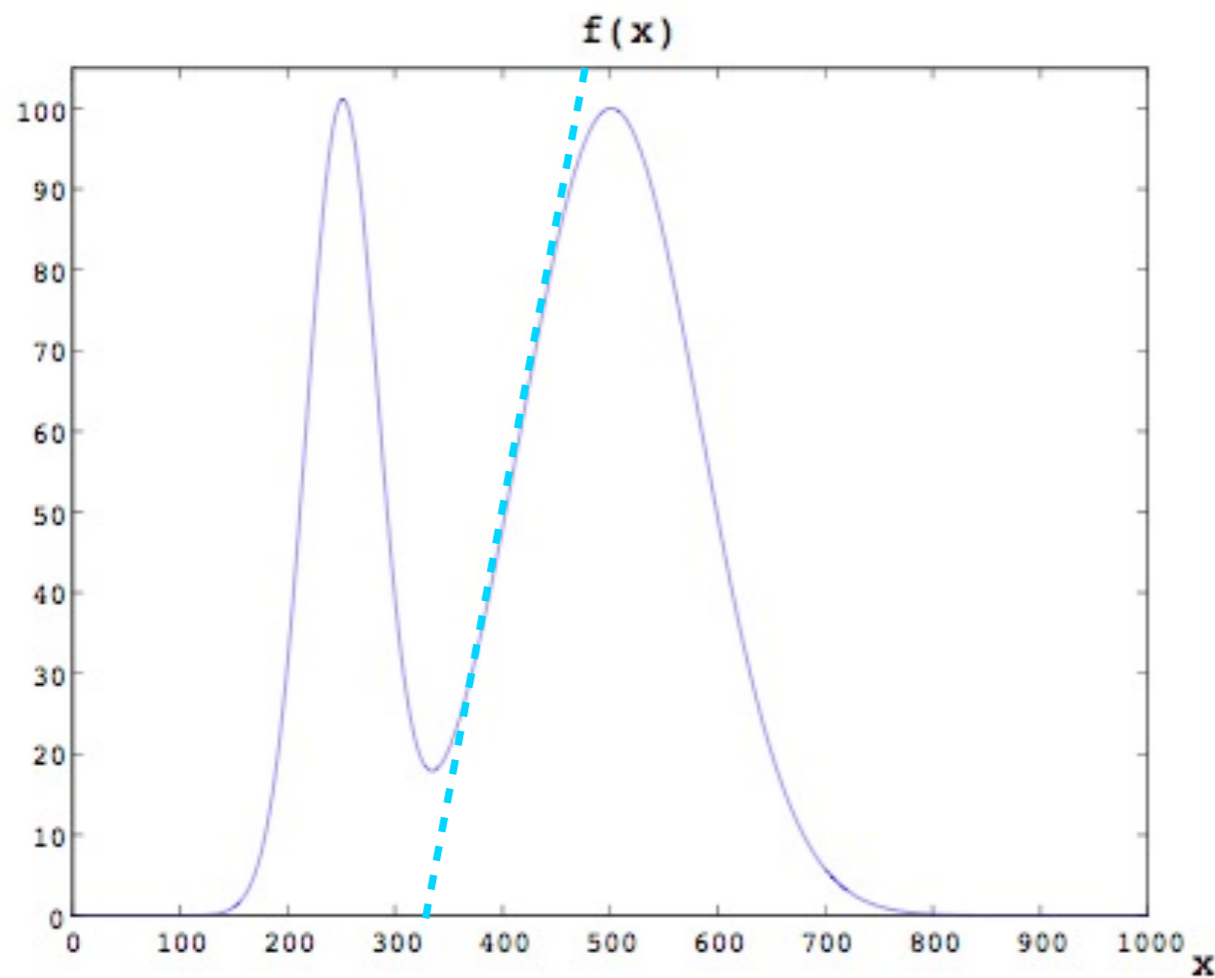


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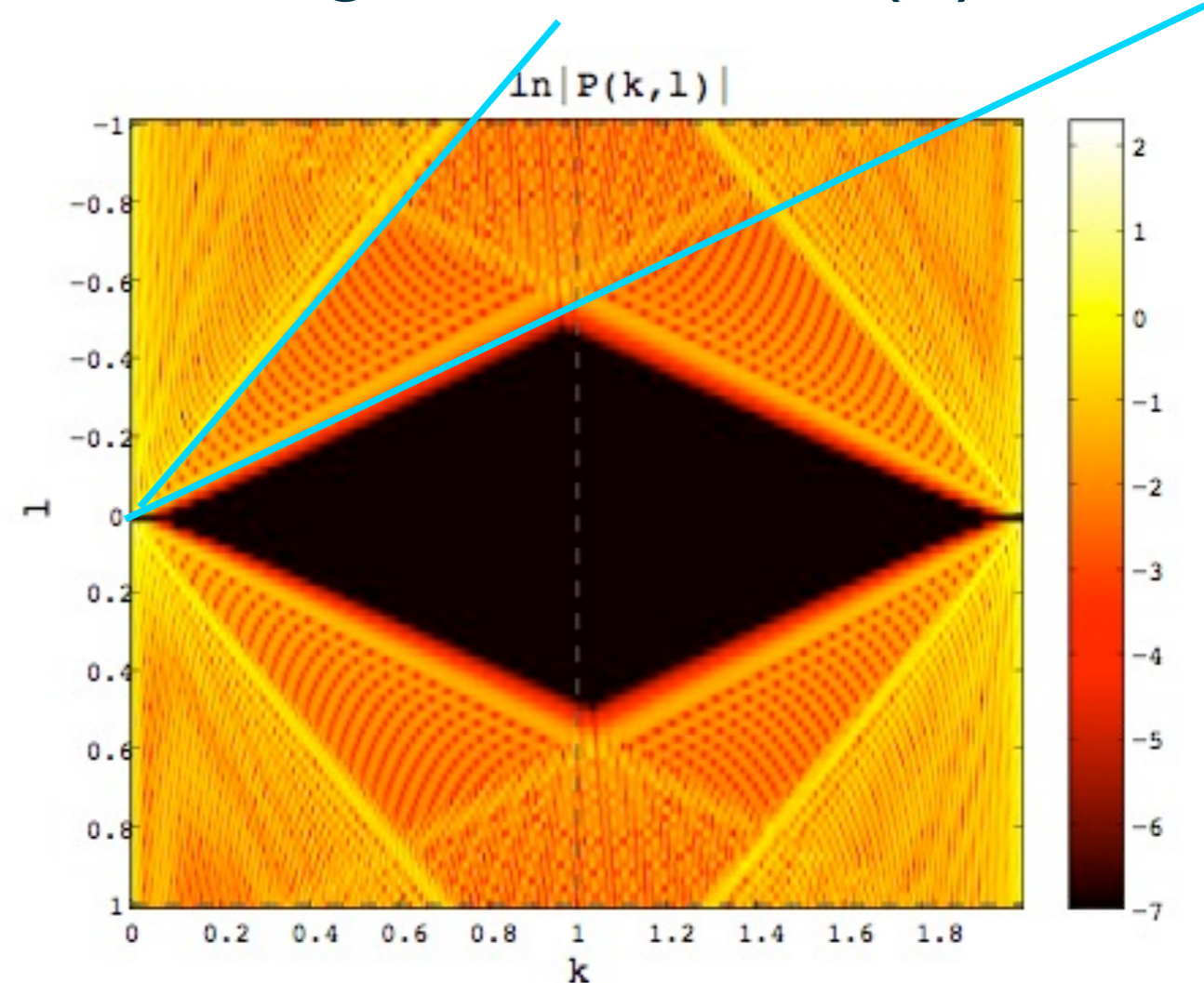
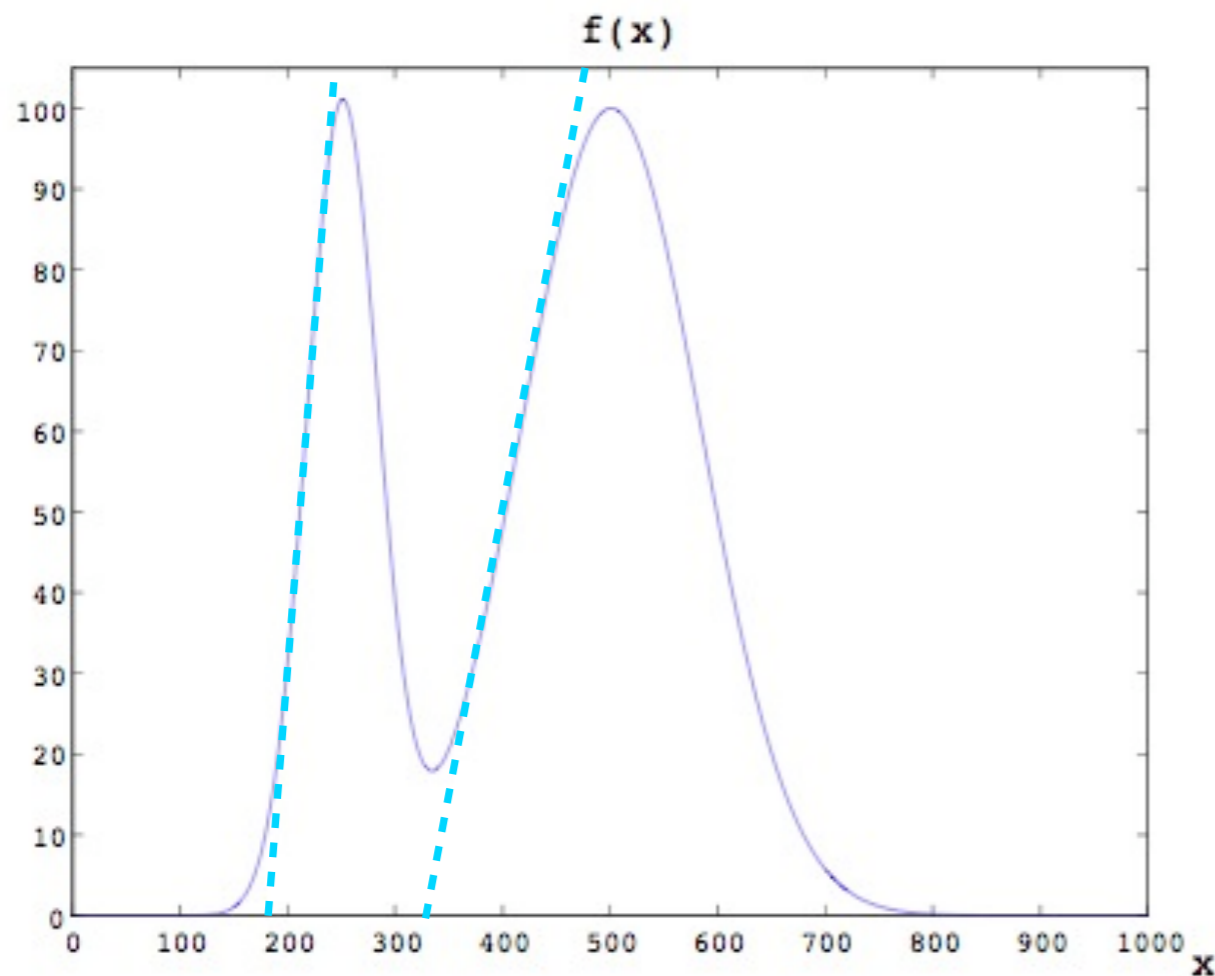
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- Slopes of lines in  $P(k,l)$  are related to  $1/f'(x)$



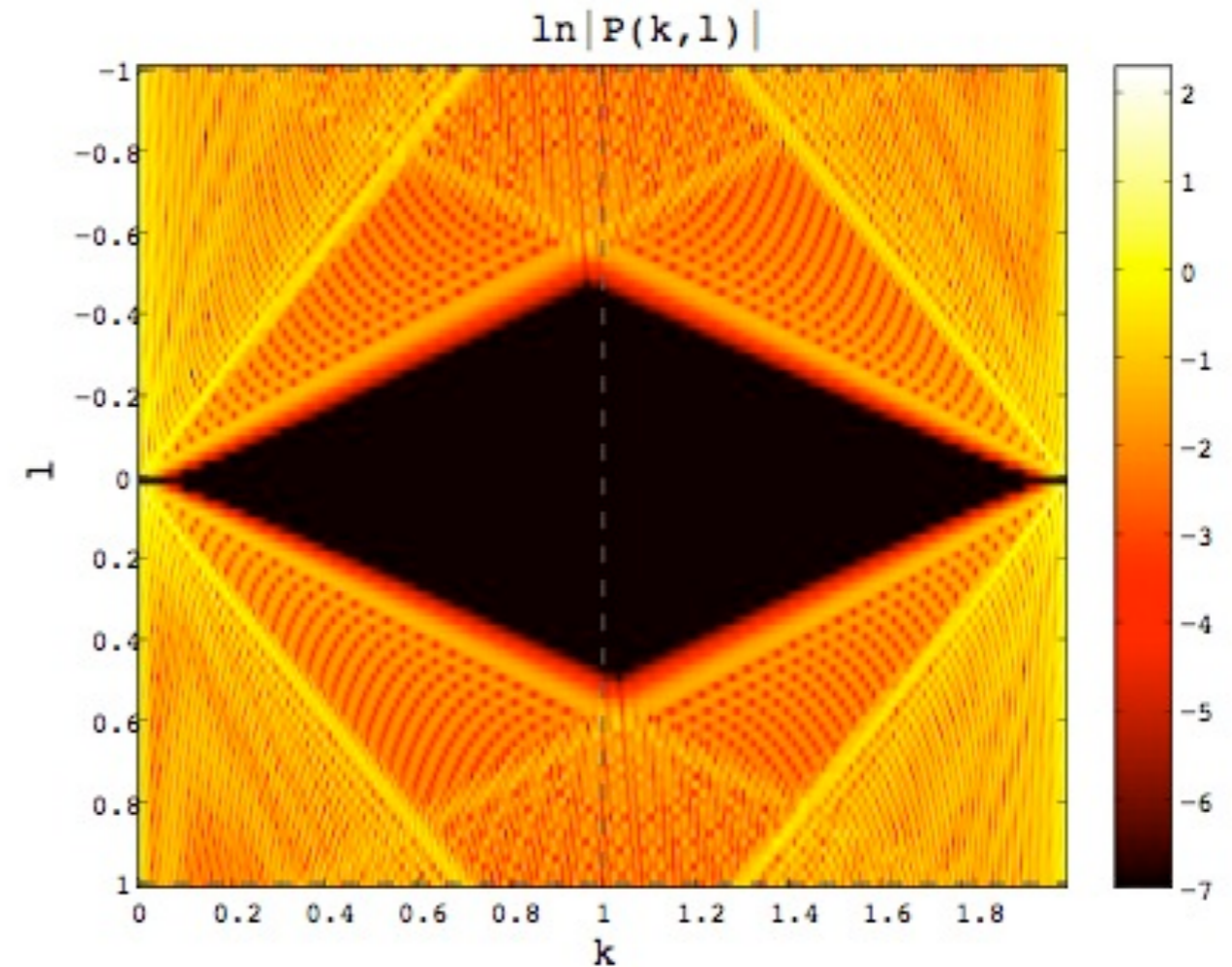
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- Slopes of lines in  $P(k,l)$  are related to  $1/f'(x)$
- Extremal slopes bounding the wedge are  $1/\max(f')$



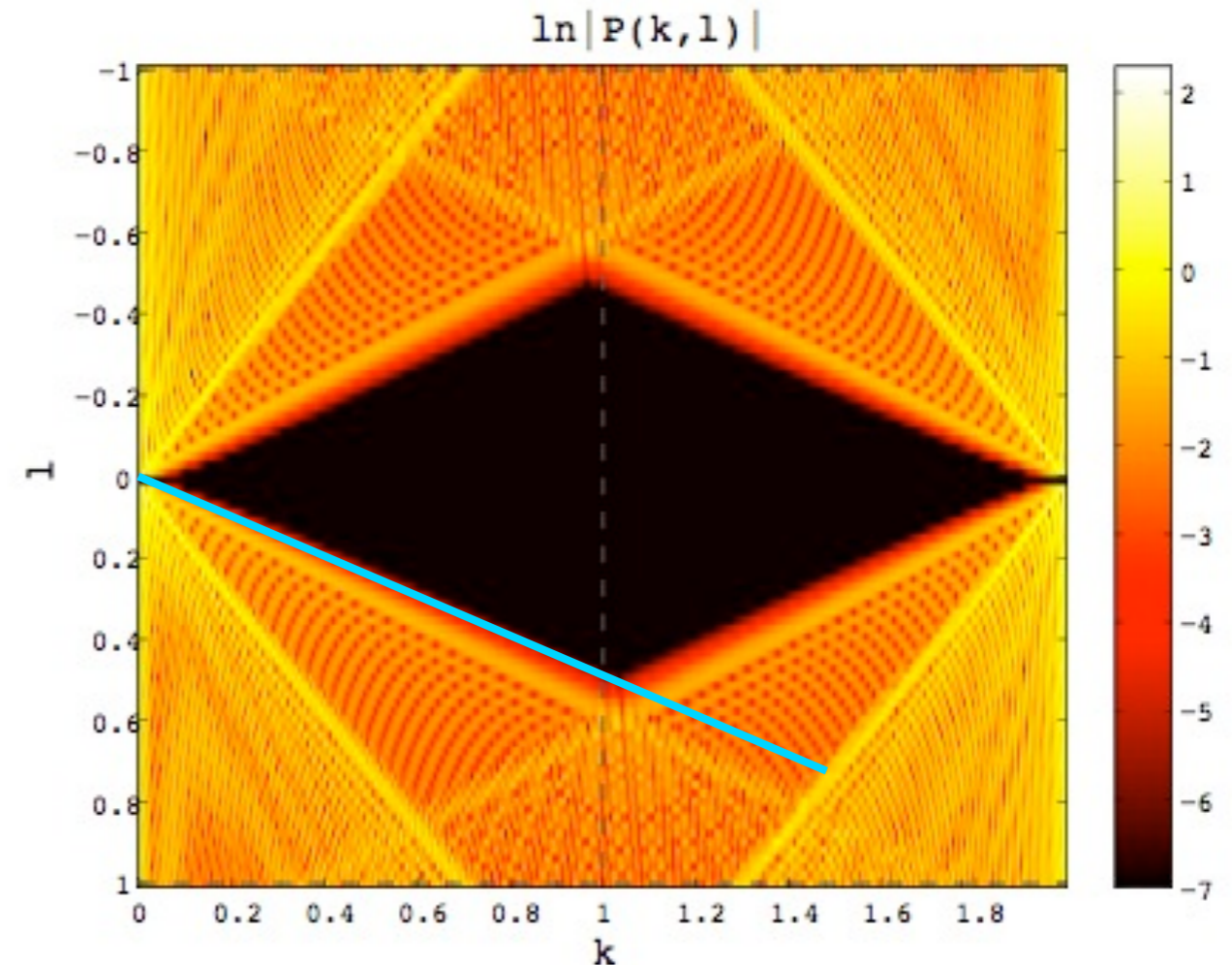
# Method of stationary phase

$$P(k, l) = \int_R e^{i(l \cdot f(x) - k \cdot x)} dx$$



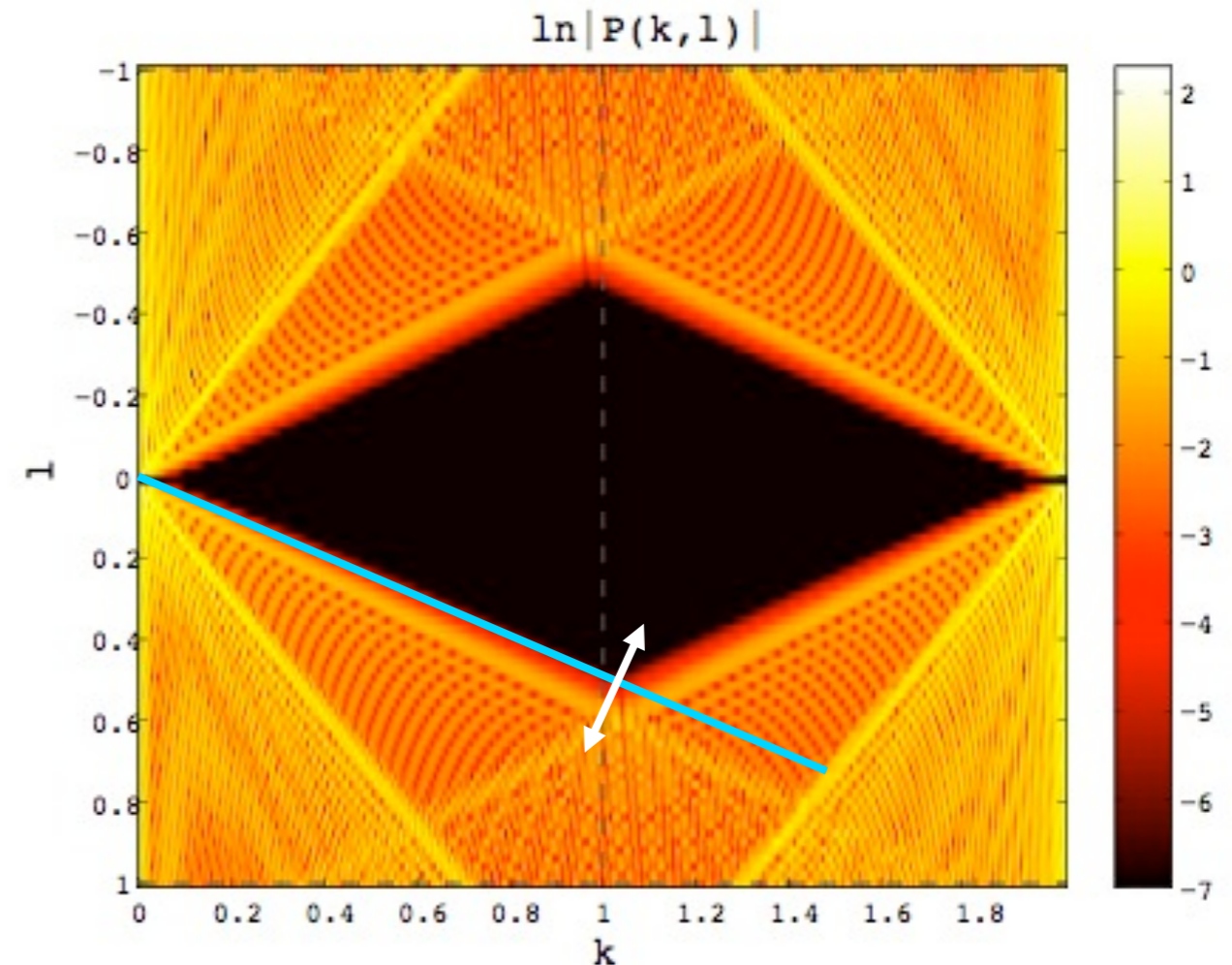
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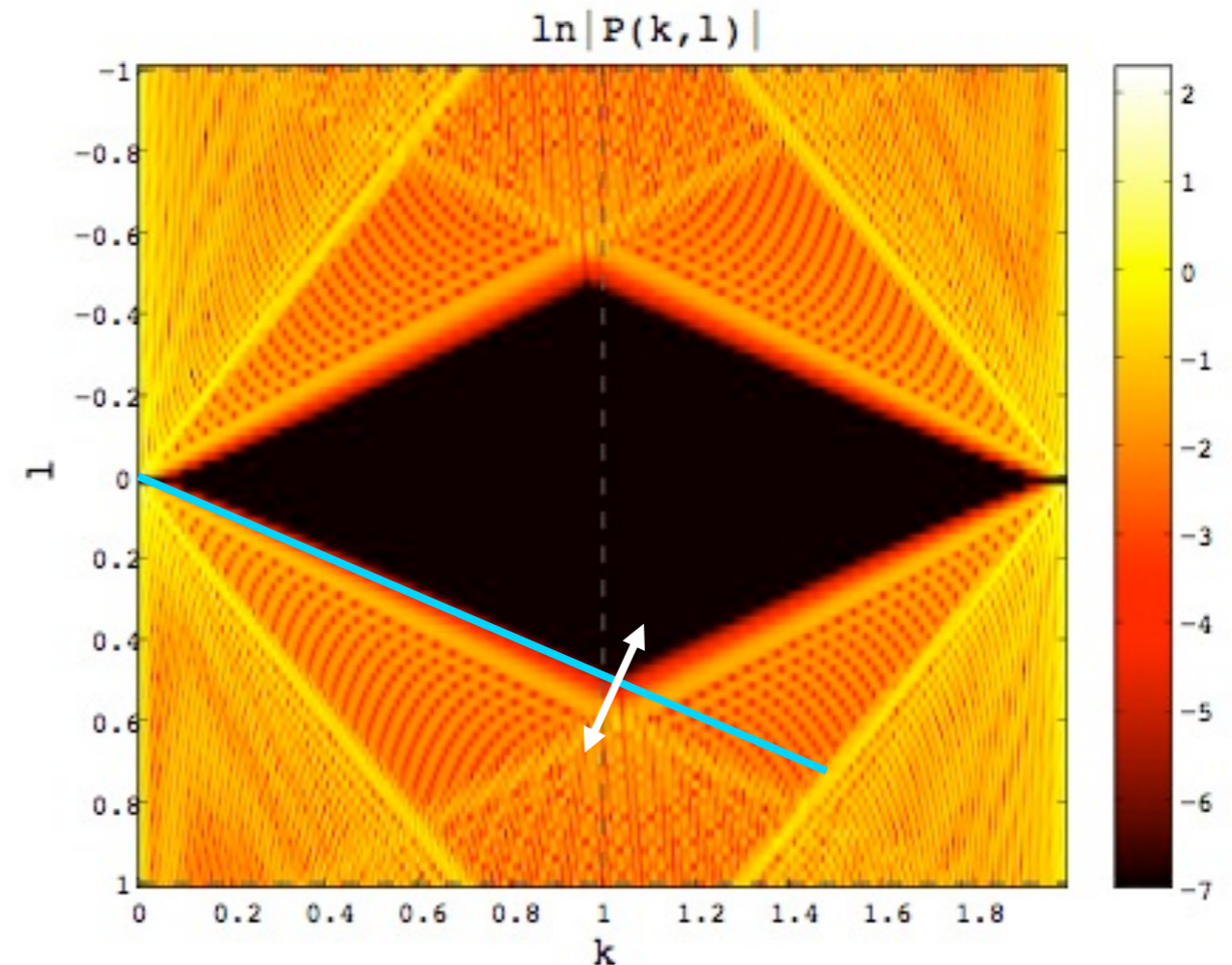




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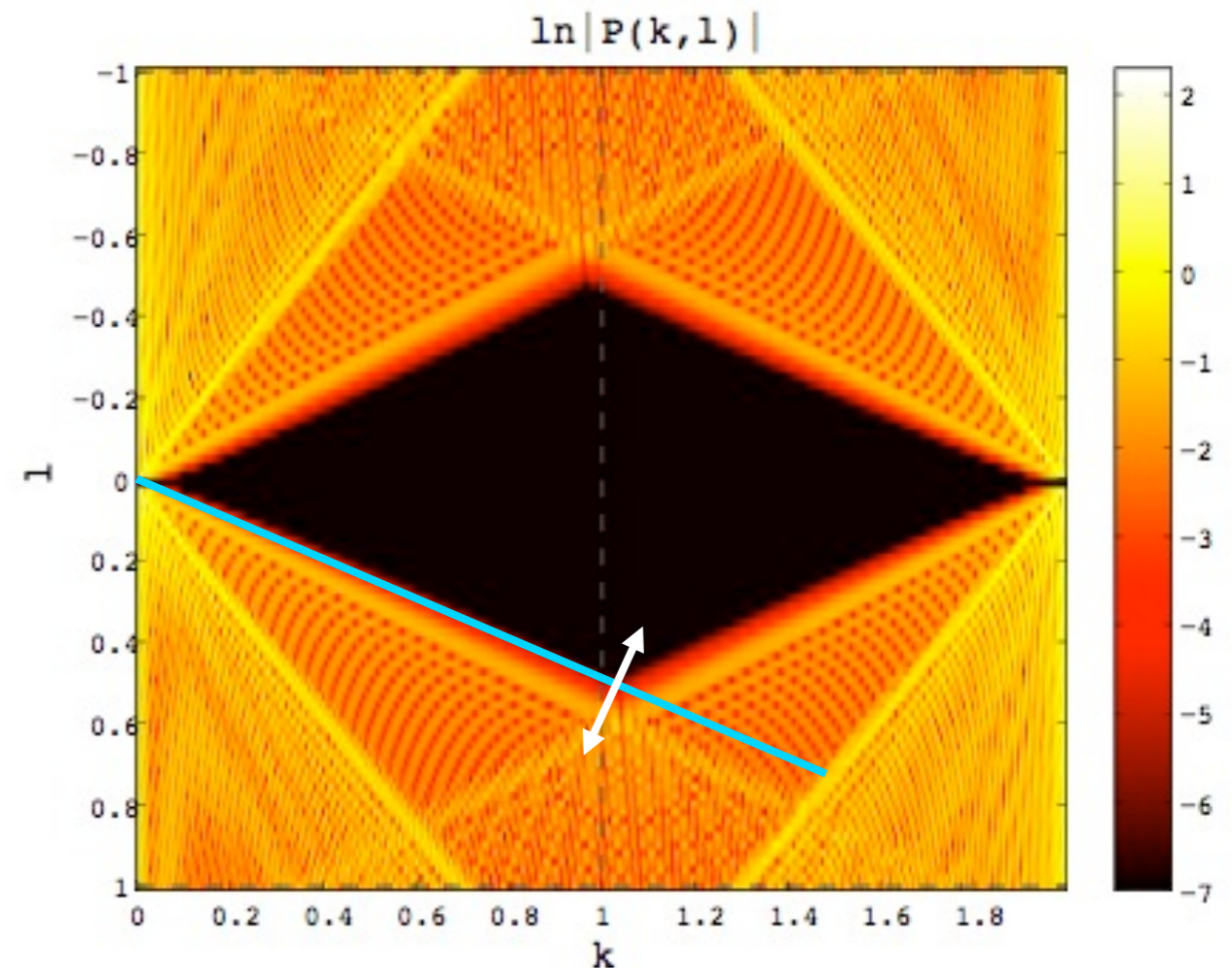
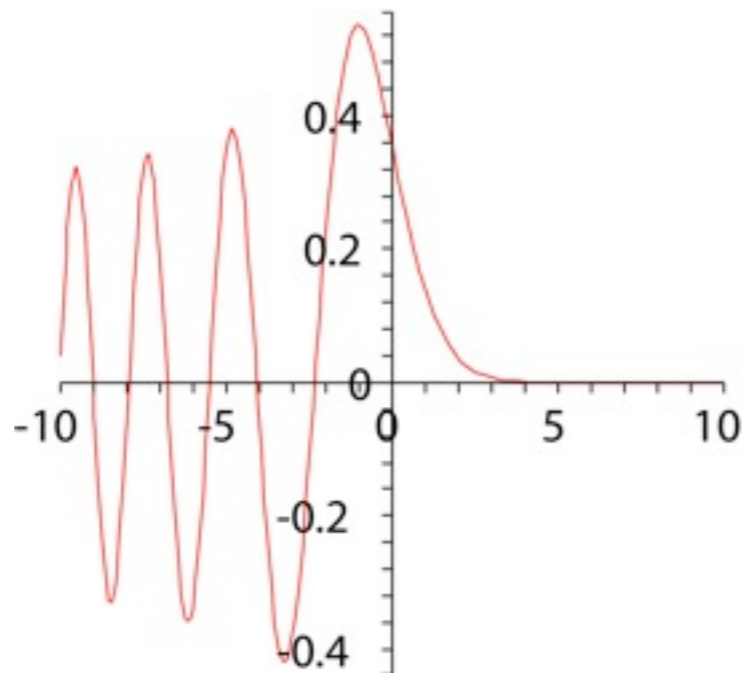
- Taylor expansion around points of stationary phase
- Exponential drop-off at maximum  $l \cdot \max |f'| = k$



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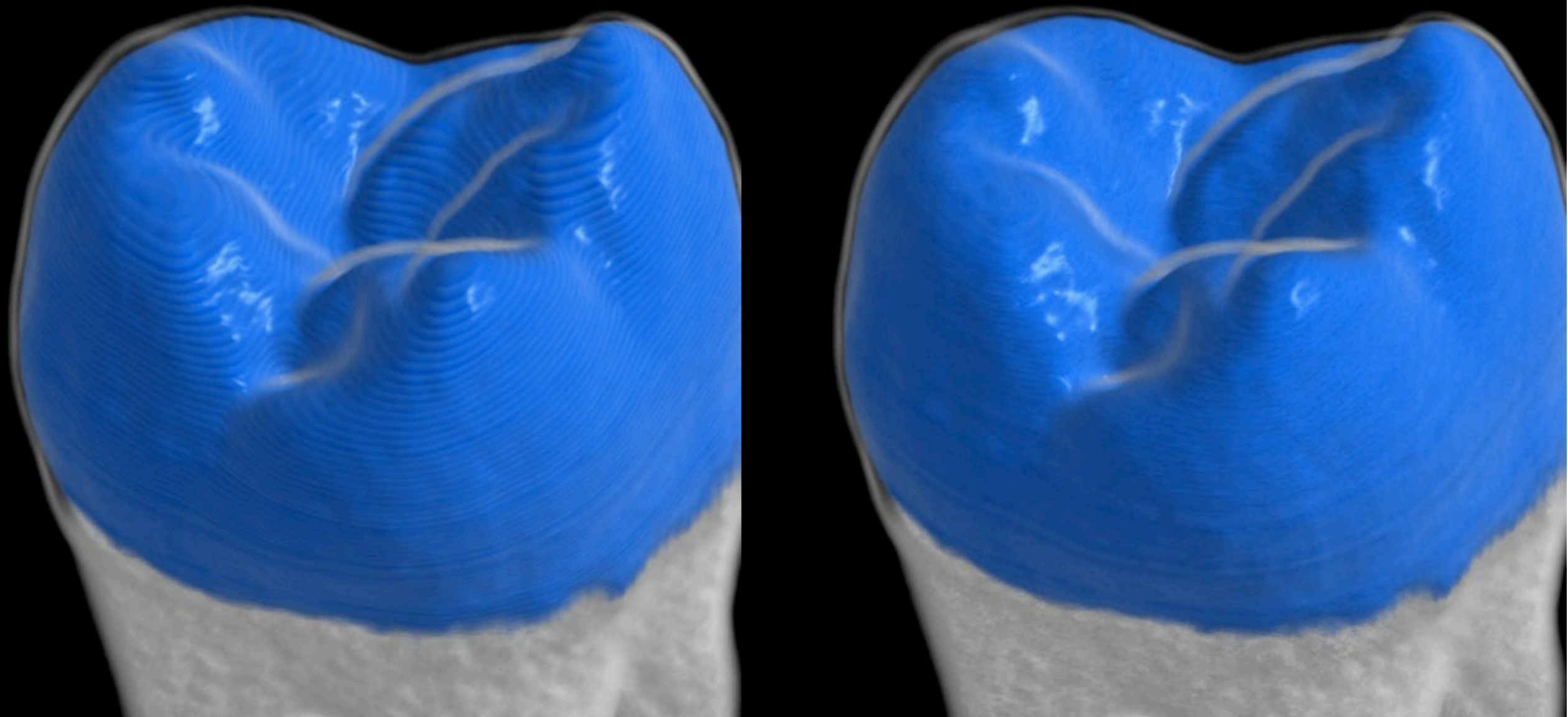
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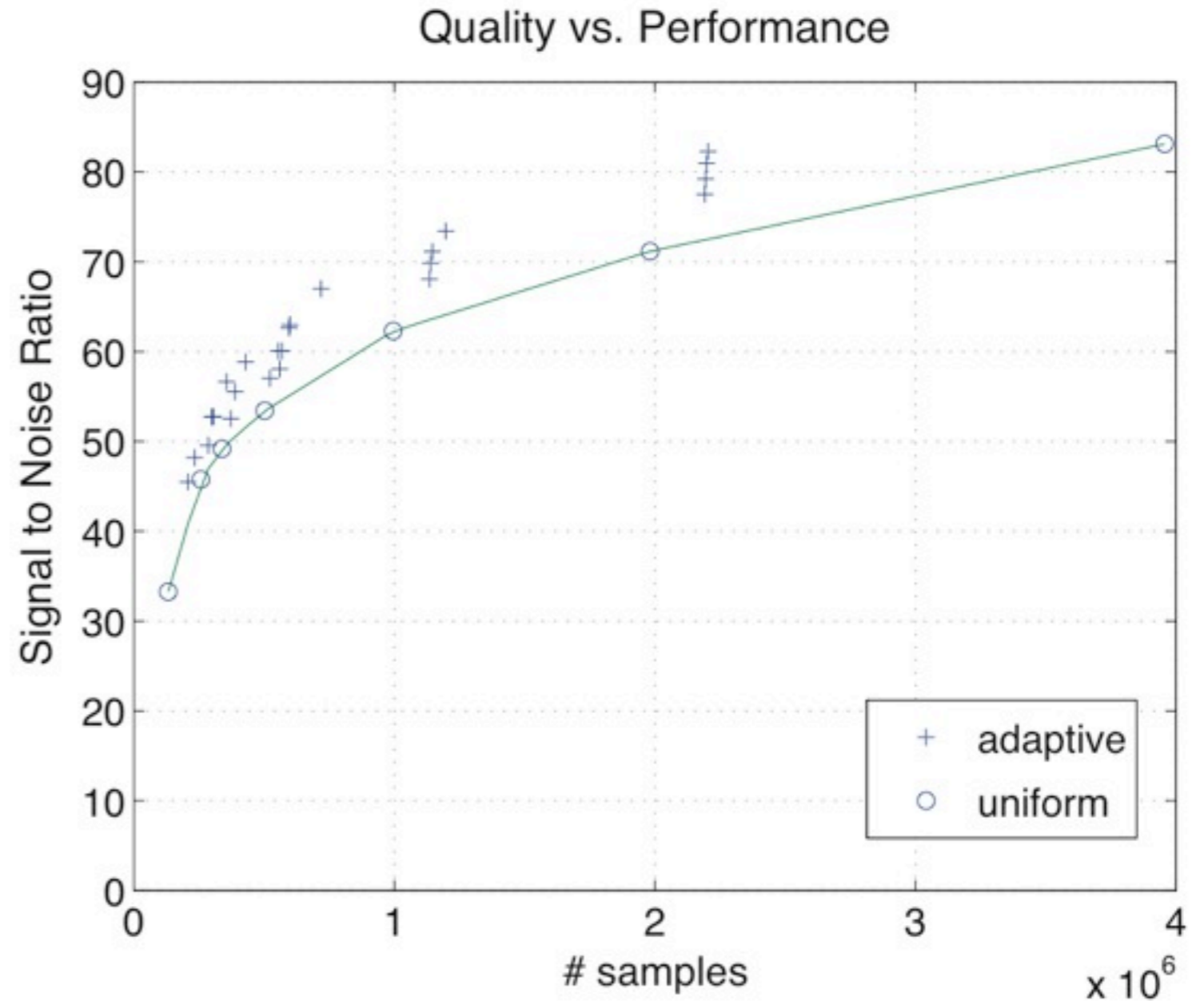
# Adaptive Raycasting

Same number of samples



# Adaptive Raycasting SNR

Ground-truth:  
computed at a fixed  
sampling distance  
of 0.06125



# Summary

- Proper sampling of combined signal  $g(f(x))$ :

$$v_h = \max(\|f'\|) \cdot v_g$$

- Solved a fundamental problem of rendering
- Composition is a general data processing operation



# Model adjustment at different levels

- User-driven experimentation: Use cases for *paraglide*
- Criteria optimization: Lighting design
- Theoretical analysis: Sampling in volume rendering
- Filling a region: Lattices with rotational dilation
- Summary and conclusion



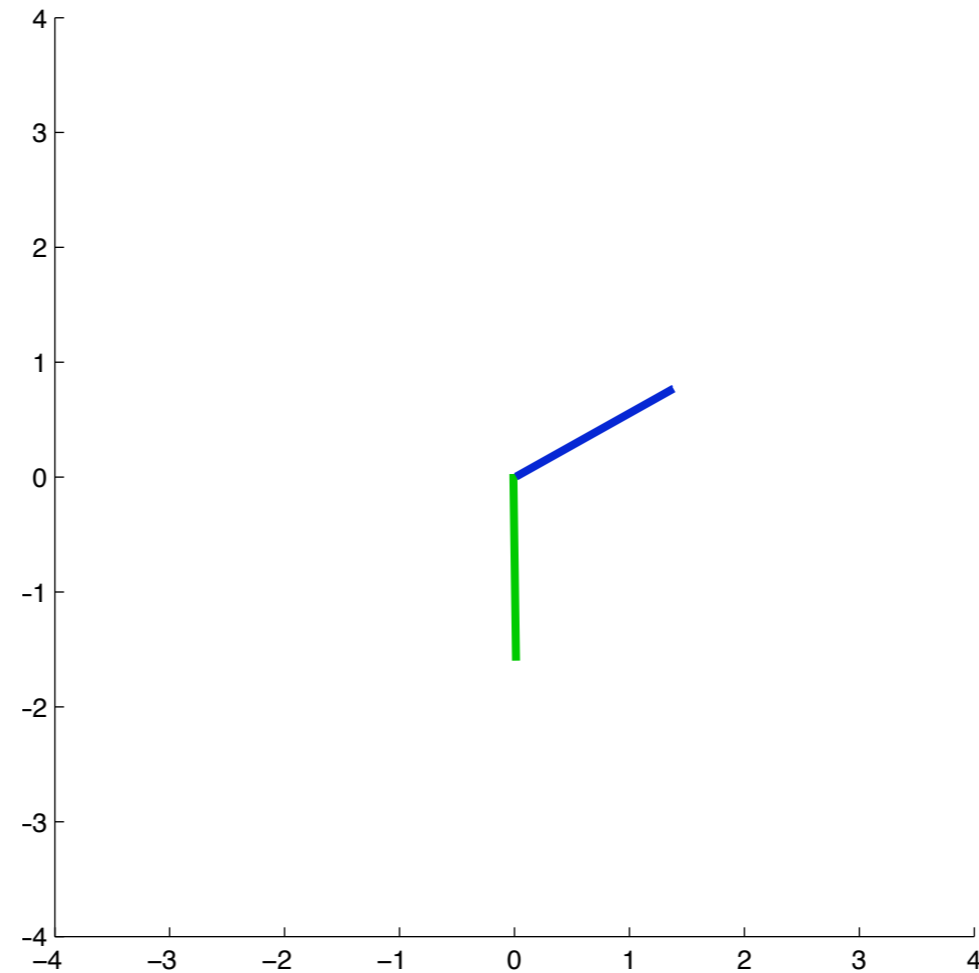
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# Point lattices

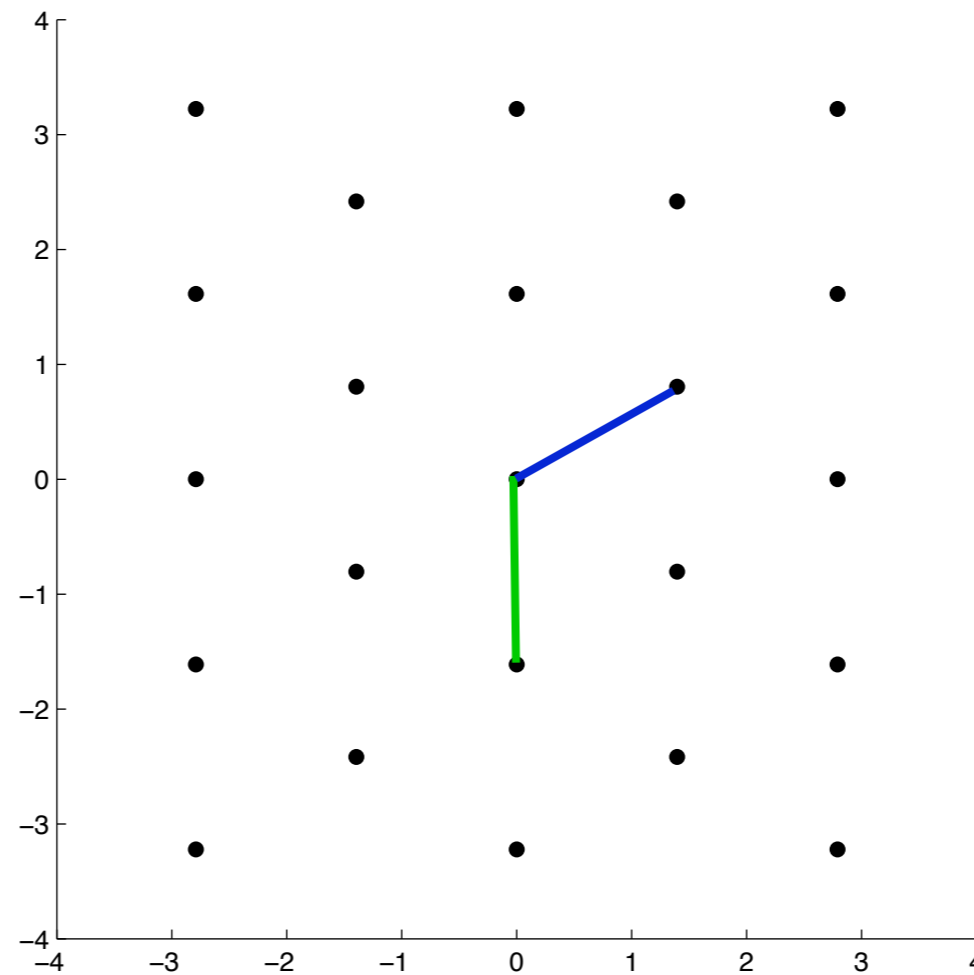
- Definition via basis  $\mathbb{R}$



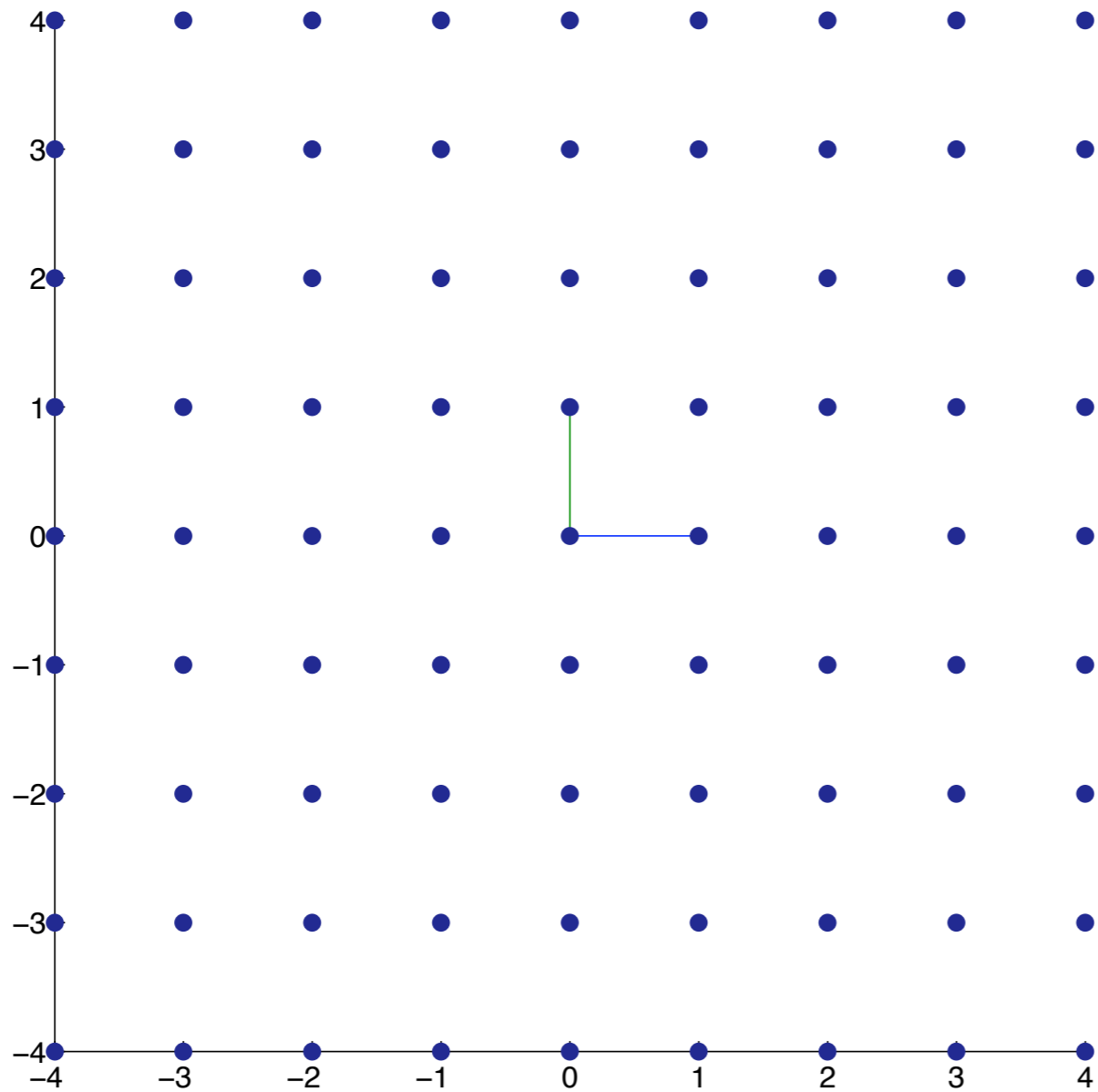


# Point lattices

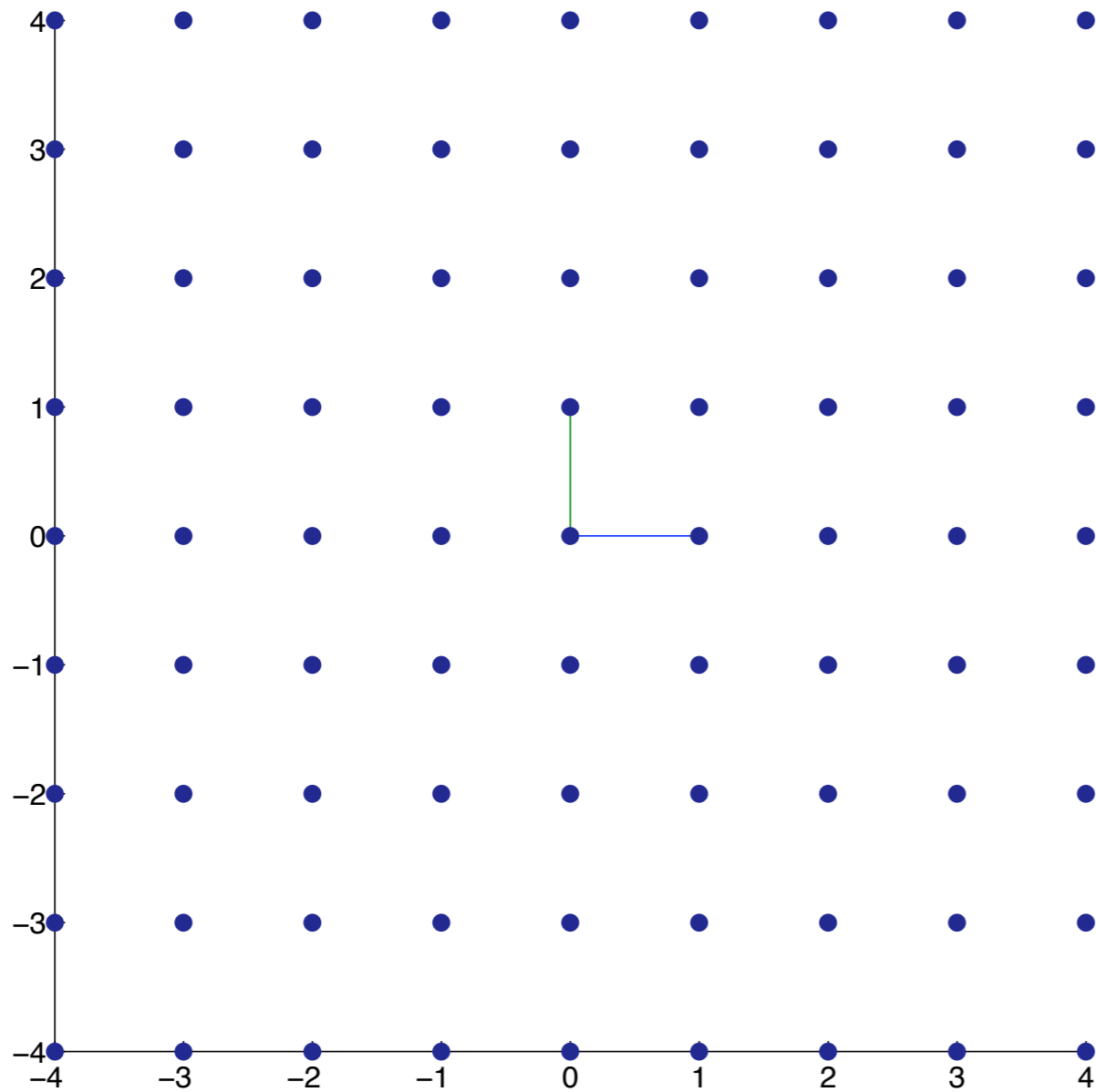
- Definition via basis  $\{\mathbf{R}k : k \in \mathbb{Z}^n\}$



$$\mathbf{R} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$



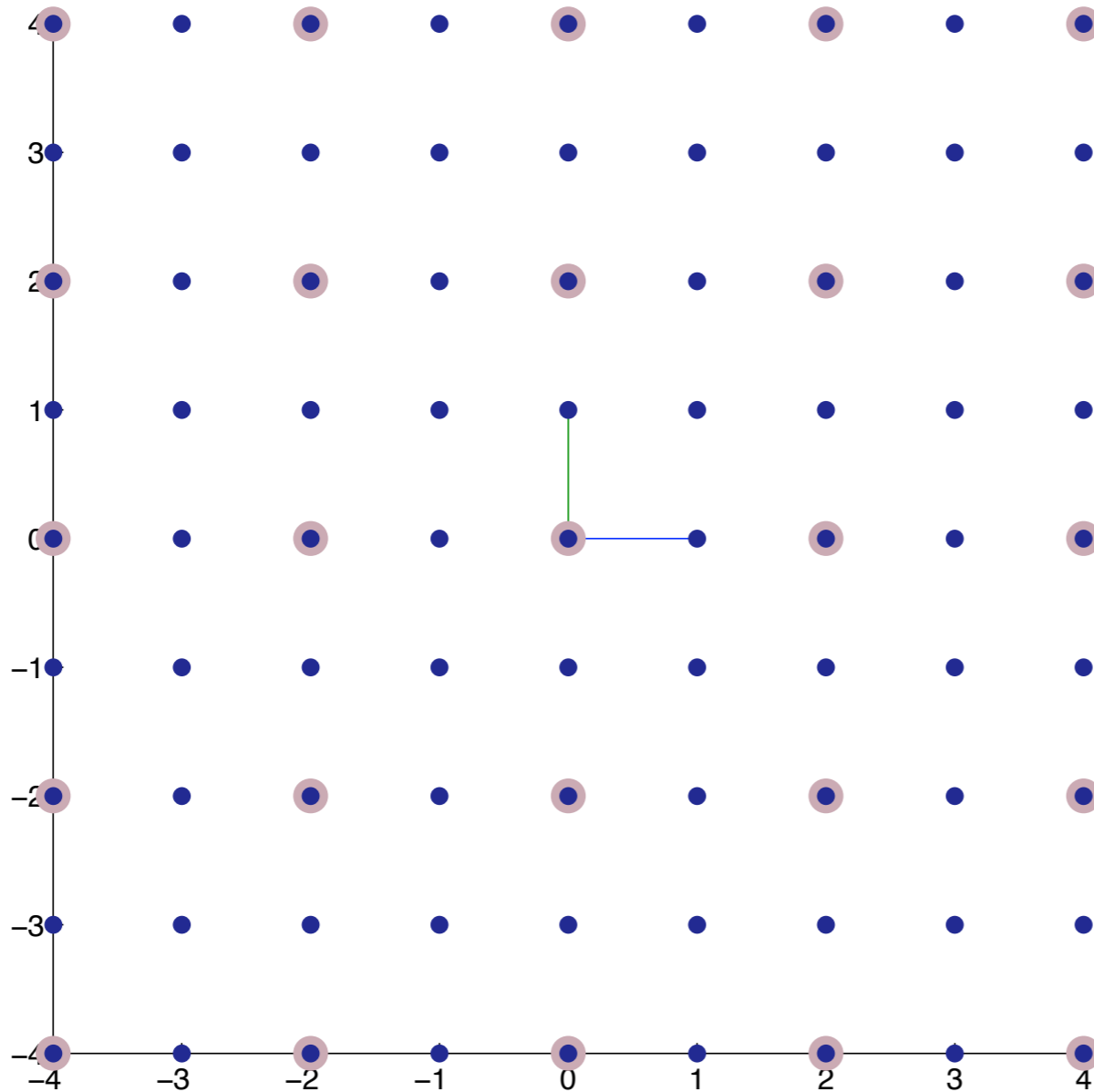
$$\mathbf{R} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \quad \mathbf{K} = \begin{bmatrix} 2 & 0 \\ 0 & 2 \end{bmatrix} = 2\mathbf{I} \quad \det \mathbf{K} = 2^n = 4$$



dyadic subsampling



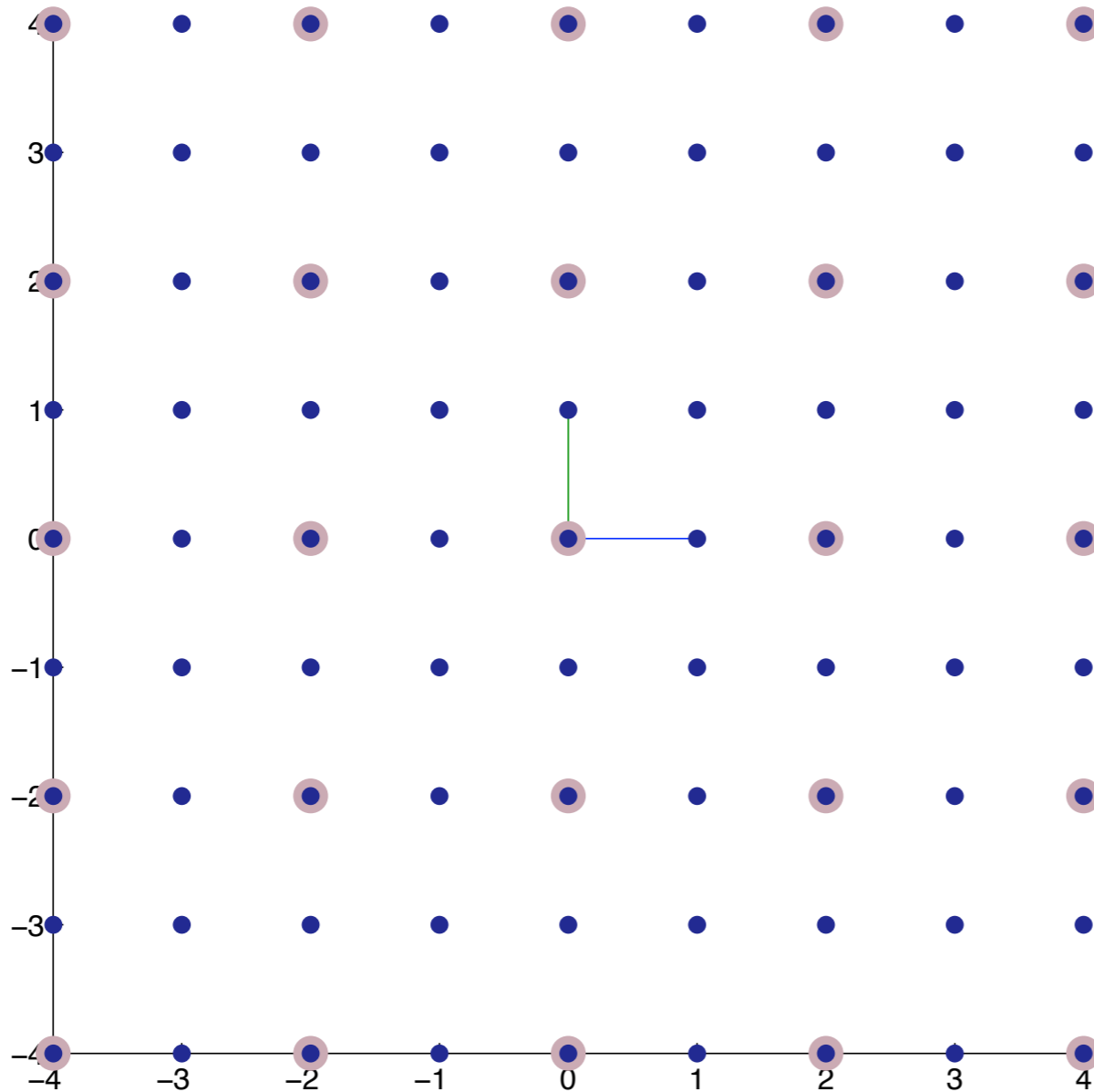
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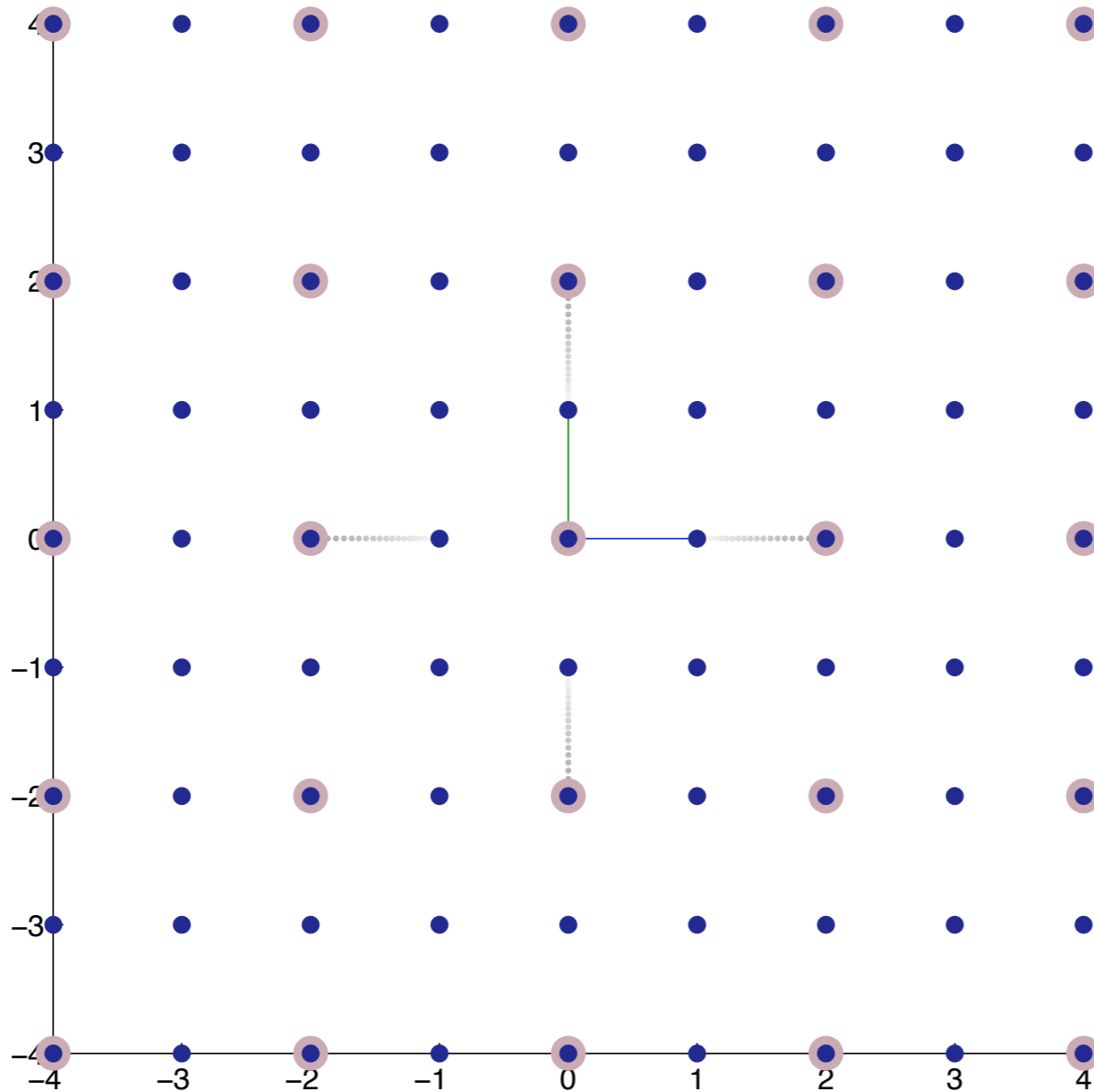


Reduction factor  
is exponential in  $n$

dyadic subsampling



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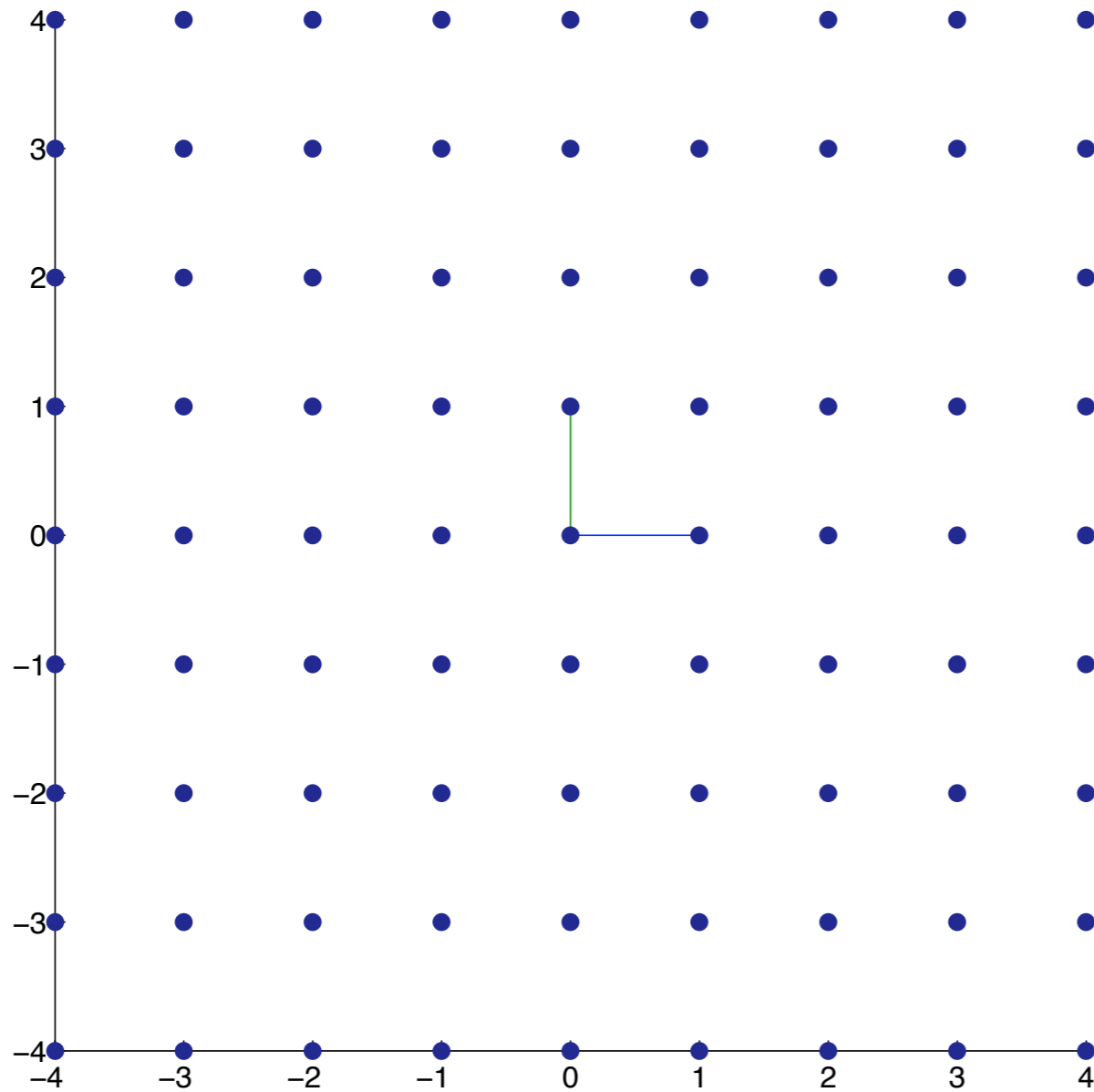


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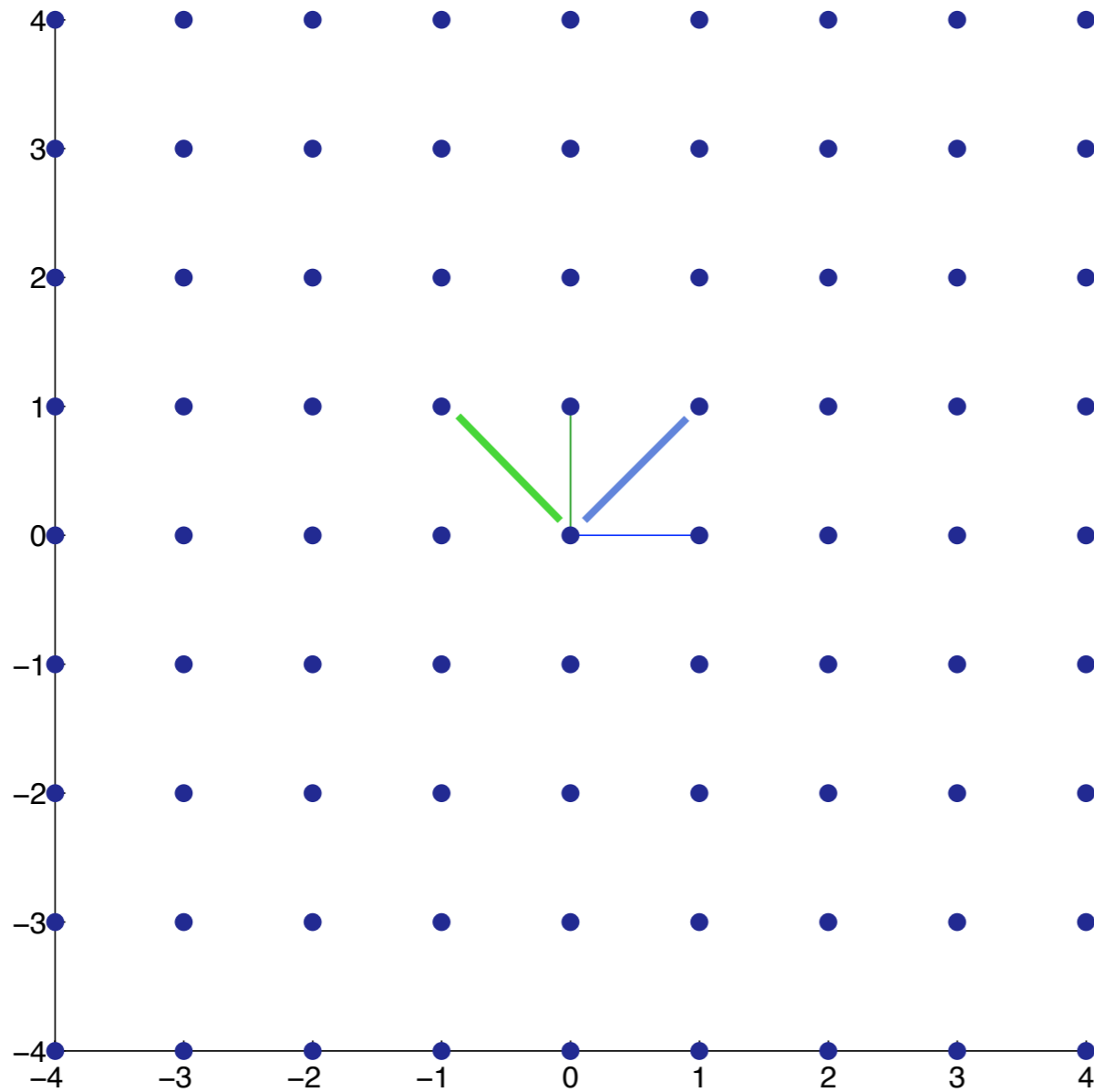
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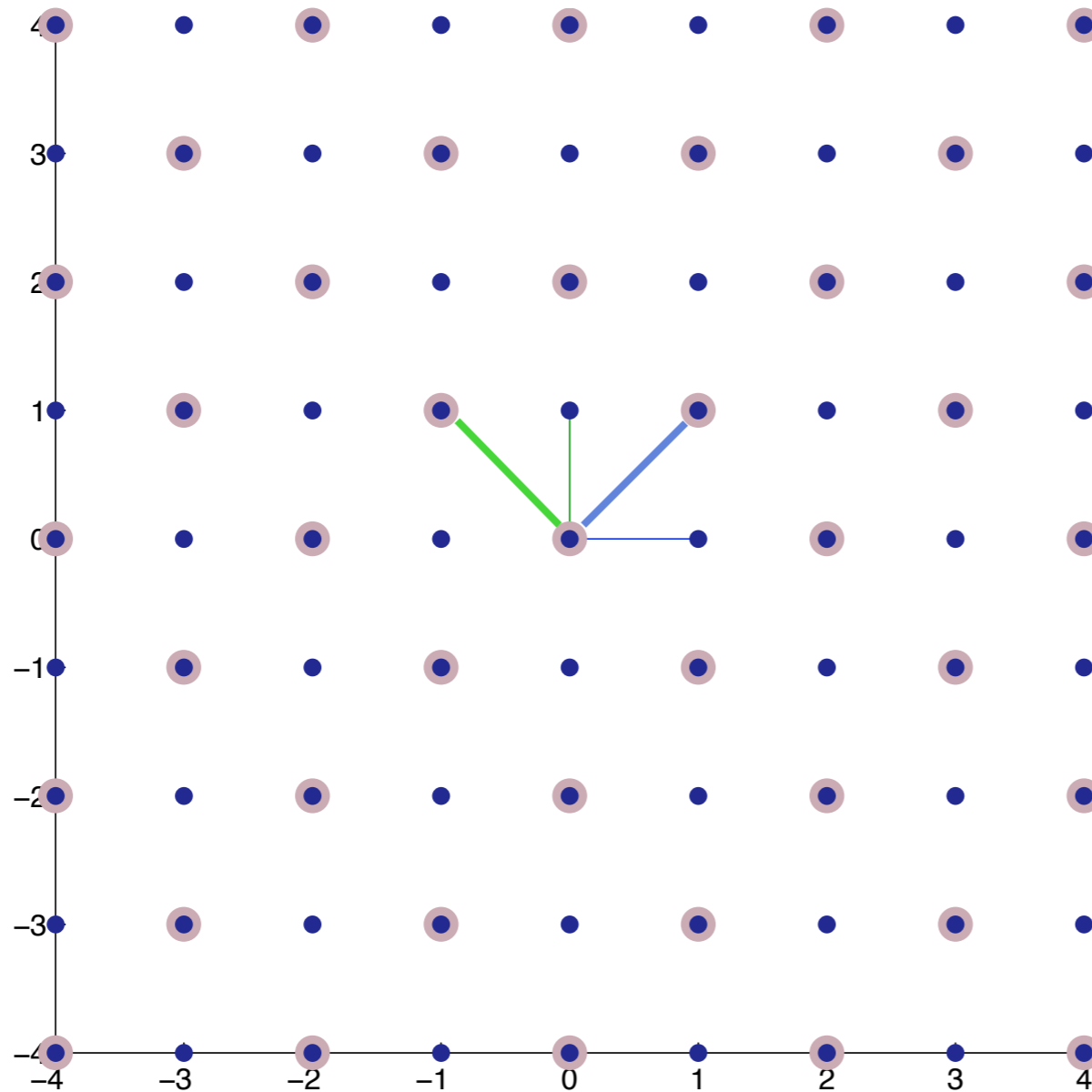


quincunx subsampling





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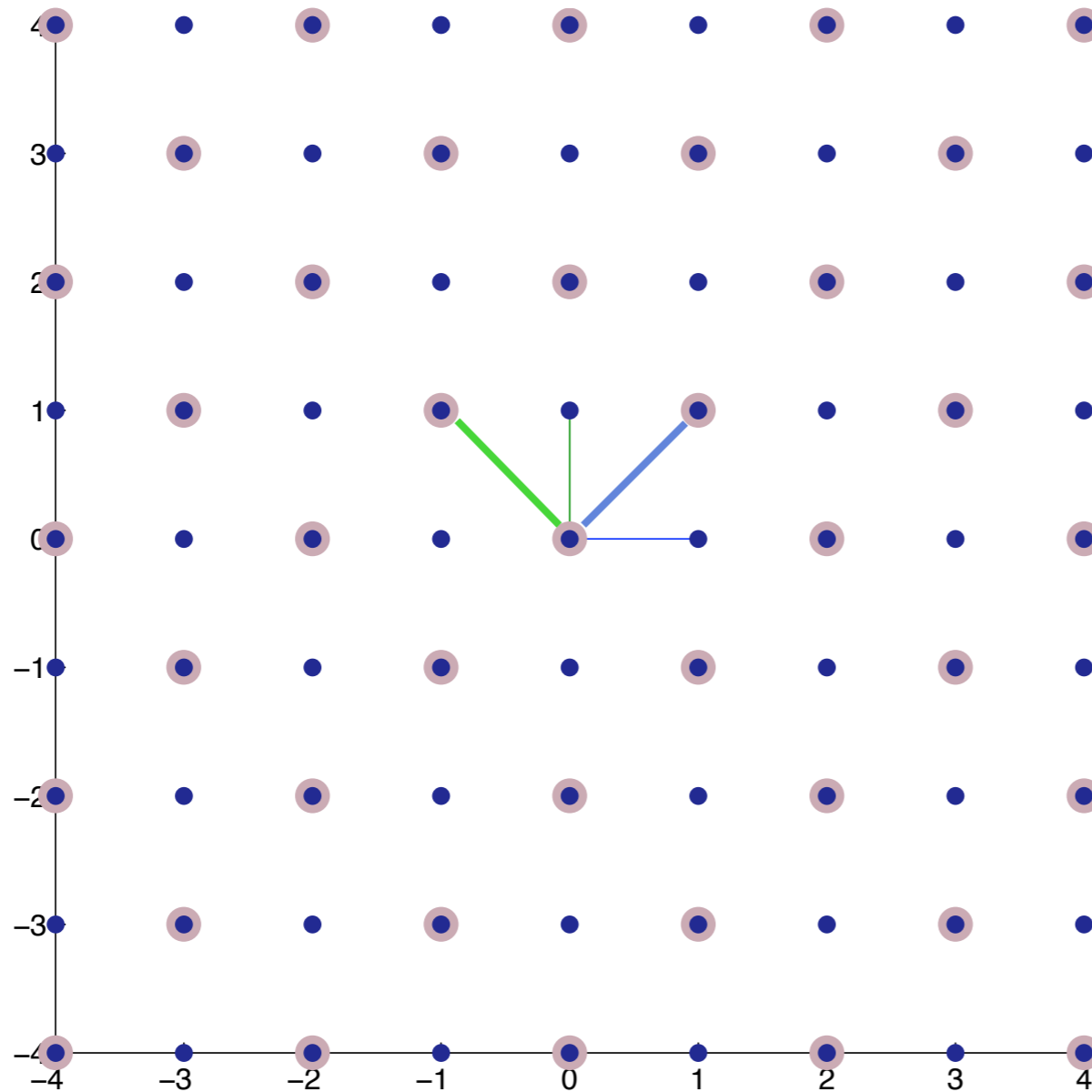


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quincunx subsampling

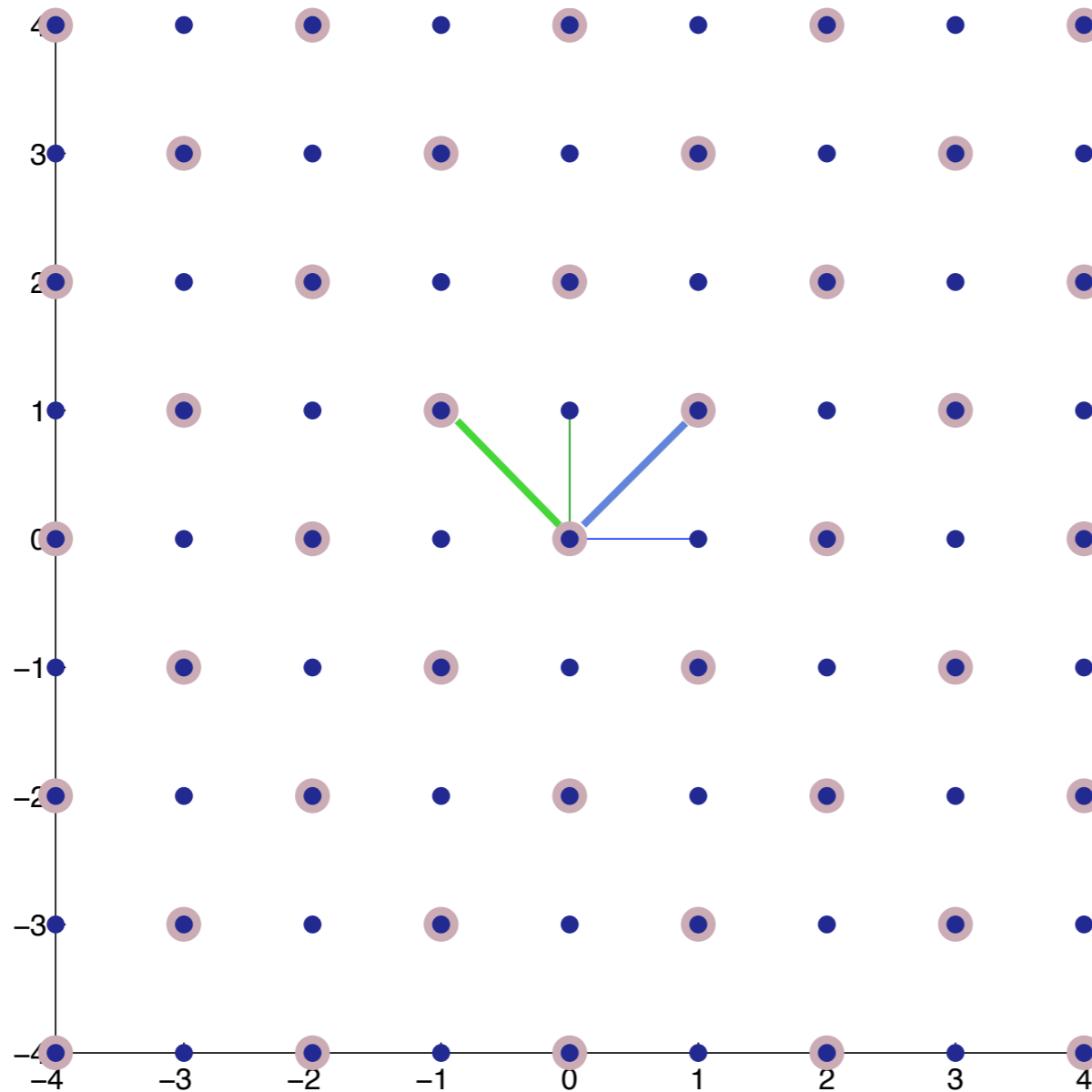
This low rate  
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[Van De Ville, Blu, Unser, SPL 05]



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quincunx subsampling

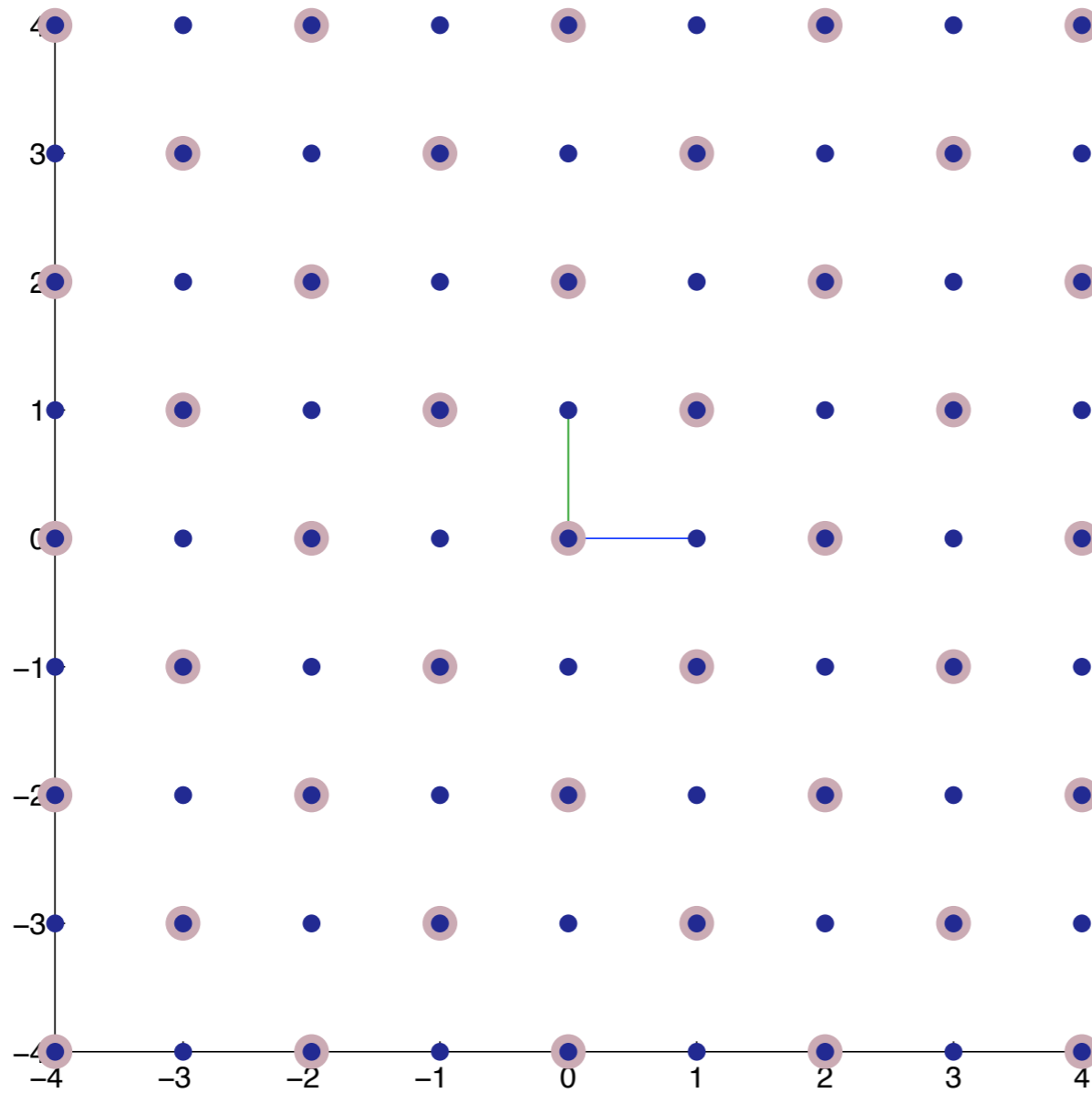
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[Van De Ville, Blu, Unser, SPL 05]

However,  
possible for  
irrational  $\mathbf{R}$  !



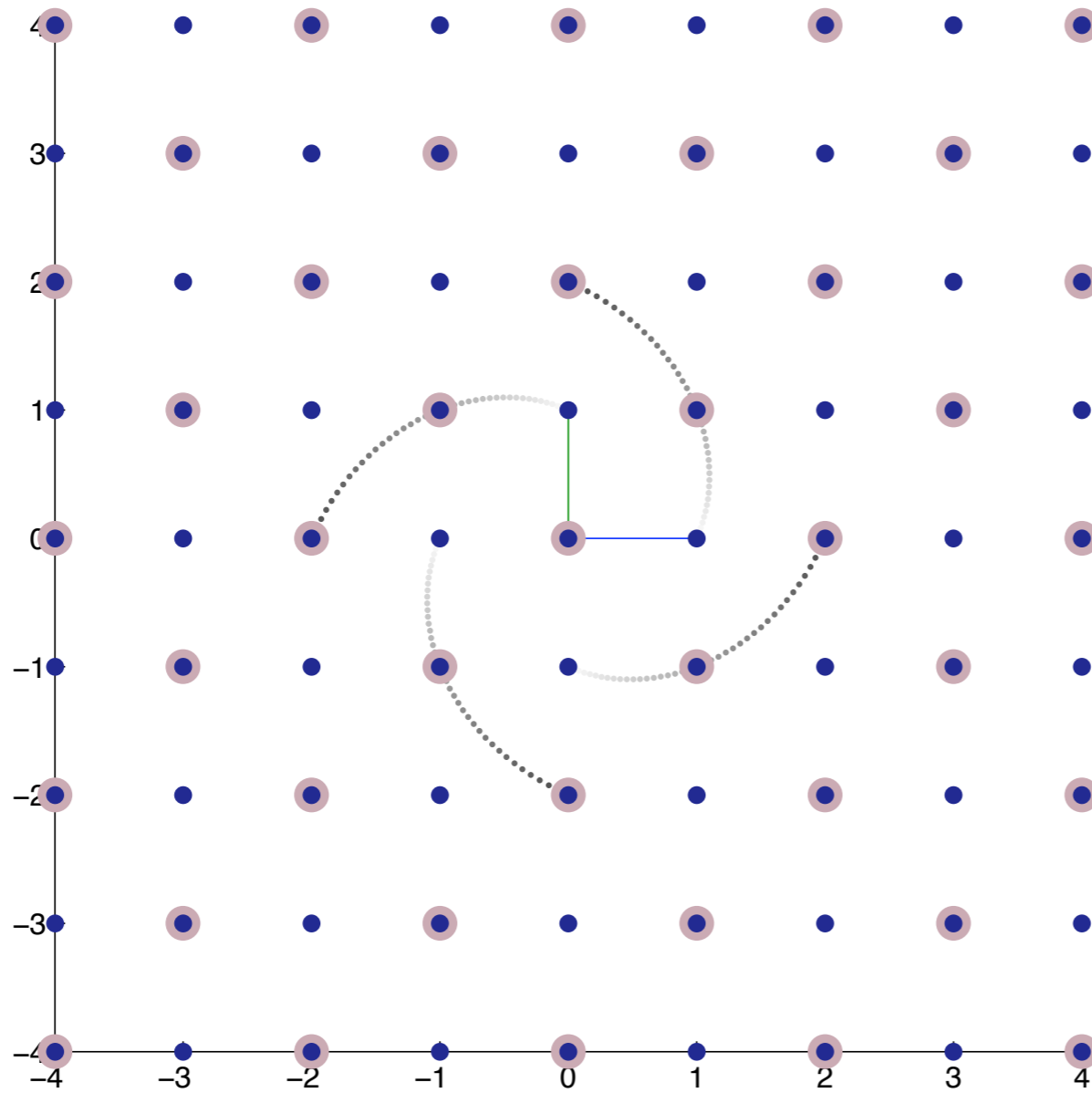
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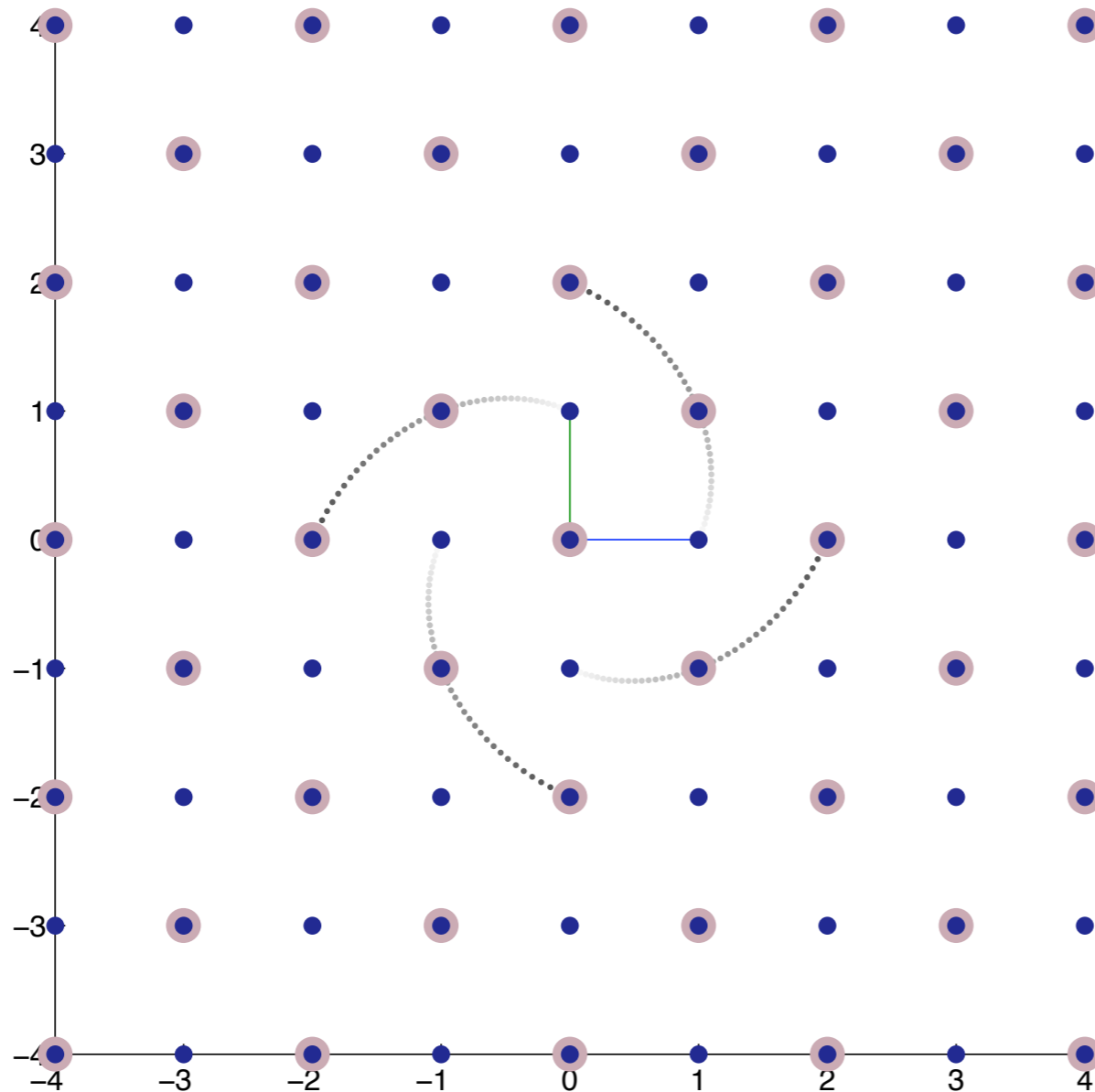
fractional subsampling

$\mathbf{RK}^s$  for  $s = 0.2$

quincunx subsampling



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fractional subsampling

$\mathbf{RK}^s$  for  $s = 0..2$

acts like a scaled  
rotation  $\mathbf{QR}$

with  $\mathbf{Q}^T \mathbf{Q} = \alpha^2 \mathbf{I}$

quincunx subsampling



**Construction**

# Similarity of $Q$ and $K$

$$QR = RK \text{ with } Q^T Q = \alpha^2 I$$





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$$R^{-1}QR = K$$



# Similarity of $\mathbf{Q}$ and $\mathbf{K}$

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- $\mathbf{K}$  and  $\mathbf{Q}$  have same characteristic polynomial  $d(\lambda) = \det(\mathbf{K} - \lambda \mathbf{I}) = \det(\mathbf{Q} - \lambda \mathbf{I})$



# Similarity of $\mathbf{Q}$ and $\mathbf{K}$

$$\mathbf{QR} = \mathbf{RK} \text{ with } \mathbf{Q}^T \mathbf{Q} = \alpha^2 \mathbf{I}$$

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 $= \sum_{k=0}^n c_k \lambda^k \in \mathbb{Z}[\lambda]$



# Similarity of $\mathbf{Q}$ and $\mathbf{K}$

$$\mathbf{QR} = \mathbf{RK} \text{ with } \mathbf{Q}^T \mathbf{Q} = \alpha^2 \mathbf{I}$$

$$\mathbf{R}^{-1} \mathbf{QR} = \mathbf{K}$$

- $\mathbf{K}$  and  $\mathbf{Q}$  have same characteristic polynomial  $d(\lambda) = \det(\mathbf{K} - \lambda \mathbf{I}) = \det(\mathbf{Q} - \lambda \mathbf{I})$   
$$= \sum_{k=0}^n c_k \lambda^k \in \mathbb{Z}[\lambda]$$
  
and thus agree in eigenvalues and determinant.



# Diagonalizing rotation $\mathbf{Q}$

$$\begin{aligned} \begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix} &= \frac{1}{2} \begin{bmatrix} 1 & 1 \\ j & -j \end{bmatrix} \begin{bmatrix} e^{j\theta} & 0 \\ 0 & e^{-j\theta} \end{bmatrix} \begin{bmatrix} 1 & j \\ 1 & -j \end{bmatrix} \\ &= \mathbf{J}_2^{-1} \Delta \mathbf{J}_2 \end{aligned}$$



# Diagonalizing rotation $Q$

$$\begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix} = \frac{1}{2} \begin{bmatrix} 1 & 1 \\ j & -j \end{bmatrix} \begin{bmatrix} e^{j\theta} & 0 \\ 0 & e^{-j\theta} \end{bmatrix} \begin{bmatrix} 1 & j \\ 1 & -j \end{bmatrix}$$

$$= \mathbf{J}_2^{-1} \Delta \mathbf{J}_2$$

Different eigenvalue structure for even and odd dimensionality

$$\Delta = \begin{bmatrix} e^{j\theta_1} & & & & \\ & e^{-j\theta_1} & & & \\ & & e^{j\theta_2} & & \\ & & & e^{-j\theta_2} & \\ & & & & \ddots \end{bmatrix} \quad \Delta = \begin{bmatrix} 1 & & & & \\ & e^{j\theta_1} & & & \\ & & e^{-j\theta_1} & & \\ & & & \ddots & \\ & & & & \ddots \end{bmatrix}$$

With analogue block-wise construction of  $\mathbf{J}_n$



# Diagonalizing rotation $\mathbf{Q}$

$$\begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix} = \frac{1}{2} \begin{bmatrix} 1 & 1 \\ j & -j \end{bmatrix} \begin{bmatrix} e^{j\theta} & 0 \\ 0 & e^{-j\theta} \end{bmatrix} \begin{bmatrix} 1 & j \\ 1 & -j \end{bmatrix} \\ = \mathbf{J}_2^{-1} \Delta \mathbf{J}_2$$

Different eigenvalue structure for even and odd dimensionality restricts characteristic polynomial:

- $n$  even:  $d(\lambda) = \lambda^n + C\lambda^{\frac{n}{2}} + \alpha^n$  with  $C^2 < 4\alpha^n$
- $n$  odd:  $d(\lambda) = \lambda^n - \alpha^n$



# Finding suitable $K$





# Finding suitable $K$

- Fulfill conditions implied by  $QR = RK$



# Finding suitable $K$

- Fulfill conditions implied by  $QR = RK$
- Exhaustive search over range of  $K \in \mathbb{Z}^{n \times n}$



# Finding suitable $K$

- Fulfill conditions implied by  $QR = RK$
- Exhaustive search over range of  $K \in \mathbb{Z}^{n \times n}$

- Companion matrix  $K = \begin{bmatrix} 0 & & & & -c_0 \\ 1 & 0 & & & -c_1 \\ & 1 & 0 & & \vdots \\ & & \ddots & \ddots & -c_{n-2} \\ & & & 1 & -c_{n-1} \end{bmatrix}$



# Finding suitable $\mathbf{K}$

- Fulfill conditions implied by  $\mathbf{QR} = \mathbf{RK}$
- Exhaustive search over range of  $\mathbf{K} \in \mathbb{Z}^{n \times n}$

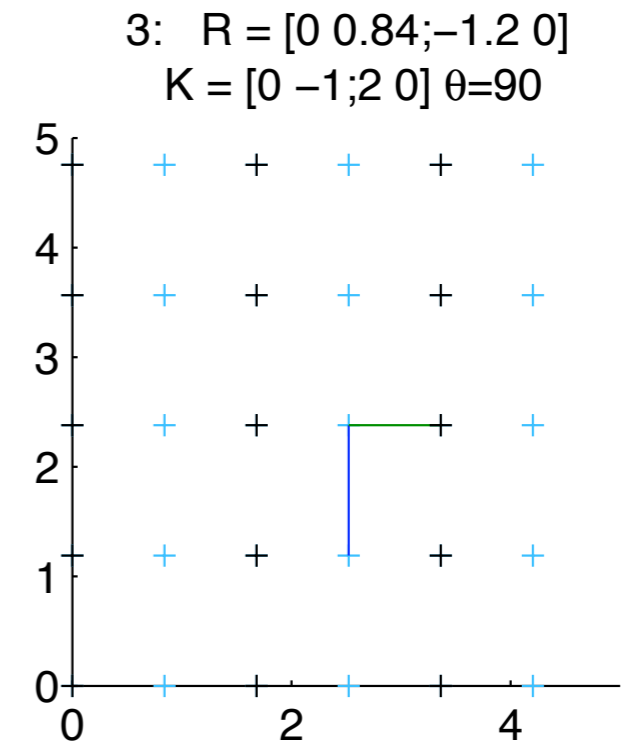
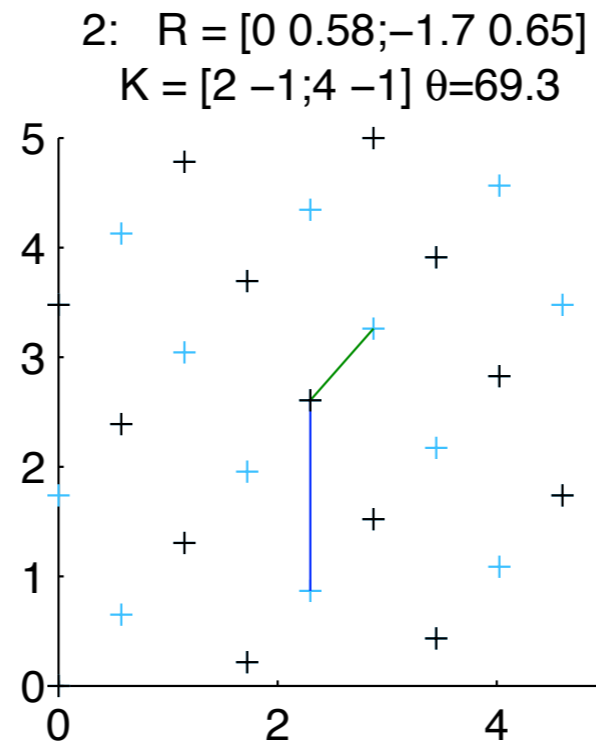
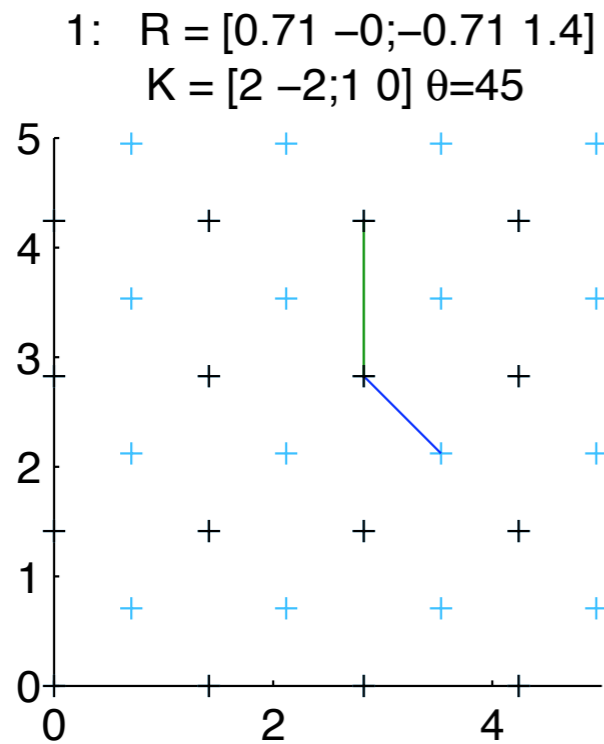
- Companion matrix  $\mathbf{K} = \begin{bmatrix} 0 & & & & -c_0 \\ 1 & 0 & & & -c_1 \\ & 1 & 0 & & \vdots \\ & & \ddots & \ddots & -c_{n-2} \\ & & & 1 & -c_{n-1} \end{bmatrix}$
- More with *unimodular* similarity transforms

$$\mathbf{K}_T = \mathbf{T}^{-1} \mathbf{K} \mathbf{T} \text{ with } \det \mathbf{T} = 1 \text{ and } \mathbf{T} \in \mathbb{Z}^{n \times n}$$



# Results

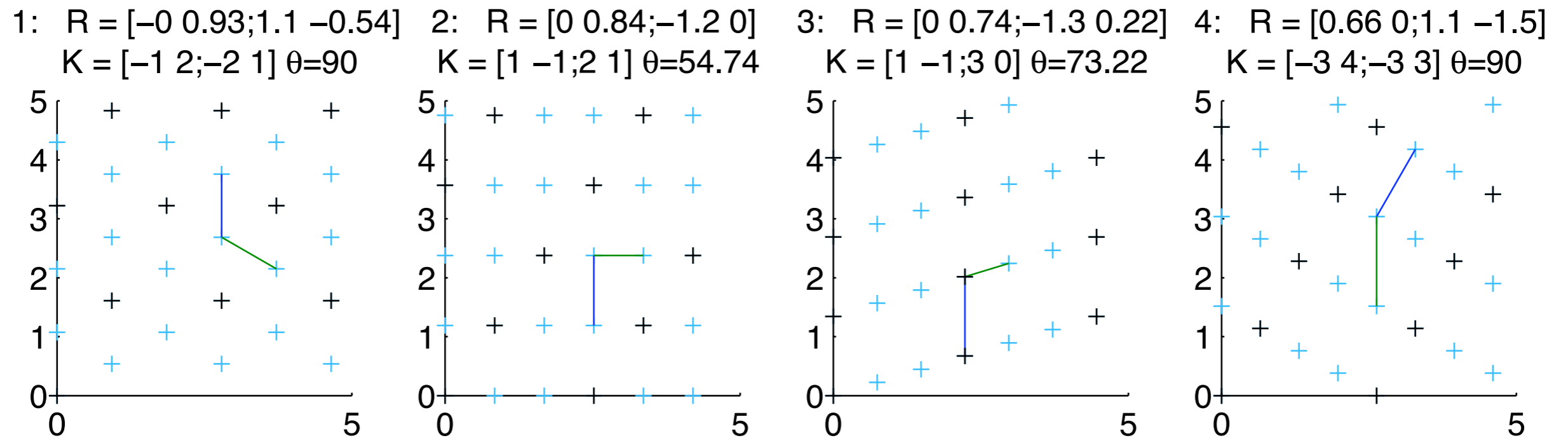
# 2D



**Dilation factor**  $|\det \mathbf{K}| = 2$



# 2D



**Dilation factor  $|\det \mathbf{K}| = 3$**



# Rotational grid summary

- First time low-rate admissible dilation matrices are available for  $n > 2$
- Additional degrees of freedom in the design enable further optimization
- Current results allow optimized constructions up to  $n=9$





# Model adjustment at different levels

- User-driven experimentation: Use cases for *paraglide*
- Criteria optimization: Lighting design
- Theoretical analysis: Sampling in volume rendering
- Filling a region: Lattices with rotational dilation
- Summary and conclusion



# Model adjustment at different levels

- User-driven experimentation: Use cases for *paraglide*
- Criteria optimization: Lighting design
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# Data taxonomy

- *primary*: field measurements
- *secondary*: synthetic data or human input
- *tertiary*: rules provided by theoretical study or statistical inference



# Model adjustment at different levels

- User-driven experimentation: Use cases for *paraglide*
- Criteria optimization: Lighting design
- Theoretical analysis: Sampling in volume rendering
- Filling a region: Lattices with rotational dilation



# Model adjustment at different levels

User input

- User-driven experimentation: Use cases for *paraglide*
- Criteria optimization: Lighting design
- Theoretical analysis: Sampling in volume rendering
- Filling a region: Lattices with rotational dilation

Theoretical input



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# Thank you! Questions?

